

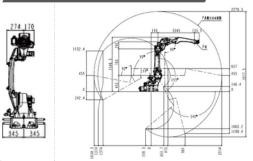


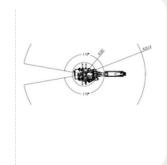
QJR6-2000H

**INDUSTRIAL** ROBOT



- Enhanced reducer with large reduction ratio design, better control the accuracy;
- 4th axis hollow structure used double angular contact bearings to replace the traditional structure. Improve joint supported rigidity;
- 4, 6 axis with special gear clearance adjustment structure, higher joint precision;
- The wrist is changed into a U-shaped structure to improve the
- With the above characteristics, the motion stability of the lengthened welding robot is greatly optimized;
- The wrist is shortened to improve flexibility;
- Special wrist noise reduction structure, lower running noise;
- New appearance with new spray painting process, excellent sensory effect.









机构形态 Mechanism	垂直多关节 Vertical multi-joint robot			
轴数 Axis Number				
有效载荷 Payload	6kg	6kg		
重复定位精度 Repeat Positioning				
最大臂展 Max Armspan				
防护等级 Protection Degree	IP30			
本体重量 Robot Body Weight	230kg			
机械限位范围 Motion Range	J1	±175°		
	J2	+159*, -95*		
	J3	+95°, -125°		
	J4	±183°		
	J5	+129*, -126*		
	J6	±360°		
最大連度 Max Speed	J1	189°/s		
	J2	189°/s		
	J3	189*/s		
	J4	360°/s		
	J5	320°/s		
	J6	974*/s		

允许扭矩	J4	8.81 N·m
	J5	8.81 N·m
	J6	3.14 N·m
惯性力矩	J4	0.2 kg·m²
	J5	0.2 kg·m²
	J6	0.03 kg·m²
安装环境 Installation Environment	温度 TEMP	0~45 ℃
	温度 HUM	20%~80% RH (不结露) No condensation
	振动 NVH	< 4.9m/s² (0.5G)
	其他 Others	避免易燃、腐蚀性气体和液体; Avoid flammable, corrosive gases and liquids;
		避免接触水、油、粉尘等;
		勿接近电器噪音源。
电源容量		Do not approach electrical noise source.
Power Capacity		
电控柜尺寸 Cabinet Size		
电控柜重量 Cabinet Weight	130kg	
电源	三相四线AC380V + 10%	
Source	Three-phase four-wire	
安装方式 Installation	地面、吊頂 Walls Ceiling	