PARALLEL • ANGULAR

GRIPPER

mindman

About **MINDMAN.**

Global vision and local operation.

600 PEOPLE
EMPLOYEES

97 COUNTRIES
SALES NETWORK

Core Business:
Manufacture and sale for varieties of high quality automation components.

1979
FOUNDED

No.1
Quantity supplied of pneumatic components in Taiwan.

HEADQUARTERS IN
TAIPEI
CITY, TAIWAN

CHING-CHENG HUANG
PRESIDENT

CAPITAL
USD 12,558,000

MANUFACTURE BASE IN
TAINAN
CITY, TAIWAN

90,000 m²
Plant Size

Mindman Industrial Co., Ltd. was established in 1979 with a destination to provide high quality automation components for a wide variety of industries.

During the past 40 years, Mindman has devoted to the expansion of our product range. Thanks to our R&D department, we are proud to possess the diversified product lineup includes solenoid valves, air treatment units, pneumatic cylinders, electric actuators and all different types of fluid power accessories.

We always believe that fast delivery of automation components is the key of success in the market. Through the complete vertical integration of all manufacturing processes and automated warehouse, we are confident to achieve on time delivery.

To keep quality high during the whole production process, we implement the strict quality control standard. We thoroughly control the process via standard operation procedure (SOP), statistical process control system (SPC) and total productive management (TPM). Most important of all, Mindman commits to providing the products with 100% inspection after assembly.

Currently, Mindman products are exported to more than 90 countries around the world. We devoted ourselves to building the relationship with customers worldwide and provide them with the strong support, such as online 3D drawing, inventory check and promotional program…etc. In the vast automation market, Mindman will spare no effort in establishing a brand – a worldclass premium automation components supplier.

OUR STANDARD
ISO 9001 *Quality*
ISO 14001 *Environment*
OHSAS 18001 *Health and Safety*
YOUR GUARANTEE

Quality Assurance Certification

Passed ISO9001, ISO14001 and OHSAS18001 international certification.

RoHS COMPLIANT

CE

MIT
Made in Taiwan

Connect with

ROBOT

Connect gripper and robotic arm to achieve various workpiece gripping applications.

PARALLEL GRIPPER

2-FINGER

All gripping force is based on the conditions below.

- Operation Pressure 0.5 MPa.
- Gripping Length 20 mm.
- Outer diameter gripping.

MCH* series
Model selection

P. 6

- Gripper selection.
- Selection suggestions.
- Selection example.

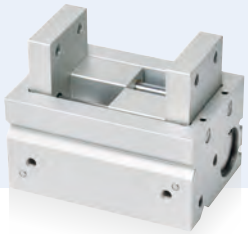
MCHC series
2-finger

P. 7

- Using linear ball bearing.
- Excellent repeatability.
- 7 kinds of mounting jaw available.
- Gripping force 4N~55N.

mindman

2-FINGER



MCHU series
2-finger

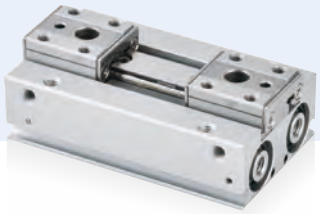
P. 23

- Using mechanism to achieve parallel gripping.
- Designed for long soft-jaws installation.
- Gripping force 20N~60N.

MCHB series
2-finger

P. 27

- Using mechanism to achieve parallel gripping.
- Economic type.
- Gripping force 5N~85N.

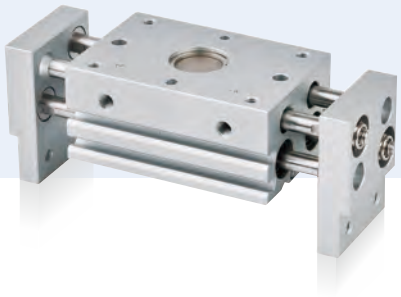


MCHD series
2-finger

P. 31

- Using linear ball bearing.
- Excellent repeatability.
- Flat profile.
- Gripping force 15N~125N.

2-FINGER



MCHX series
2-finger

P. 41

- Using rack and pinions to achieve parallel gripping.
- Long gripping stroke.
- High rigidity.
- Gripping force 16N~250N.

MCHH series
2-finger

P. 48

- Using rack and pinions to achieve parallel gripping.
- High rigidity.
- Gripping force 100N~500N.

MCHS series
2-finger

P. 53

- Using transmission cam to achieve parallel gripping.
- High rigidity.
- Gripping force 150N~1500N.

PARALLEL GRIPPER

3-FINGER

MCHG2 series
3-finger

P. 62

- Using transmission cam to achieve centering gripping.
- High rigidity.
- Gripping force 12N~1300N.

MCHJ series
3-finger

P. 69

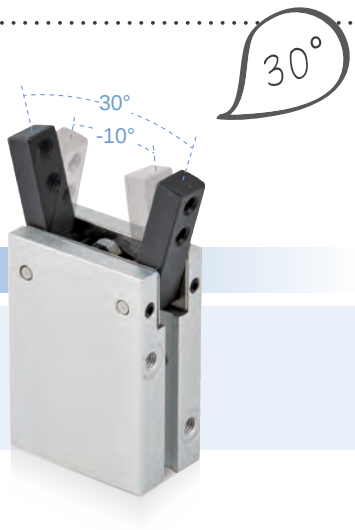
- Using transmission cam to achieve centering gripping.
- High rigidity.
- Gripping force 400N~6000N.

All gripping force is based on the conditions below.

- Operation Pressure 0.5 MPa.
- Gripping Length 20 mm.
- Outer diameter gripping.

ANGULAR GRIPPER

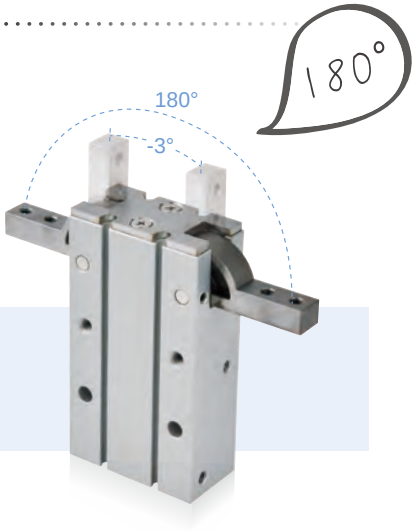
2-FINGER



MCHA series
2-finger

P. 75

- Simple structure with high stability.
- Economic type.
- Gripping force 10N~150N.



MCHY series
2-finger

P. 80

- Using cams to achieve angular gripping.
- Gripping force 8N~70N.

SENSOR SWITCH

RDE series

P. 85

- Non-contact
- NPN, PNP

RDFE series

P. 86

- Non-contact
- NPN, PNP

RDGV series

P. 87

- Non-contact
- NPN, PNP

Gripper selection

- Depends on the coefficient of friction and the gripping conditions between soft fingers and work piece.

When gripping a workpiece as in the figure as shown above:

F: Gripping force of single finger (N)
n: Number of finger
μ: Coefficient of friction between the attachments and the workpiece
m: Workpiece mass (kg)
g : Gravitational acceleration (=9.8m/s^2)
a : Safe factor

the conditions under which the workpiece will not drop are,

$$n \times \mu F > m \times g$$

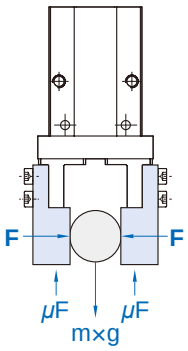
Therefore,

$$F \geq \frac{m \times g}{n \times \mu}$$

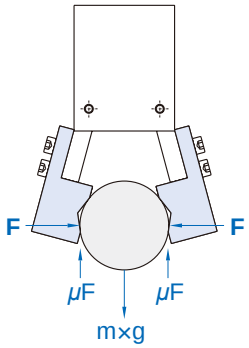
With "a" representing the extra margin, "F" is determined by the following formula:

$$F \geq \frac{m \times g}{n \times \mu} \times a$$

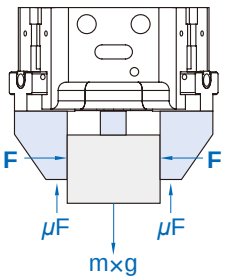
Parallel gripper (2-Finger)



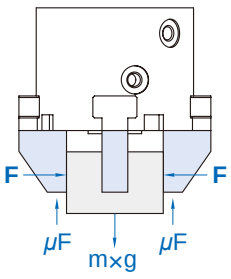
Angular gripper



Parallel gripper (3-Finger)



Parallel gripper (4-Finger)

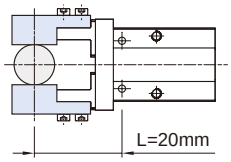


Model selection suggestions

1. For normal gripping and carrying usage, the recommended safe factor (a) is 4.
2. The value of gripping force of single finger can be found at the gripping force table.
3. The safe factor (a) have to be higher if the gripper is using with a great accelerated velocity or impaction condition.

Model selection example

In the motion process did not produce high acceleration, deceleration or impact forces, Workpiece mass: 0.3kg , Gripping method: External gripping, Operating pressure: 0.5 MPa, Coefficient of friction (*μ*): 0.1, Holding position: L=20mm (no overhang)

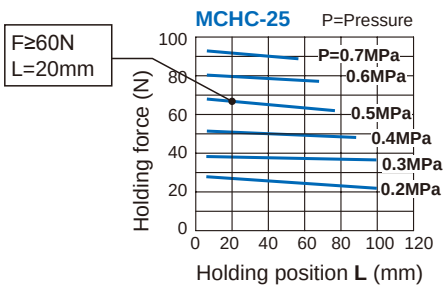


1. Based on the above formula, the required gripping force can be derived:

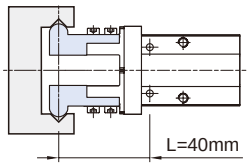
$$F \geq \frac{0.3 \times 9.8}{2 \times 0.1} \times 4$$

$$\geq 60(N)$$

2. From Effective Gripping Force Fig, Operating pressure: 0.5 MPa; Holding position: 20 mm Effective gripping force is greater than 60 (N) So selected **MCHC-25** grippers.



In the motion process did not produce high acceleration, deceleration or impact forces, Workpiece mass: 0.05kg , Gripping method : External gripping, Operating pressure: 0.3 MPa, Coefficient of friction (*μ*): 0.1, Holding position: L=40mm (no overhang)

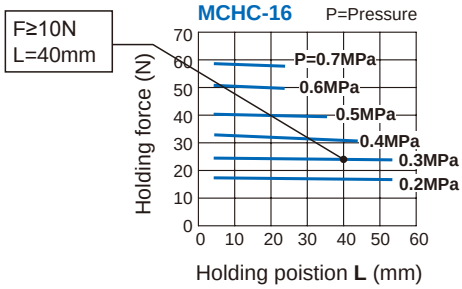


1. Based on the above formula, the required gripping force can be derived:

$$F \geq \frac{0.05 \times 9.8}{2 \times 0.1} \times 4$$

$$\geq 10(N)$$

2. From Effective Gripping Force Fig, Operating pressure: 0.3 MPa; Holding position: 40 mm Effective gripping force is greater than 10 (N) So selected **MCHC-16** grippers.



