

## Product Specifications

Model	THL800	THL900	THL1000
Type	Horizontal multi-joint		
No. of controlled axes	4		
Arm Length	800mm (350mm + 450mm)	900mm (450mm + 450mm)	1000mm (550mm + 450mm)
Range of Motion	First axis	±125°	
	Second axis	±145°	
	Third axis (Z-axis)	0 ~ 300mm	
	Fourth axis (Z-axial rotation)	±360°	
Maximum Speed*1	First axis	187.5°/s	
	Second axis	217.5°/s	
	Third axis (Z-axis)	2000mm/s	
	Fourth axis (Z-axial rotation)	1700°/s	
	Composite speed	4.3m/s	4.6m/s
Standard Cycle Time (with 2kg load) *2	0.47s	0.48s	0.48s
Maximum payload	10kg (Ratings : 2kg)		
Allowable end moment	0.2kg·m <sup>2</sup>		
Position	X, Y (plane surface)	±0.02mm	
	Z-axis (vertical)	±0.015mm	
Repeatability*3	Fourth axis (Z-axial rotation)	±0.007°	
Input Signal for Hand	8 inputs, 8 outputs		
Hand pneumatic joints*4	φ6×3		
Position Detection Method	Absolute encoder mode		
Robot controller cable	3.5m		
Power capacity	1.4kVA		
Total Weight	33kg	35kg	37kg

\*1: Acceleration/deceleration rates may be limited according to the motion pattern, load mass and amount of offset.

\*3: Horizontal 300mm, vertical 25mm, round-trip. Continuous operation is not possible beyond the effective load ratio.

\*2: When the environment temperature is constant 20°C. Positioning repeatable accuracy in one-direction movement. Not absolute positioning accuracy.

\*4: Pneumatic joints are provided on the base. Please refer to the drawings for the details of the pneumatic joints. Pipes to be provided by the customers.

## Controller Specifications

TSL3000 Controller	
<b>Series</b>	THL, THE, BAIII
<b>Teach Pendant</b>	TP1000, TP3000
<b>Power Supply</b>	Single phase 190-240VAC @ 50/60Hz
<b>Max Power Capacity</b>	0.7 ~ 1.4 kVA
<b>Dimensions</b>	150W x 266H x 304D
<b>Mass</b>	7kg
<b>Storage</b>	256 programs 6400 points 12800 steps
<b>CE Version</b>	TSL3000E Dimensions change: 320W x 266H x 304D 13kg
<b>USER I/O Count</b>	8/8
<b>SYSTEM I/O Count</b>	13/9
<b>SYSTEM INPUTS</b>	Alarm reset, strobe, program reset, step reset, cycle reset, output reset, start, external servo on, stop, cycle mode, break, low speed, servo off
<b>SYSTEM OUTPUTS</b>	Servo ready, battery alarm, acknowledge, external mode on, system ready, autorun, alarm, cycle end, low speed on
<b>Fieldbus SLAVE options</b>	DeviceNet, Profibus, CC-Link, Ethernet I/P, EtherCat, ProfiNet
<b>Extended I/O Options</b>	TR48-DIOC Module Add 28In/20Out Up to 2 modules can be added to controller
<b>Communications</b>	RS232C (2), Ethernet (TCP/IP), USB
<b>Standard SCOL Functions</b>	Torque control (individual axis), gain control (individual axis), interrupt functions, SPURT function, coordinate calculations, payload command, multi-tasking, AREA output function, NCBOY additional axis control, self-diagnostics
<b>Optional SCOL Functions</b>	Pulse output control, conveyor tracking, vision+conveyor tracking
<b>External Control Standard Functions</b>	HOST Protocol, .dll library, LabView integration support