## **Product Specifications**

Arm Length	Full length	400 mm
	First arm	225 mm
	Second arm	175 mm
Working Envelope	Axis 1	±130 °
	Axis 2	±145°
	Axis 3 (Z-axis)	0 ~ 160 mm
	Axis 4 (Z-axial rotation)	±360°
Maximum Speed *1	Axis 1	672 °/sec
	Axis 2	780 °/sec
	Axis 3 (Z-axis)	1,120 mm/sec
	Axis 4 (Z-axial rotation)	1,800 °/ssec
	Composite (Axis 1 and 2 composite)	7.0 m/sec
Standard Cycle Time *2	(With 2 Kg load)	0.39 sec
Load	Maximum payload mass *1	5 kg
	Allowable moment of inertia *1	0.06 kg·m2 *2
Position Repeatability *3	X-Y	±0.01 mm
	Axis 3 (Z-axis)	±0.01 mm
	Axis 4 (Z-axial rotation)	±0.007 °
Hand wiring *4		8 inputs and 8 outputs
Hand Pneumatic Joint *4		Provided by user
Position Detection		Absolute
Robot Controller Cable		3.5 m
Power Supply		2.6 kVA
Mass		15 kg
Controllers		→ TSL3000 → TSL3000E

<sup>\*1:</sup> Acceleration/deceleration rates may be limited according to the motion pattern, load mass and amount of offset.

<sup>\*2:</sup> Horizontal 300 mm, vertical 25 mm, round-trip with coarse positioning. Continuous operation is not possible beyond the effective load ratio.

<sup>\*3:</sup> Positioning repeatable accuracy in one-direction movement, when the environmental temperature is constant 20°C. Not absolute positioning accuracy. Positioning repeatability for X-Y and C are for when Z-axis is at the upper-most position. Trajectory accuracy is not ensured.

<sup>\*4:</sup> Optional design duct for hand wiring and tubing is planned.

## **Controller Specifications**

Controllor opcomodations		
	TSL3000 Controller	
Series	THL, THE, BAIII	
Teach Pendant	TP1000, TP3000	
Power Supply	Single phase	
	190-240VAC @ 50/60Hz	
Max Power Capacity	0.7 ~ 1.4 kVA	
Dimensions	150W x 266H x 304D	
Mass	7kg	
Storage	256 programs	
	6400 points	
	12800 steps	
<b>CE Version</b>	TSL3000E	
	Dimensions change:	
	320W x 266H x 304D 13kg	
USER I/O Count	8/8	
SYSTEM I/O Count	13/9	
SYSTEM INPUTS	Alarm reset, strobe, program reset, step reset, cycle reset, output reset, start, external	
	servo on, stop, cycle mode, break, low speed, servo off	
SYSTEM OUTPUTS	Servo ready, battery alarm, acknowledge, external mode on, system ready, autorun,	
	alarm, cycle end, low speed on	
Fieldbus SLAVE options	DeviceNet, Profibus, CC-Link, Ethernet I/P, EtherCat, ProfiNet	
Extended I/O Options	TR48-DIOC Module	
	Add 28In/20Out	
	Up to 2 modules can be added to controller	
Communications	RS232C (2), Ethernet (TCP/IP), USB	
	Torque control (individual axis), gain control (individual axis), interrupt functions, SPURT	
Standard SCOL Functions	function, coordinate calculations, payload command, multi-tasking, AREA output	
	function, NCBOY additional axis control, self-diagnostics	
Optional SCOL Functions	Pulse output control, conveyor tracking, vision+conveyor tracking	
External Control Standard	HOST Protocol, .dll library, LabView integration support	
Functions		