Connect with

AIR CYLINDER

Connect gripper with cylinder to
achieve regular workpiece gripping.

MCHC series [feature]

PARALLEL GRIPPER (2-Finger)

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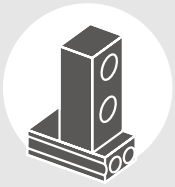


7 kinds of mounting jaw available

Linear ball bearing guide for high rigidity and precision

Whole gripping set made with martensitic stainless steel

VARIOUS FINGER TYPES

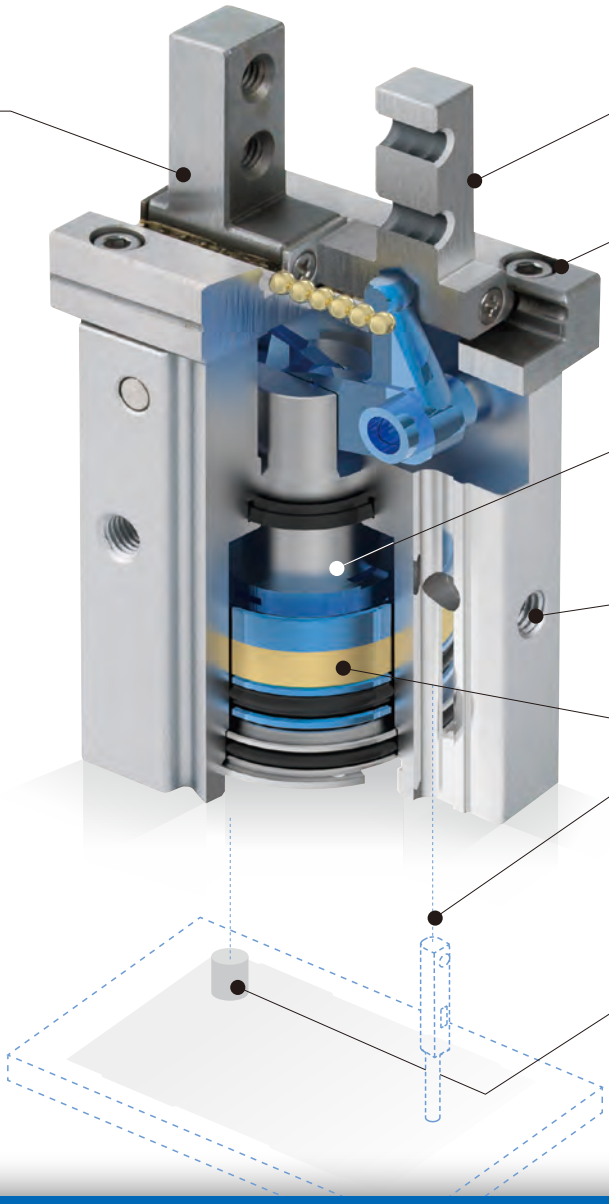
- Standard

- Narrow

- Side tapped mounting

- Through hole

- Flat



REPEATABILITY

±0.01 mm

STROKE

Standard and long stroke.

The long stroke type is approximately double compare with standard type.

ACTING

Single / Double acting
N.C. / N.O. (optional)

MOUNTING POSITION

Bottom / Side / Front

SENSOR SWITCH

RDE, RNE, RPE series

Standard with magnet
Embedded sensor design

POSITIONING HOLES

With positioning holes for fast positioning when changing grippers.

MCHC series

PARALLEL GRIPPER (2-Finger)

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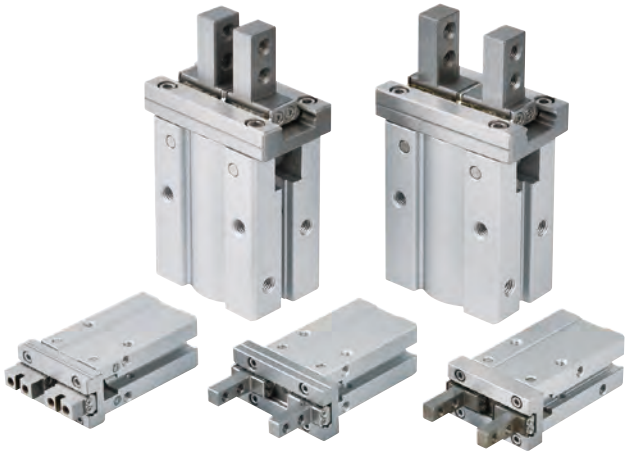


Features

- Integral linear guide used for high rigidity and high precision.
- The material of finger is martensitic stainless steel.
- Body thickness tolerance ±0.05mm.
- Bottom pin holes for accurate re-locating.
- Grooves on the body for sensor switch to be inserted into.
- The gripping stroke of long-stroke type is approximately double compare with standard type.
- Standard with magnet.

Specification

Model		MCHC				
Acting type		Double acting / Single acting				
Tube I.D. (mm)		6	10	16	20	25
Opening / Closing stroke (mm)		4	4(8)	6(12)	10(18)	14(22)
Port size		M3×0.5		M5×0.8		
Medium		Air				
Operating pressure range	Double acting	0.15~0.7	0.2~0.7	0.1~0.7 MPa		
	Single acting	–	0.35~0.7	0.25~0.7 MPa		
Ambient temperature		-10~+60°C (No freezing)				
Repeatability		± 0.01 mm				
Max. frequency		180 (120) cycle / min				
Lubricator		Not required				
Sensor switch (*2)		*1	RDE, RDE-D: Non-contact			
Weight (g)	Double acting	27	55(56)	124(125)	250(252)	461(463)
		–	[53]	[124]	[244]	[450]
	Single acting	–	70	145	270	490

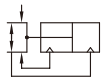
*1. Tube I.D. ø6 use R*FE(V) sensor switch.
2. RDE, R*FE(V) specification, please refer to page 85, 86.
*3. ( ) value for long stroke, [ ] value for flat type.

Order example

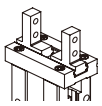
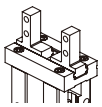
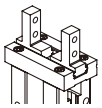
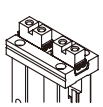
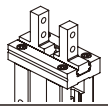
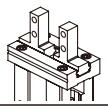
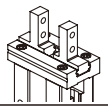
MCHC □ – 20 – □ N

Model	Tube ID.	Style (*1)	Type (*2)
MCHC (Standard stroke)	**6**	Blank: Double acting	Blank:Standard **1**: Side tapped mounting **2**: Standard (Through hole)
	10 **16** **20** **25**	Blank: Double acting **S**: Single acting / Normally open **C**: Single acting / Normally closed	Blank:Standard **1**: Side tapped mounting **2**: Standard (Through hole) **3**: Flat **N**: Narrow **N1**: Narrow type side tapped mounting **N2**: Narrow (Through hole)
MCHCL (Long stroke)	**10** **16** **20** **25**	Blank: Double acting	Blank:Standard **1**: Side tapped mounting **2**: Standard (Through hole)

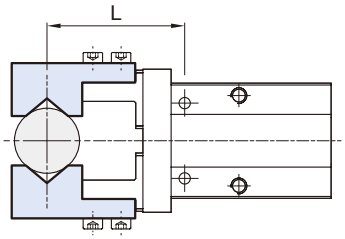
*1. STYLE

Blank: Double acting	**S**: Single acting / Normally open	**C**: Single acting / Normally closed
		

*2. TYPE

Blank: Standard	**1**: Side tapped mounting	**2**: Standard (Through hole)	**3**: Flat
			
N: Narrow	**N1**: Narrow type side tapped mounting	**N2**: Narrow (Through hole)	
			

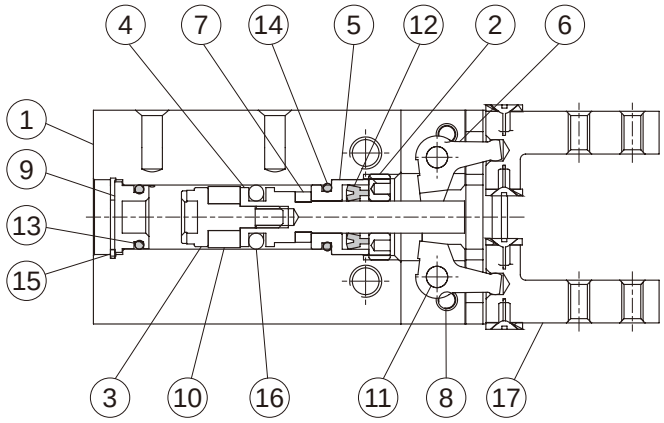
Gripping force



Tube I.D. (mm)		6	10	16	20	25
Double acting	External	3.3(0.3)	11(1.1)	34(3.5)	42(4.3)	65(6.6)
	Internal	6.1(0.6)	17(1.7)	45(4.6)	66(6.7)	104(10.6)
Single acting / Normally open	External	–	7.1(0.7)	27(2.8)	33(3.4)	45(4.6)
Single acting / Normally closed	Internal	–	13(1.3)	38(3.9)	57(5.8)	83(8.5)

* Operation pressure 0.5 MPa, gripping length 20mm, the effective gripping force for each finger is *** N(kgf).

Double acting



Material

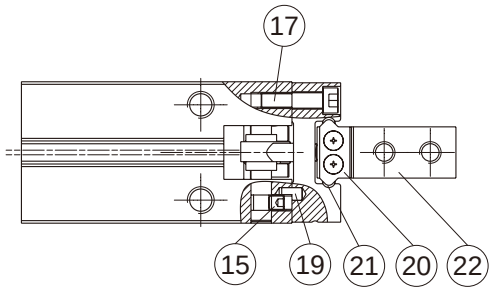
No.	Part name	Material	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy	1	
2	Front cap	Stainless steel	1	
3	Magnet holder	Stainless steel	1	
4	Piston rod	Stainless steel	1	
5	Rod cover	Stainless steel	1	
6	Lever	Stainless steel	2	
7	Cushion pad	PU	1	●
8	Screw	Stainless steel	4	
9	Head cover	Aluminum alloy	1	
10	Magnet ring	Magnet material	1	
11	Pin	Steel	2	
12	Rod packing	NBR	1	●
13	O-ring	NBR	1	
14	O-ring	NBR	1	
15	Snap ring	Carbon steel	1	●
16	Piston packing	NBR	1	●
17	Gripping set	Stainless steel (*)	1	

* Bearing steel balls as standard.

