

## Product Specifications

<b>Arm Length</b>	<b>Full length</b>	1,200 mm
	<b>First arm</b>	750 mm
	<b>Second arm</b>	450 mm
<b>Working Envelope</b>	<b>Axis 1</b>	±125 °
	<b>Axis 2</b>	±155 °
	<b>Axis 3 (Z-axis)</b>	0 ~ 300 mm
	<b>Axis 4 (Z-axial rotation)</b>	±360°
<b>Maximum Speed *1</b>	<b>Axis 1</b>	187.5 °/sec
	<b>Axis 2</b>	217.5 °/sec
	<b>Axis 3 (Z-axis)</b>	2,000 mm/sec
	<b>Axis 4 (Z-axial rotation)</b>	1,700 °/ssec
	<b>Composite (Axis 1 and 2 composite)</b>	5.7 m/sec
<b>Load</b>	<b>Maximum payload mass *1</b>	10 kg
	<b>Allowable moment of inertia *1</b>	0.2 kg·m <sup>2</sup>
<b>Standard Cycle Time *2</b>	<b>(With 2 Kg load)</b>	0.58 sec
<b>Positioning repeatability *3</b>	<b>X-Y</b>	±0.05 mm
	<b>Z (axis 3)</b>	±0.03 mm
	<b>C (axis 4, rotation)</b>	±0.014 deg
<b>Hand wiring</b>		8 inputs and 8 outputs
<b>Hand pneumatic joint *4</b>		φ6×3 pcs
<b>Position detection</b>		Absolute
<b>Robot controller cable</b>		3.5 m
<b>Power supply</b>		1.4 kVA
<b>Mass</b>		40 kg
<b>Controllers</b>		TSL3000 TSL3000E

\*1: Speed and acceleration/deceleration rates may be limited depending on the motion pattern, load mass and amount of offset.

\*2: Horizontal 300 mm, vertical 25 mm, round-trip with coarse positioning. Continuous operation is not possible beyond the effective load ratio.

\*3: Positioning repeatable accuracy in one-direction movement, when the environmental temperature is constant 20°C., not absolute positioning accuracy. Positioning repeatability for X-Y and C are for when Z-axis is at the upper-most position. Trajectory accuracy is not ensured.

\*4: Pneumatic joints are provided on the base. Pipes are to be provided by the customers..

## Controller Specifications

TSL3000 Controller	
<b>Series</b>	THL, THE, BAIII
<b>Teach Pendant</b>	TP1000, TP3000
<b>Power Supply</b>	Single phase 190-240VAC @ 50/60Hz
<b>Max Power Capacity</b>	0.7 ~ 1.4 kVA
<b>Dimensions</b>	150W x 266H x 304D
<b>Mass</b>	7kg
<b>Storage</b>	256 programs 6400 points 12800 steps
<b>CE Version</b>	TSL3000E Dimensions change: 320W x 266H x 304D 13kg
<b>USER I/O Count</b>	8/8
<b>SYSTEM I/O Count</b>	13/9
<b>SYSTEM INPUTS</b>	Alarm reset, strobe, program reset, step reset, cycle reset, output reset, start, external servo on, stop, cycle mode, break, low speed, servo off
<b>SYSTEM OUTPUTS</b>	Servo ready, battery alarm, acknowledge, external mode on, system ready, autorun, alarm, cycle end, low speed on
<b>Fieldbus SLAVE options</b>	DeviceNet, Profibus, CC-Link, Ethernet I/P, EtherCat, ProfiNet
<b>Extended I/O Options</b>	TR48-DIOC Module Add 28In/20Out Up to 2 modules can be added to controller
<b>Communications</b>	RS232C (2), Ethernet (TCP/IP), USB
<b>Standard SCOL Functions</b>	Torque control (individual axis), gain control (individual axis), interrupt functions, SPURT function, coordinate calculations, payload command, multi-tasking, AREA output function, NCBOY additional axis control, self-diagnostics
<b>Optional SCOL Functions</b>	Pulse output control, conveyor tracking, vision+conveyor tracking
<b>External Control Standard Functions</b>	HOST Protocol, .dll library, LabView integration support