

SIMPLE, AFFORDABLE AUTOMATION

Automata

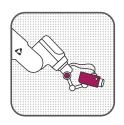
AVAILABLE EXCLUSIVELY IN AUSTRALIA FROM



australiseng.com.au

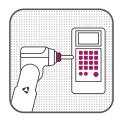


EVA THE AFFORDABLE ROBOT FOR



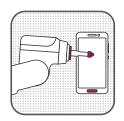
Inspection

Integrate Eva with a camera for quality control and inspection tasks



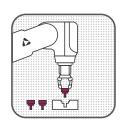
Machine Tending

Program Eva to load or unload parts from your existing machines



Product testing

Safely and accurately perform test sequences in a repeatable, consistent way



Sorting

Move items into different locations based on detection of sensory inputs



- Increase throughput and efficiency
- Reduce production costs
- Free staff from manual tasks
- Remove bottlenecks in production

CONNECTIVITY



There are multiple ways to programme Eva:

Teach by hand and fine tune with **Choreograph**, the browser-based software

Use the **REST API** and **Python SDK** to build integrations and expand the robot's capabilities further"

SIMPLICITY



Eva's light weight and small footprint enable rapid changeovers to minimise downtime between runs, with no special technical expertise or equipment required.

Eva ideal for smaller and mid-sized manufacturing businesses with high mix, low volume runs.

No control boxes, no pendants.

GETTING STARTED

Eva also includes:

- Access to Automata's support team to assist with set-up and troubleshooting
- ➤ A lifetime Choreograph software license, including future updates and feature releases
- One year full warranty protection, including parts and labour





In the box you will find:

- Eva, your portable six axis robot arm
- A mains power supply
- An emergency stop button
- ► A user manual
- ► A brake release lever



PREPARING FOR INSTALLATION

For simple pick and place tasks, Eva has been designed to be installed and programmed in under 30 minutes by someone with no prior robotics experience.

For more complex projects or those requiring integration with existing machines, our in-house integrations team or one of our specialist integration partners will be able to help.

Get in touch at sales@automata.tech

Map out the process(es) you will be automating

Prioritise highly repetitive, bottleneck tasks that take up valuable human time

Scope out technical requirements for peripherals

Understand what kind of end of arm tooling or gripper is required for your parts

Understand integration requirements

Including parts presentation, sensors, vision, feeding systems, a PLC or other integrations

Prepare your workspace

Install Eva on a sturdy surface, secured with M6 screws or clamps

INTEGRATION

SPECIFICATIONS

Eva Desktop Robot Arm **Degrees of Freedom:** 6 **Repeatability:** ± 0.5 mm

Max Payload: 1.25 kg

Reach: 600 mm

Installation Position: Upright

Weight: 9.5 kg

Joint velocity limits: 120° / second

TCP speed: 1500 mm/s Power: 24 VDC @ 11.67A

Power Consumption: 280 W Peak

Footprint: 160 x 160 mm

Electronic Interfaces

4X: Analog Inputs

2X: Analog Outputs

6X: Digital Inputs

6X: Digital Outputs

1X: E-Stop inputs

1X: Ethernet

1X: Wifi Card

Tool Power: 24 VDC @ 1 A

Base I/O Power: 24 VDC @ 1.5 A

Operating **Environment**

Ingress Rating: IP20

Temperature: 5 - 30 °C

Cabling: Max 3 m for power, e-stop, tools

Programming

Type: Remote REST API

Interface: GUI through web browser

Communication: Ethernet or wifi

Deployment: Local (installed on robot)

Export/Import: Base64 / Javascript

Joint Position Limits

A1: ±180°

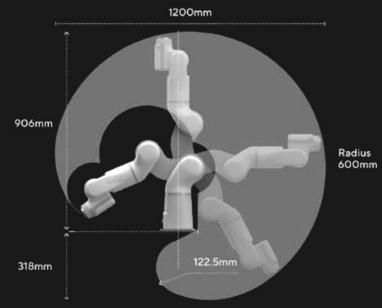
A2: -152° / +70°

A3: -160°/ + 42°

A4: ± 180°

A5: -159° / + 11°

A6: ± 180°



For more information visit our website: automata.tech