Order example of repair kits

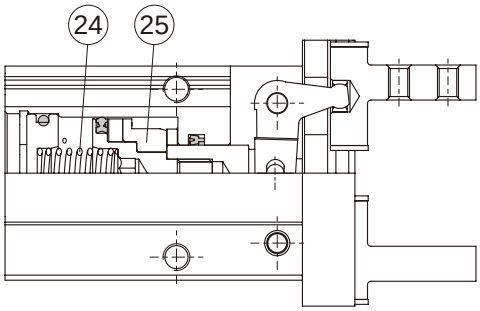
Tube I.D.	Repair kits
ø6	**PS-MCHC-6**

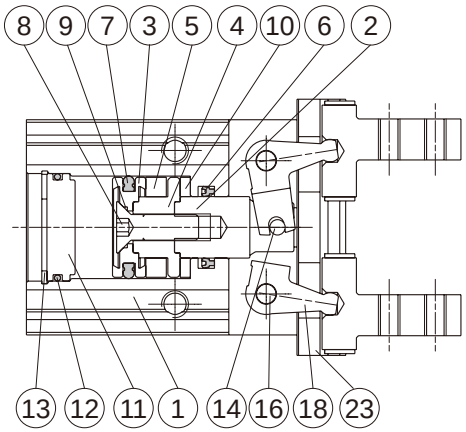
Double acting



Single acting

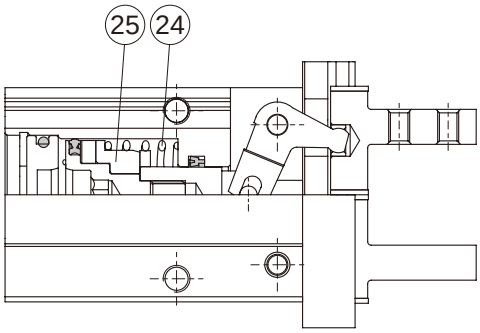
Normally open





Single acting

Normally closed



Material

No.	Tube I.D. / Part name	10	16	20	25	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy				1	
2	Piston rod	Stainless steel				1	
3	Piston	Aluminum alloy				1	
4	Piston R	*1	Aluminum alloy			1	
5	Magnet ring	Magnet material				1	
6	Rod packing	NBR				1	●
7	Piston packing	NBR				1	●
8	Screw	—	Stainless steel			1	
9	O-ring	—	NBR			1	●
10	Cushion pad	PU				1	●
11	Head cover	Aluminum alloy				1	
12	Cover ring	NBR				1	●
13	Stop ring	*2	Stainless steel			1	
14	Spindle river	Carbon steel				1	
15	Screw	Carbon steel				4	
16	Grip rivet	Carbon steel				2	
17	Bolt	Stainless steel				4	
18	Lever	Stainless steel				2	

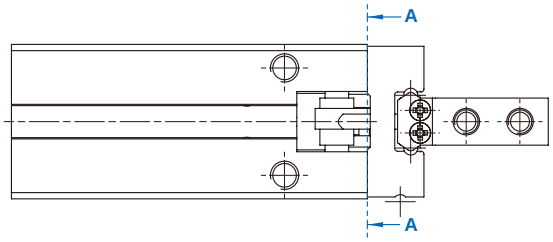
No.	Tube I.D. / Part name	10	16	20	25	Q'y	Repair kits (inclusion)
19	Pin	Carbon steel				2	
20	Roller stopper	Stainless steel				4	
21	Steel balls	Bearing steel				24	
22	Finger	Stainless steel				2	
23	Guide	Stainless steel				1	
24	Magnet holder	Stainless steel				1	
25	Stop ring	Stainless steel				1	

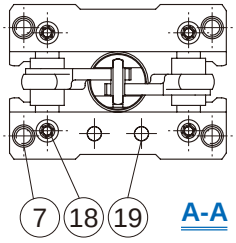
*1. Stainless steel *2. Carbon steel

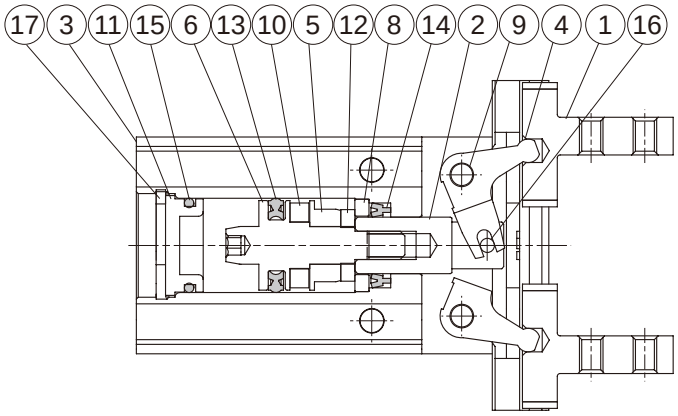
Order example of repair kits

Tube I.D.	Repair kits
ø10	**PS-MCHC-10**
ø16	**PS-MCHC-16**
ø20	**PS-MCHC-20**
ø25	**PS-MCHC-25**

Double acting







Material

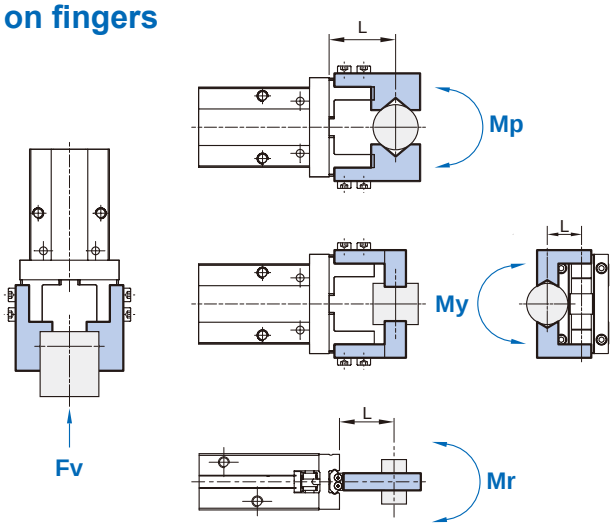
No.	Tube I.D. / Part name	10	16	20	25	Q'y	Repair kits (inclusion)
1	Gripping set	Stainless steel (*1)				1	
2	Piston rod	Stainless steel				1	
3	Body	Aluminum alloy				1	
4	Lever	Stainless steel				2	
5	Spring holder	Stainless steel				1	
6	Piston	Stainless steel				1	
7	Bolt	Stainless steel				4	
8	Stop ring	*2	–			1	
9	Grip rivet	Mild carbon steel				2	
10	Magnet ring	Magnet material				1	
11	Head cover	Aluminum alloy				1	
12	Gasket	NBR				1	●
13	Piston packing	NBR				1	●
14	Rod packing	NBR				1	●
15	O-ring	NBR				1	●
16	Spindle river	Carbon steel				1	
17	Snap ring	*3	Stainless steel			1	
18	Hexgon screw	Stainless steel				4	
19	Pin	Carbon steel				2	

*1. Bearing steel balls as standard.
*2. Stainless steel 3.Carbon steel

Order example of repair kits

Tube I.D.	Repair kits
ø10	**PS-MCHCL-10**
ø16	**PS-MCHCL-16**
ø20	**PS-MCHCL-20**
ø25	**PS-MCHCL-25**

Confirmation of external force on fingers

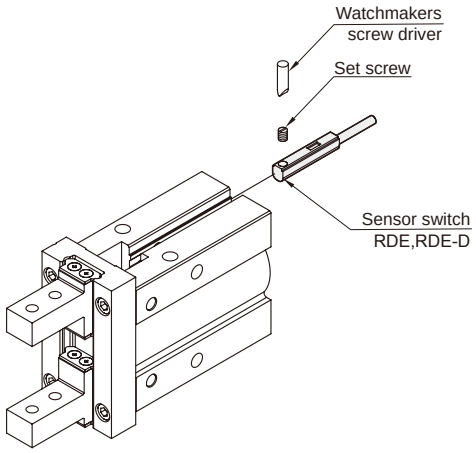


L: distance to the point at which the load is applied (mm)

Tube I.D. (mm)	Allowable vertical load Fv (N)	Maximum allowable moment		
		Pitch moment Mp (N-m)	Yaw moment My (N-m)	Roll moment Mr (N-m)
6	10	0.04	0.04	0.08
10	58	0.26	0.26	0.53
16	98	0.68	0.68	1.36
20	147	1.32	1.32	2.65
25	255	1.94	1.94	3.88

* Values for load and moment in the table indicate static values.

Installation of sensor switch



Allowable load calculation

$$\text{Allowable load } F(N) = \frac{M(\text{maximum allowable moment})(N\cdot m)}{L(m)}$$

Example

When a static load of f=20N is operating,which applies pitch moment to point L=25mm from the **MCHC-16** guide.

$$\text{Allowable load } F(N) = \frac{0.68\ (N\cdot m)}{25\times10^{-3}(m)}$$

$$= 27.2\ (N)$$

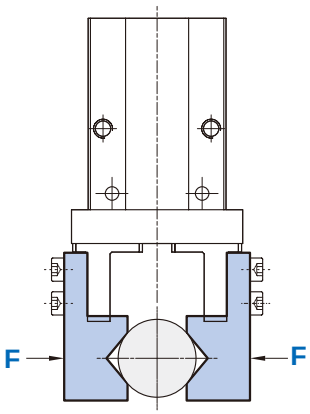
Load f=20 (N) < 27.2 (N), so can be used.

Model selection suggestions

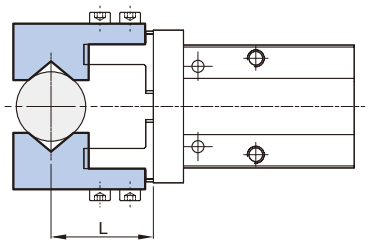
1. For normal gripping and carrying usage, the recommended safe factor (a) is 4.
2. The value of gripping force of single finger can be found at the gripping force table.
3. The safe factor (a) have to be higher if the gripper is using with a great accelerated velocity or impaction condition.

Effective gripping force (Double acting)

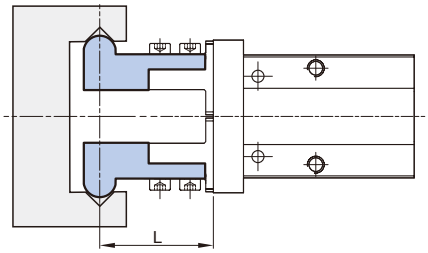
Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



1N=0.102 kgf
1MPa=10.2 kgf/cm^2



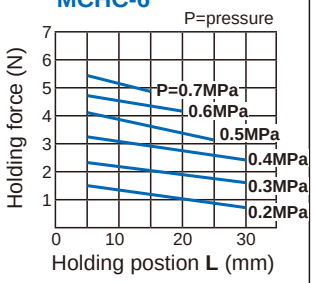
External grip



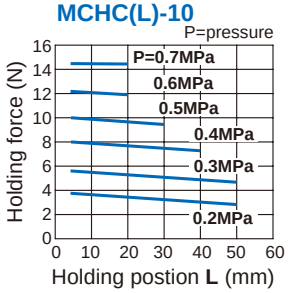
Internal grip

External gripping force

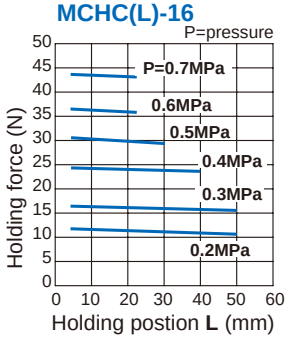
MCHC-6



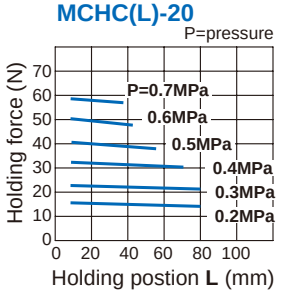
MCHC(L)-10



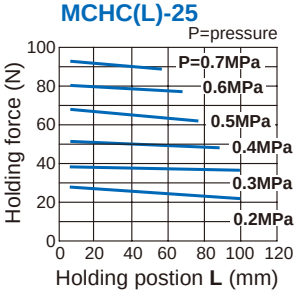
MCHC(L)-16



MCHC(L)-20

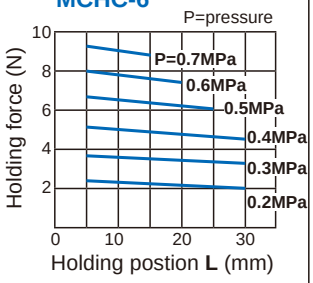


MCHC(L)-25

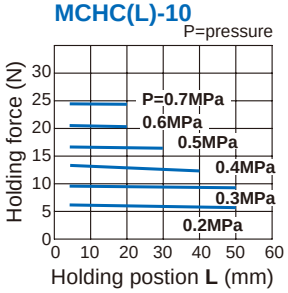


Internal gripping force

MCHC-6



MCHC(L)-10



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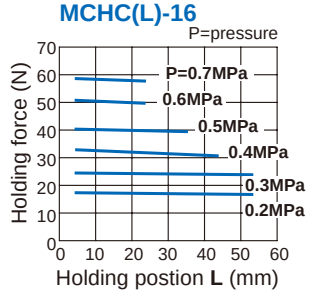

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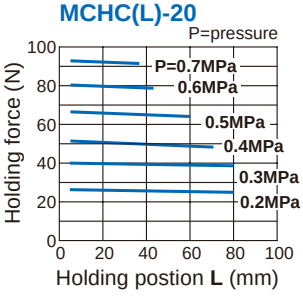
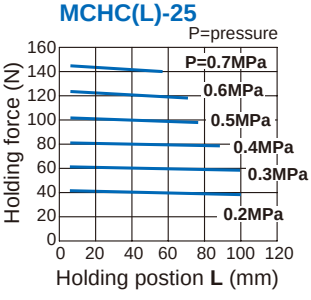


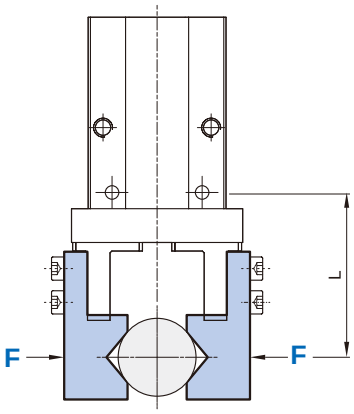
MCHC(L)-25



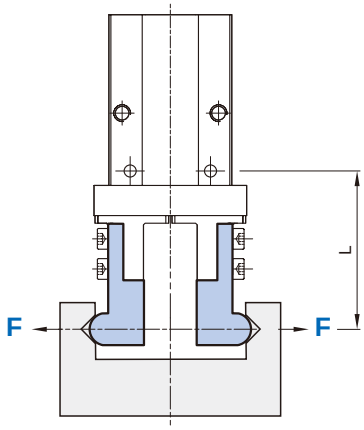
Effective gripping force (Single acting)

Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

1N=0.102 kgf
1MPa=10.2 kgf/cm^2



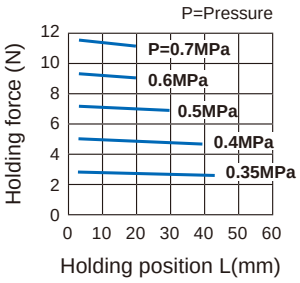
External grip
(Single acting / Normally open)



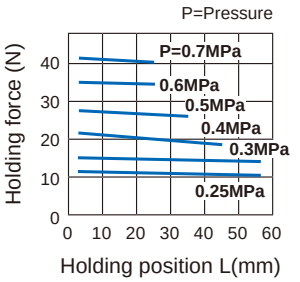
Internal grip
(Single acting / Normally closed)

External gripping force
Single acting / N.O.

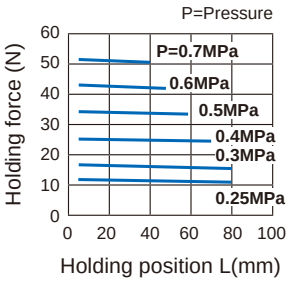
MCHC-10-S



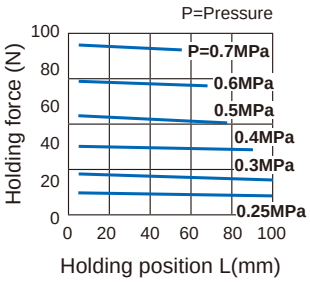
MCHC-16-S



MCHC-20-S

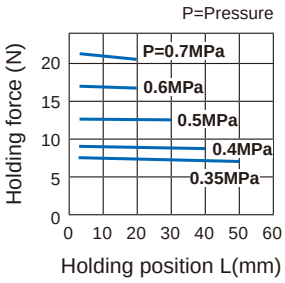


MCHC-25-S

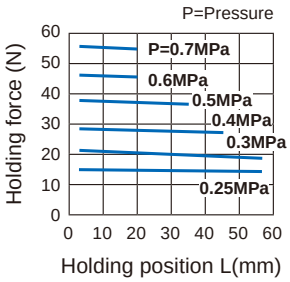


Internal gripping force
Single acting / N.C.

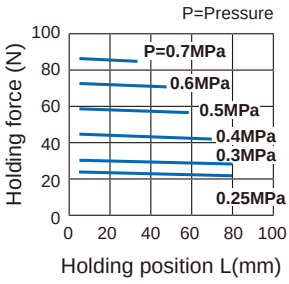
MCHC-10-C



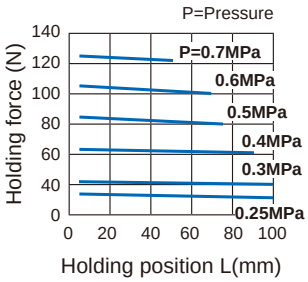
MCHC-16-C



MCHC-20-C

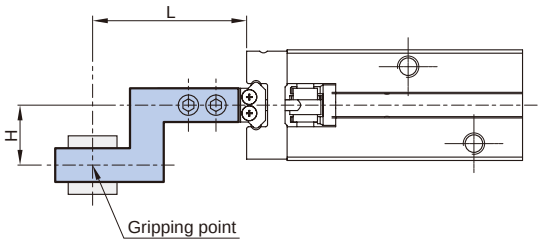


MCHC-25-C

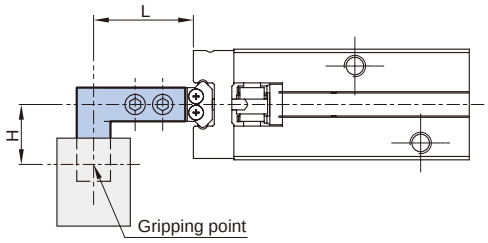


Confirmation of gripping point

- The air gripper should be operated so that the workpiece gripping point "L" and the amount of overhang "H" stay within the range shown for each operating pressure given in the graphs to the right.
- If the workpiece gripping point goes beyond the range limits, this will have an adverse effect on the life the air gripper.



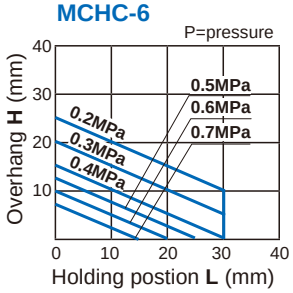
External grip



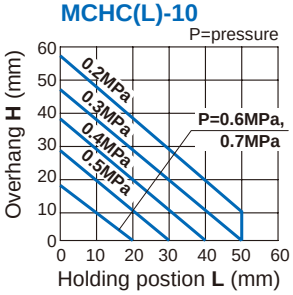
Internal grip

External gripping force

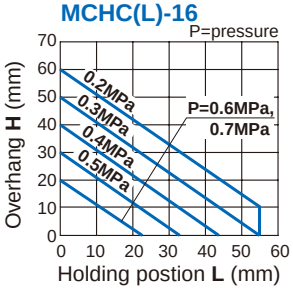
MCHC-6



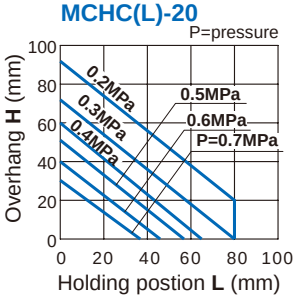
MCHC(L)-10



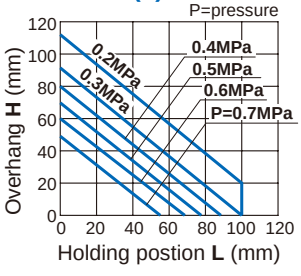
MCHC(L)-16



MCHC(L)-20

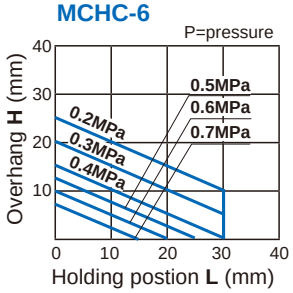


MCHC(L)-25

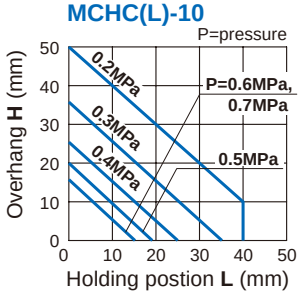


Internal gripping force

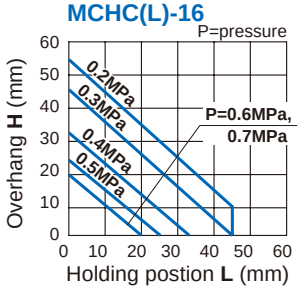
MCHC-6



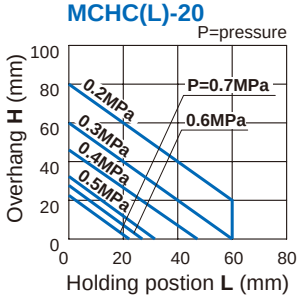
MCHC(L)-10



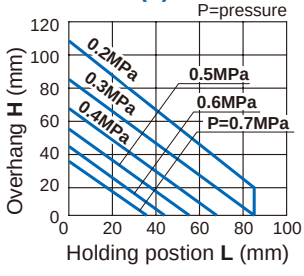
MCHC(L)-16

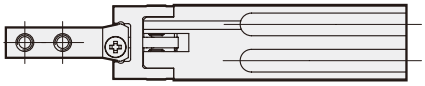


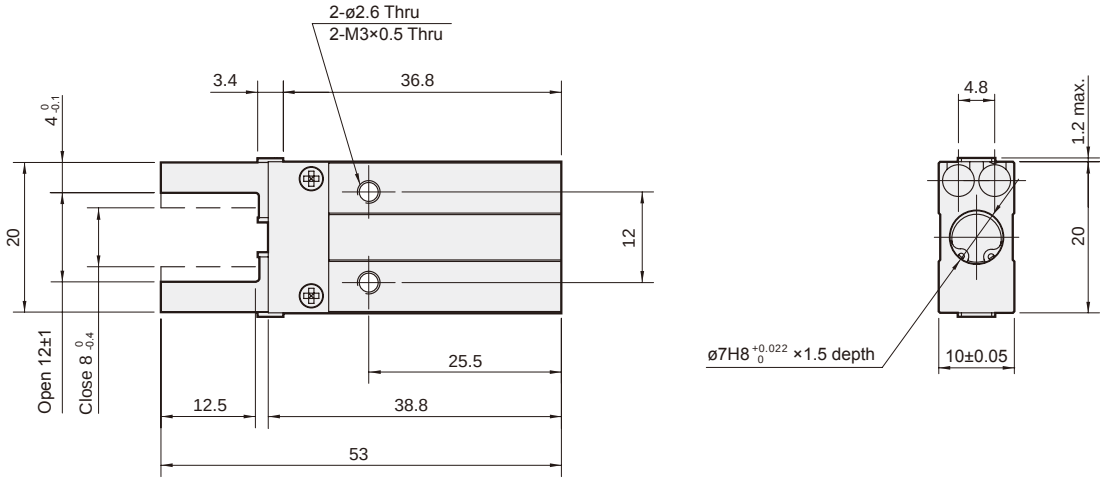
MCHC(L)-20

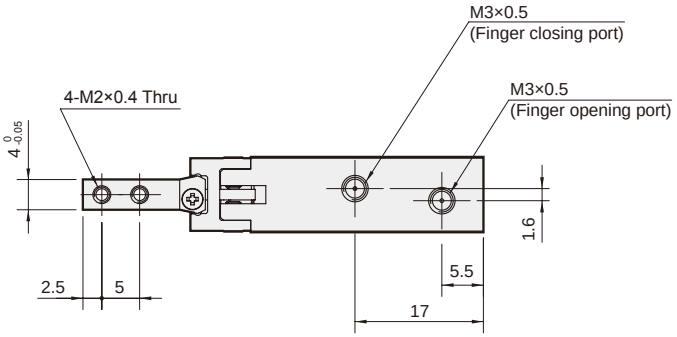


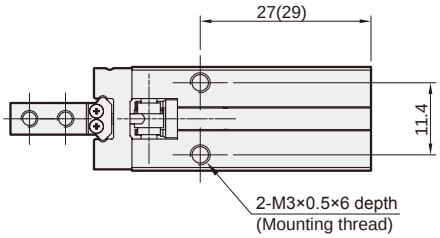
MCHC(L)-25

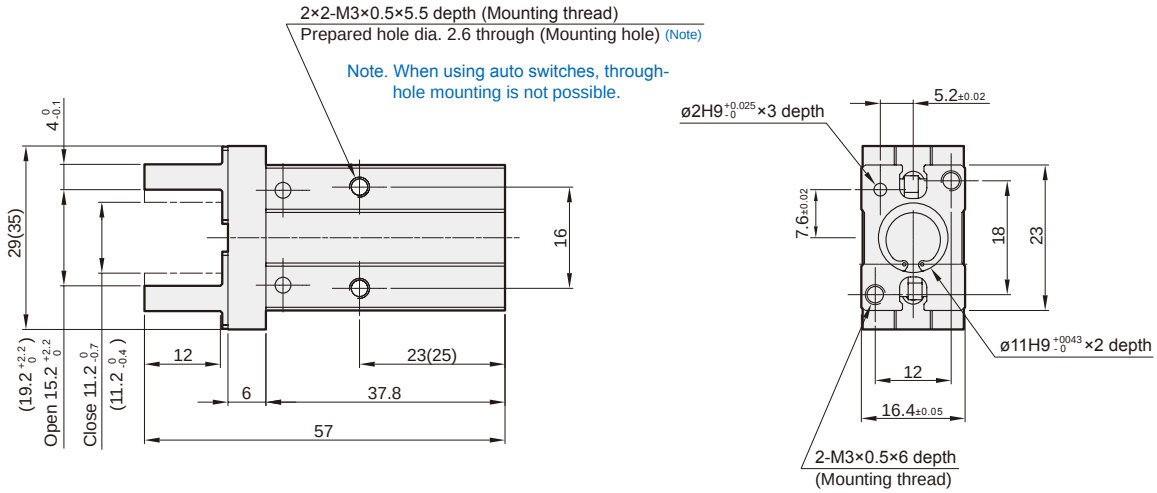


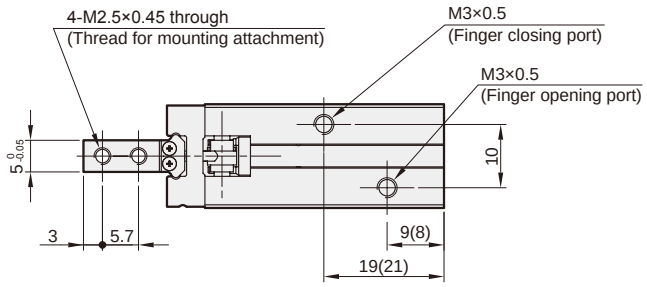



2-ø2.6 Thru
2-M3×0.5 Thru
3.4
36.8
4 0 -0.1
20
12
Open 12±1
Close 8 0 -0.4
25.5
12.5
38.8
53
4.8
1.2 max.
20
ø7H8 +0.022 0 ×1.5 depth
10±0.05


M3×0.5
(Finger closing port)
M3×0.5
(Finger opening port)
4-M2×0.4 Thru
4 0 -0.05
1.6
5.5
2.5
5
17



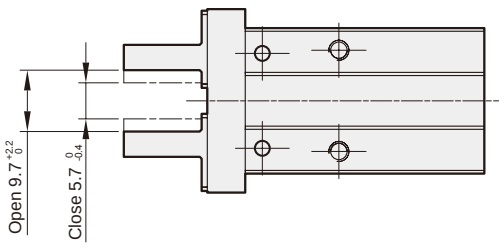


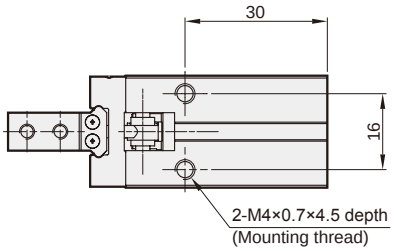


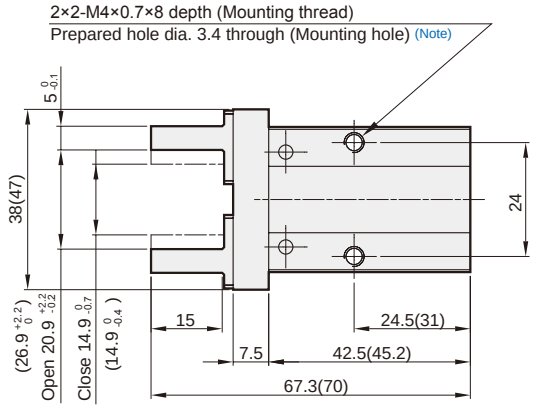
*( ) for long stroke value.

Finger position – Narrow type

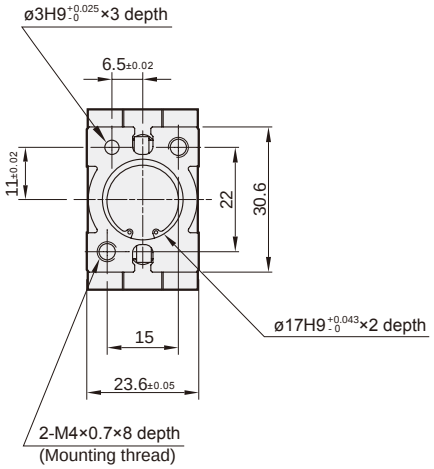
MCHC(L)-10-N

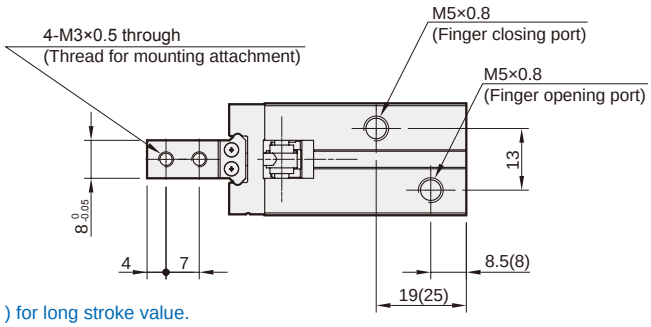






Note. Through-hole mounting is not possible when using the auto switch at the square groove.

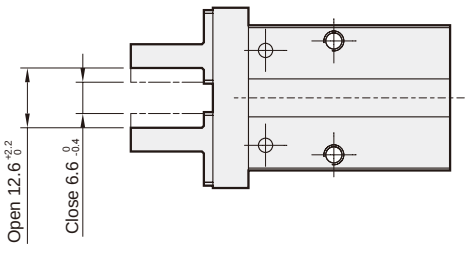


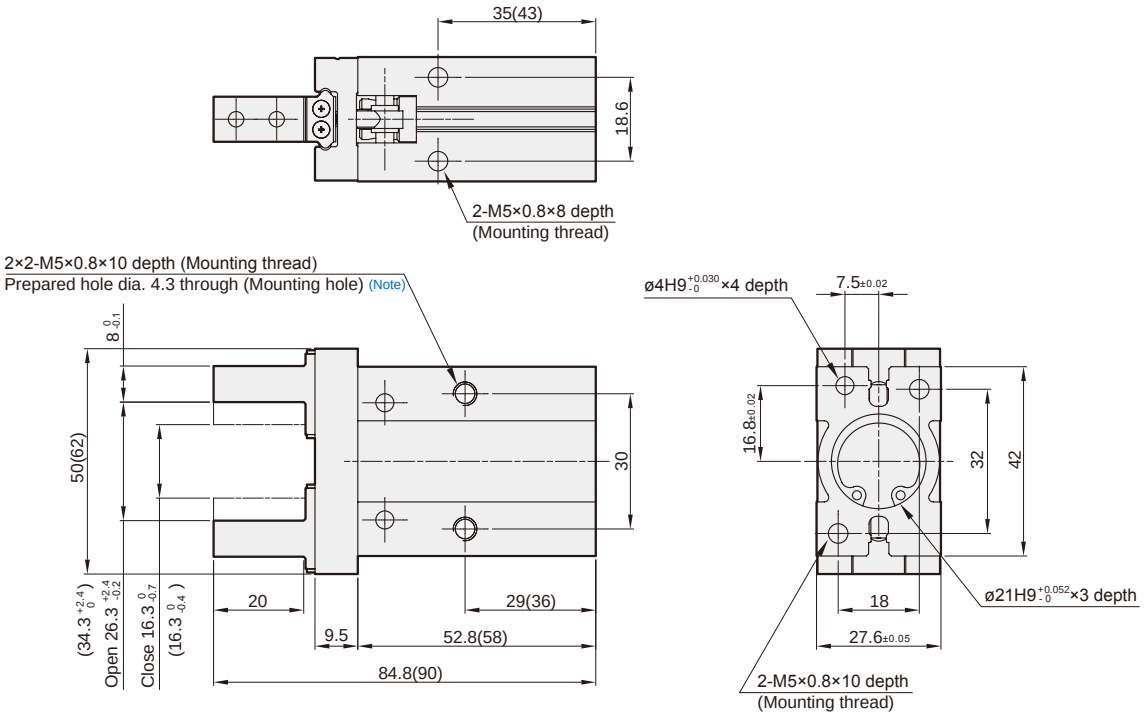


*( ) for long stroke value.

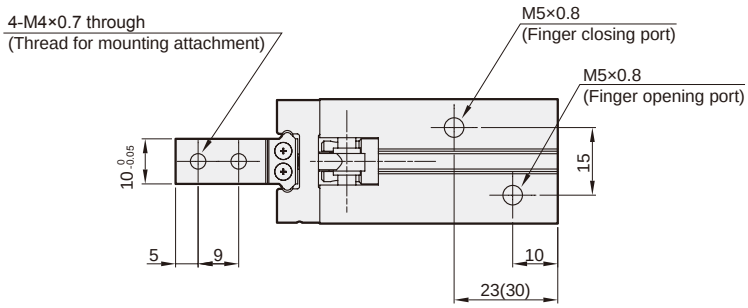
Finger position – Narrow type

MCHC(L)-16-N





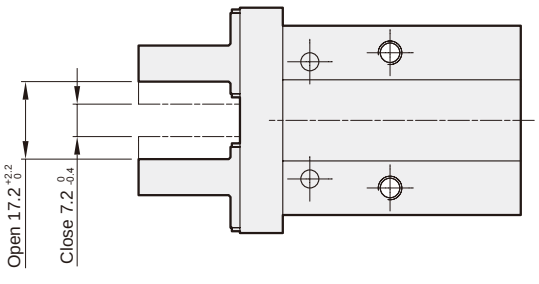
Note. Through-hole mounting is not possible when using the auto switch at the square groove.

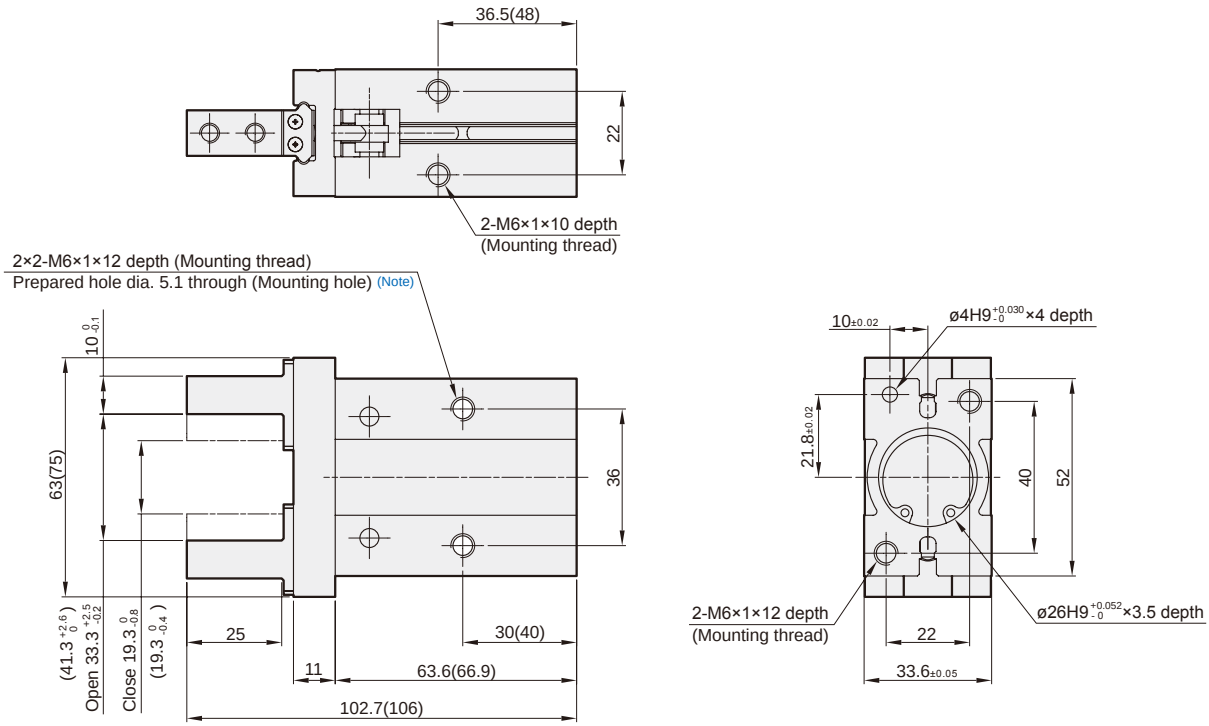


*( ) for long stroke value.

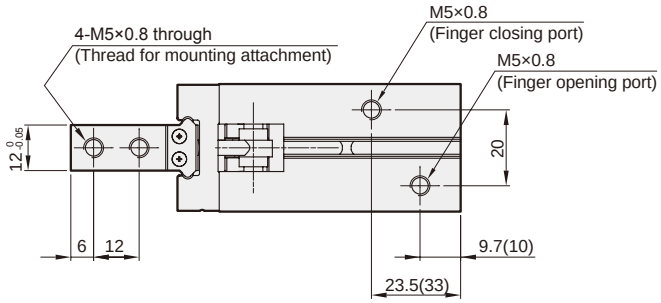
Finger position – Narrow type

MCHC(L)-20-N





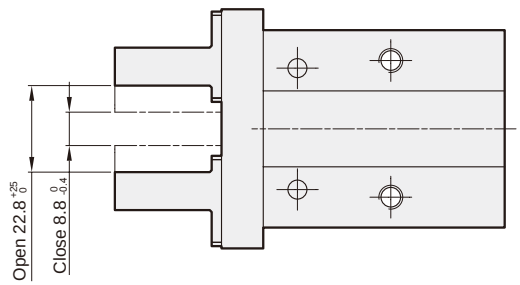
Note. Through-hole mounting is not possible when using the auto switch at the square groove.



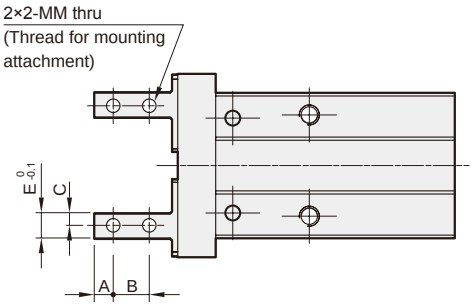
*( ) for long stroke value.

Finger position – Narrow type

MCHC(L)-25-N

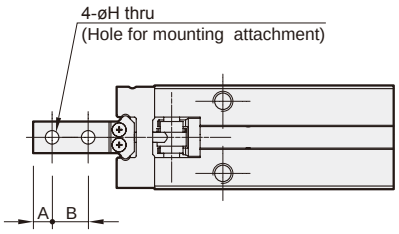


MCHC*-1, N1 Side tapped mounting



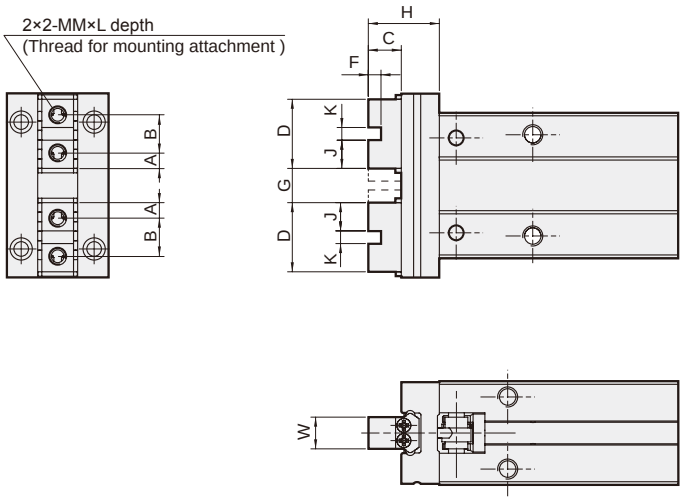
Code / Tube I.D.	A	B	C	E	MM
6	2.5	5	2	4	M2×0.4
10	3	5.7	2	4	M2.5×0.45
16	4	7	2.5	5	M3×0.5
20	5	9	4	8	M4×0.7
25	6	12	5	10	M5×0.8

MCHC*-2, N2 Through hole type



Code / Tube I.D.	A	B	H
6	2.5	5	ø2.4
10	3	5.7	ø2.9
16	4	7	ø3.4
20	5	9	ø4.5
25	6	12	ø5.5

MCHC*-3 Flat type

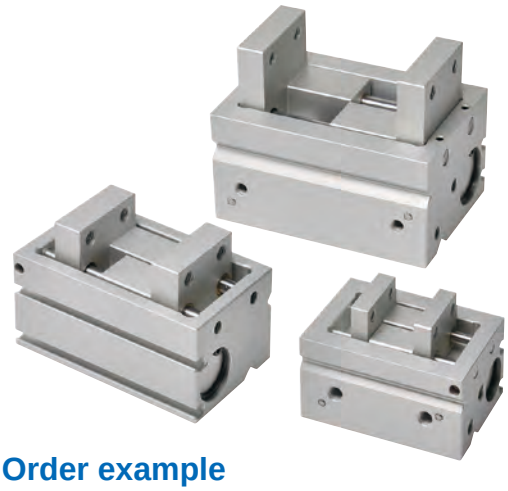


Code / Tube I.D.	A	B	C	D	F	G Open	G Closed	H	J	K	MM	L	W
10	2.45	6	5.2	10.9	2	5.4 +2.2 0	1.4 0 -0.2	11.2	4.45	2H9 +0.025 0	M2.5×0.45	5	5 0 -0.05
16	3.05	8	8.3	14.1	2.5	7.4 +2.2 0	1.4 0 -0.2	15.8	5.8	2.5H9 +0.025 0	M3×0.5	6	8 0 -0.05
20	3.95	10	10.5	17.9	3	11.6 +2.3 0	1.6 0 -0.2	20	7.45	3H9 +0.025 0	M4×0.7	8	10 0 -0.05
25	4.90	12	13.1	21.8	4	16 +2.5 0	2 0 -0.2	24.1	8.9	4H9 +0.03 0	M5×0.8	10	12 0 -0.05

Connect with

AUTOMATIC ASSEMBLY MACHINE

Connect gripper with cylinder to achieve regular workpiece gripping.



Features

- Compact design, low weight with rugged construction.
- Jaws mounted to wear resistant bush guides.
- Proximity and reed switches can be used with this unit.
- Magnetic as standard.

Specification

Model	MCHU		
Acting type	Double acting		
Tube I.D. (mm)	12	16	20
Stroke	15	20	25
Fluid	Air 0.2~0.7 MPa		
Ambient temperature	-10~+60°C (No freezing)		
Lubrication (*1)	Not required		
Repeatability	±0.03 mm		
Sensor switch (*2) 2 wire	**RDFE(V)**: Non-contact		
Sensor switch (*2) 3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP		
Weight (kg)	0.16	0.29	0.58

*1. Sliding area of jaws need scheduled relubrication.
*2. R*FE(V) specification, please refer to page 86.

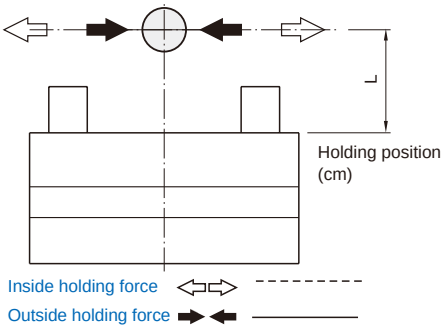
Order example

MCHU — 12 M

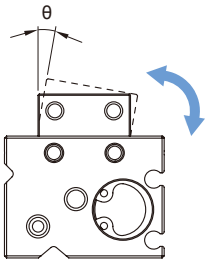
- MODEL: MCHU
- TUBE I.D.: **12**, **16**, **20**
- **M**: Magnet

* Magnetic as standard.

Capacity

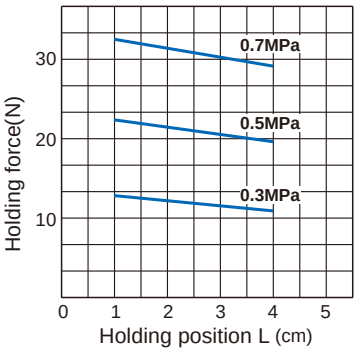


Non-rotaing accuracy

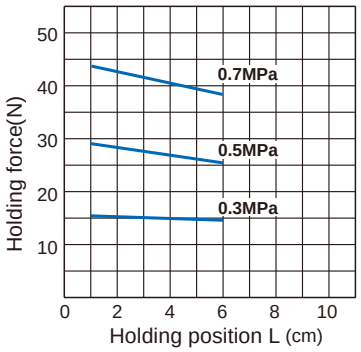


Tube I.D.	(θ)
ø12	±0.25°
ø16	±0.2°
ø20	±0.15°

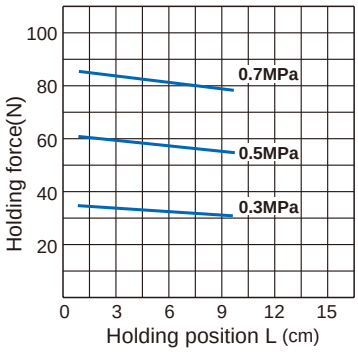
MCHU-12



MCHU-16



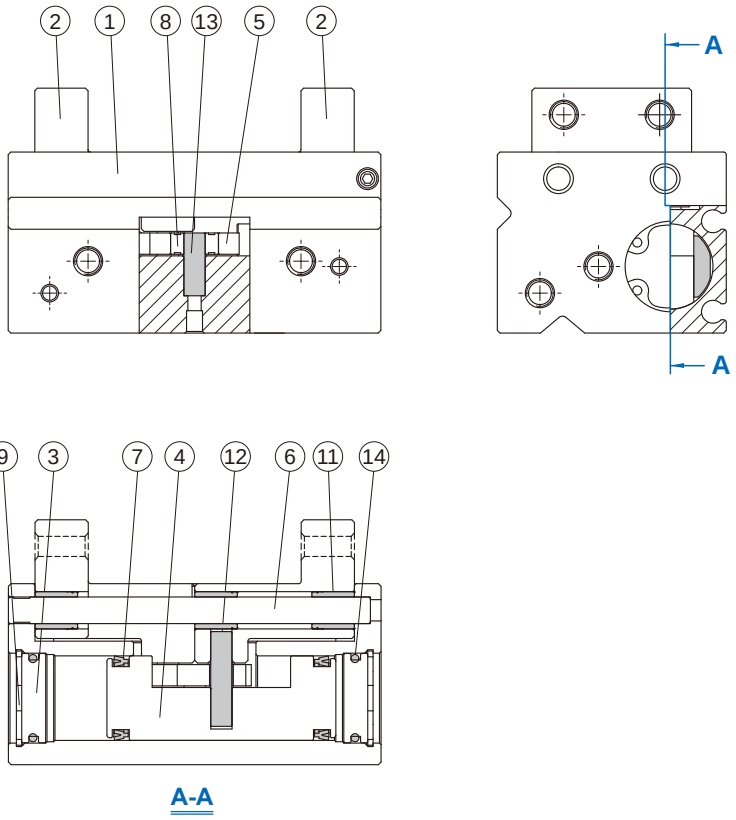
MCHU-20



Model selection suggestions

* Finger selection please refer to page 6.

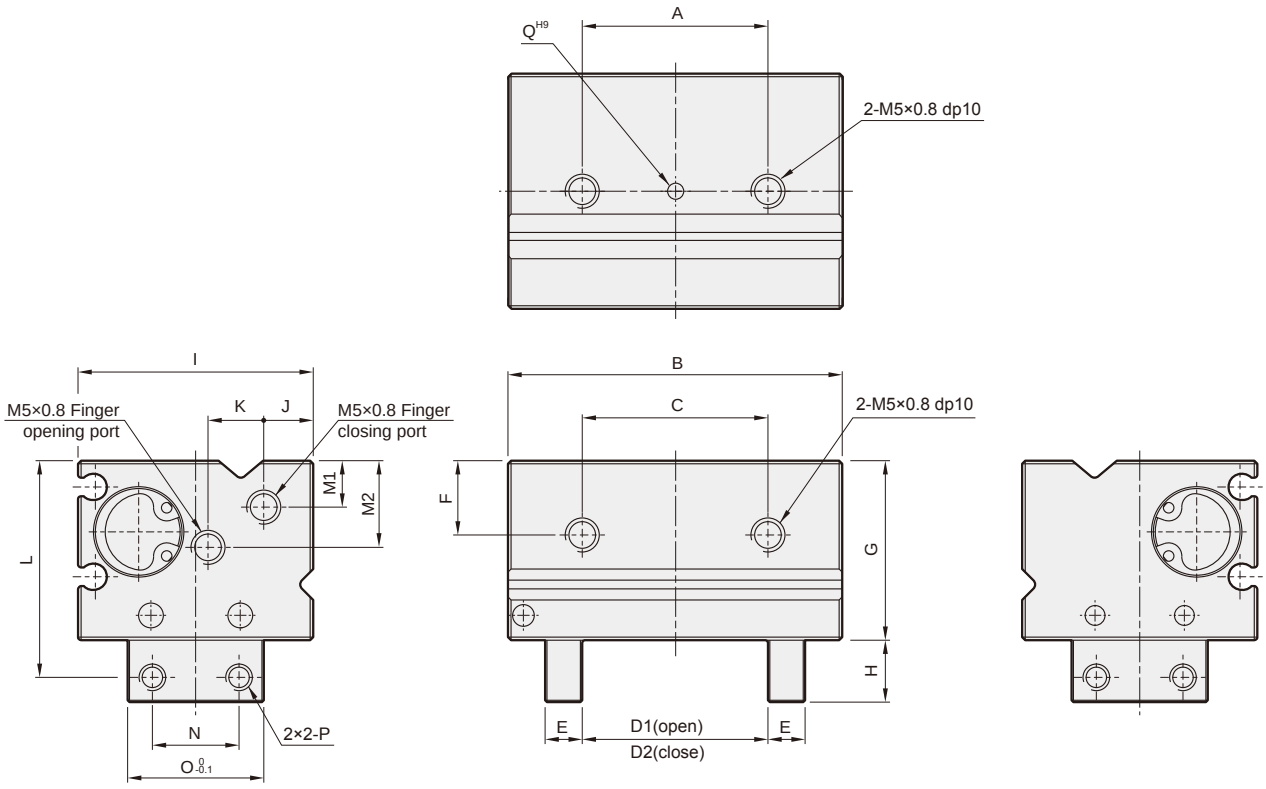
1. For normal gripping and carrying usage, the recommended safe factor (a) is 4.
2. The value of gripping force of single finger can be found at the gripping force table.
3. The safe factor (a) have to be higher if the gripper is using with a great accelerated velocity or impaction condition.



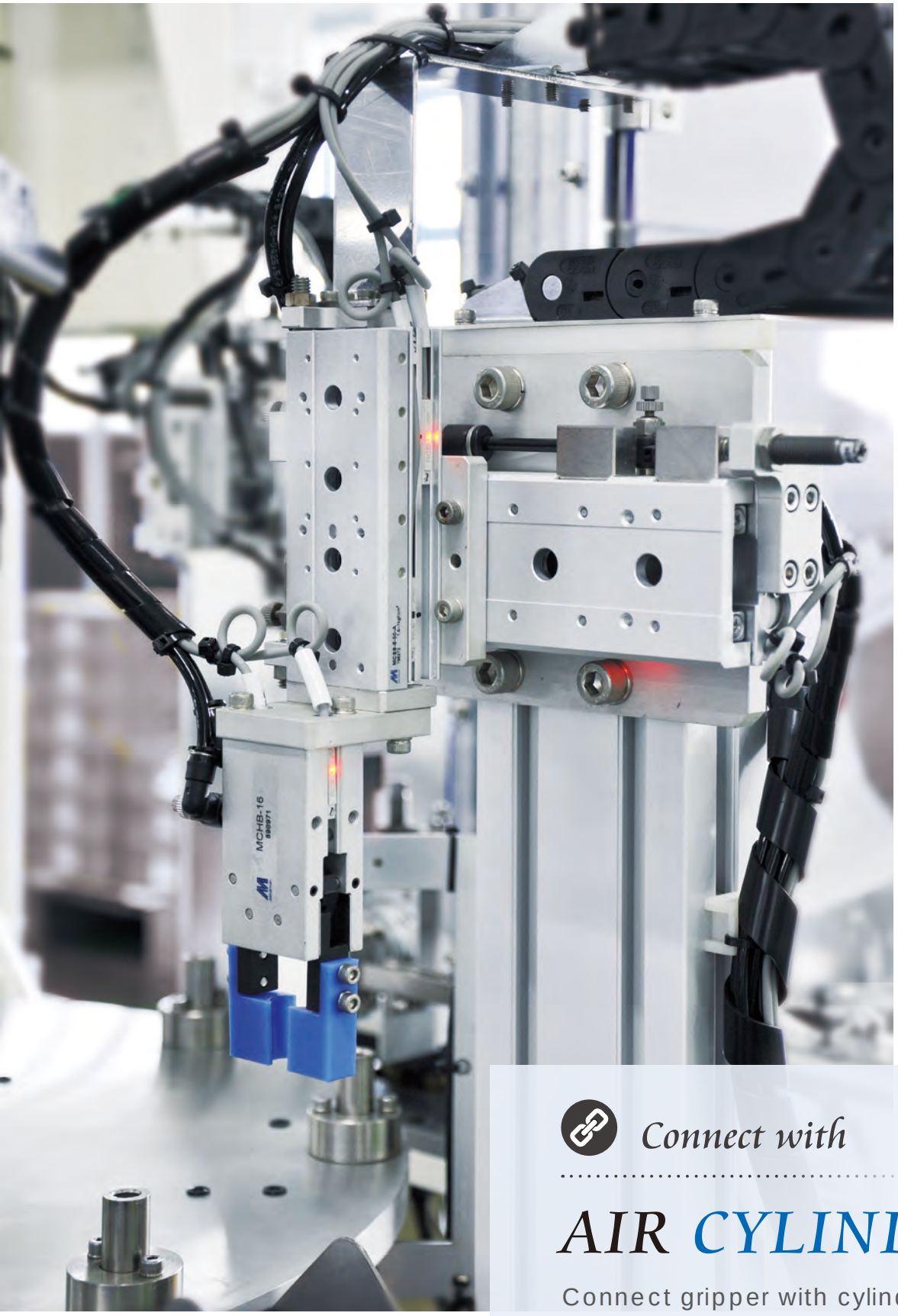
A-A

Material

No.	Tube I.D. / Part name	12	16	20	Q'y
1	Body	Aluminum alloy			1
2	Finger	Aluminum alloy			2
3	Cover	Aluminum alloy			2
4	Piston	Stainless steel			1
5	Cam	SCM			1
6	Guide rod	Carbon steel			2
7	Piston packing	NBR			2
8	Bearing	Bearing steel			1
9	Snap ring	Spring steel			2
10	Magnet	Magnet material			1
11	Bush	Copper			6
12	Pin	High carbon steel			2
13	Pin	High carbon steel			1
14	O-ring	NBR			2



Code / Tube I.D.	A	B	C	D1	D2	E	F	G	H	I	J	K	L	M1	M2	N	O	P	Q H9
12	30	54	30	30	15	6	12	29	10	38	8	9	35	7.5	14	14	22	M4×0.7	ø2 +0.025 -0 ×2dp
16	40	70	40	40	20	10	13.5	34	12	43	8	11	41	7.5	12.5	18	30	M5×0.8	ø3 +0.025 -0 ×4dp
20	60	82	60	50	25	10	15	43	22	56	10	15	59	9	20	20	35	M5×0.8	ø3 +0.025 -0 ×6dp



Connect with

AIR CYLINDER

Connect gripper with cylinder to achieve regular workpiece gripping.

MCHB series

PARALLEL GRIPPER (2-Finger)

Features

- Available with comprehensive range of Tube I.D. 12 ~ 32mm.
- Highly accurate air driven device for holding work-piece.
- Magnetic as standard.

Specification

Model		MCHB				
Acting Type		Double Acting				
Tube I.D. (mm)		12	16	20	25	32
Port size		M3×0.5	M5×0.8			
Medium		Air				
Operating pressure range		0.15~0.7 MPa				
Ambient temperature		-5~+60°C (No freezing)				
Max. frequency		180 Cycles/min				
Lubrication	Cylinder	Not required				
	Lever	Grease (Actuation at)				
Max. arm length (L) (mm)		30	40	60	70	85
Theoretical holding (*1) force (N)	Closed side	8	24	47	75	100
	Opened side	5	18	35	60	85
Lever open / close stroke		6	8	12	14	16
Sensor switch (*2)		RDE, RDE-D: Non-contact				
Weight (g)		66	144	255	419	719

*1. Gripping point length L=30mm, Pressure=0.5 MPa.

*2. RDE, RDE-D specification, please refer to page 85.

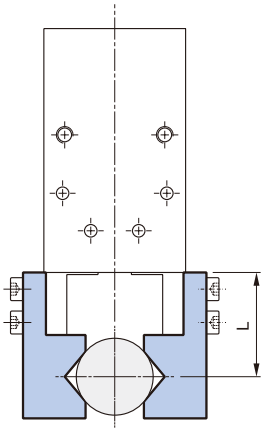
Order example

MCHB — 16

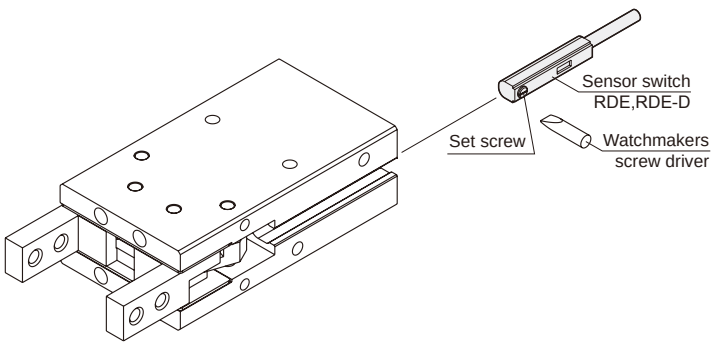
MODEL

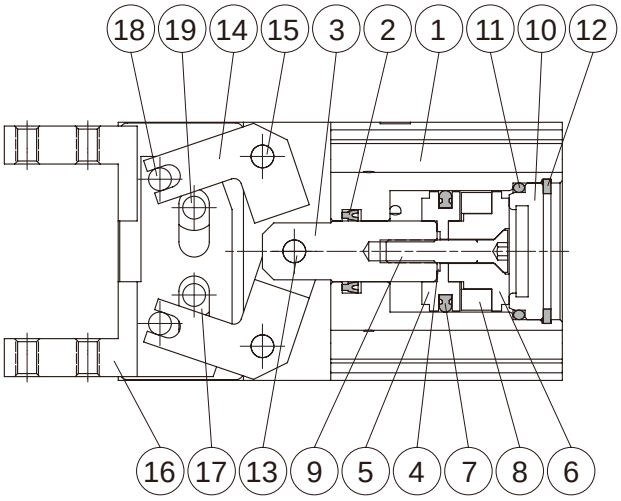
TUBE I.D.
12
16
20
25
32

Length of gripping point



Installation of sensor switch



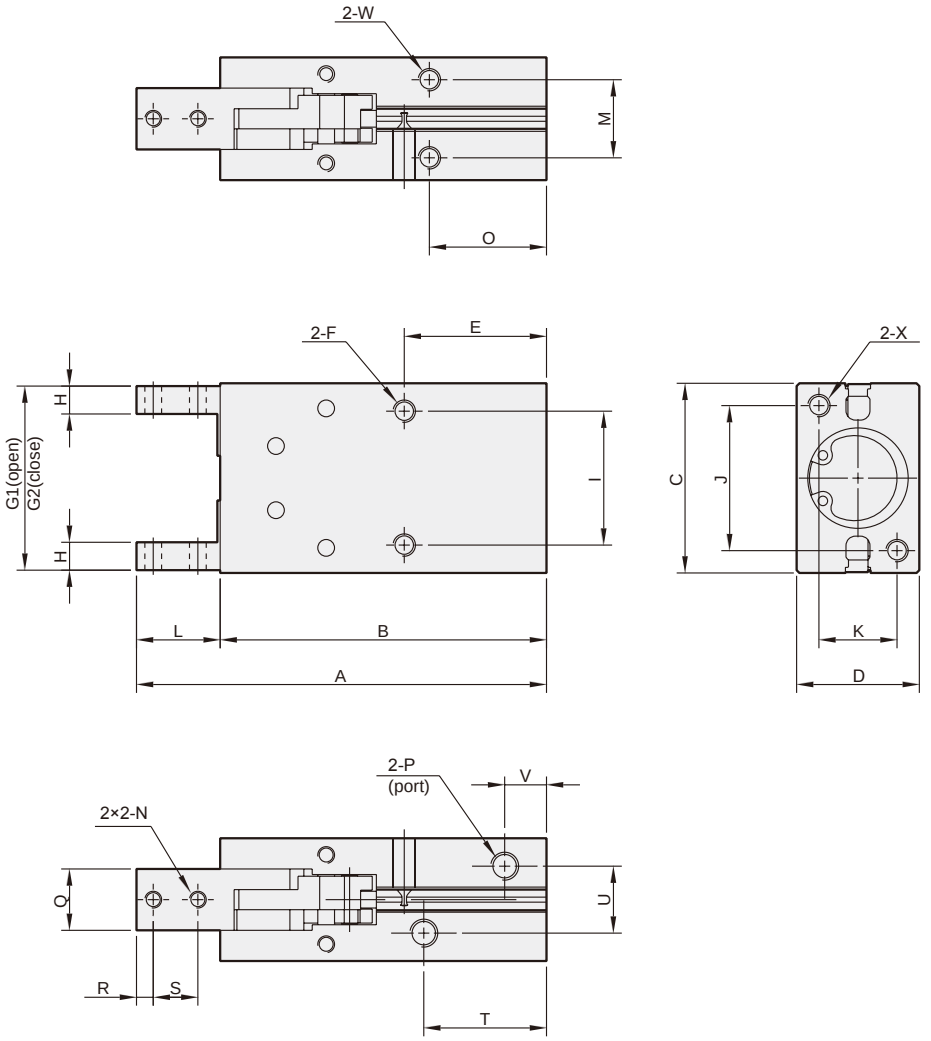


Material

No.	Part name	Material	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy	1	
2	Rod packing	NBR	1	●
3	Piston rod	Stainless steel	1	
4	Gasket	NBR	1	●
5	Piston-R	Aluminum alloy	1	
6	Piston-H	Aluminum alloy	1	
7	Piston packing	NBR	1	●
8	Magnet ring	Magnet material	1	
9	Screw	Stainless steel	1	
10	Head cover	Carbon steel	1	
11	Cover ring	NBR	1	●
12	Stop ring	Spring steel	1	
13	Spindle river	Bearing steel	1	
14	Grip per	Carbon steel	2	
15	Grip rivet	Carbon steel	2	
16	Grip per	Carbon steel	2	
17	Bush	Stainless steel	4	
18	Grip rivet	Bearing steel	2	
19	Grip rivet	Carbon steel	2	
20	Screw	SCM	4	
21	Screw	SCM	4	
22	Washer for grip	Stainless steel	2	

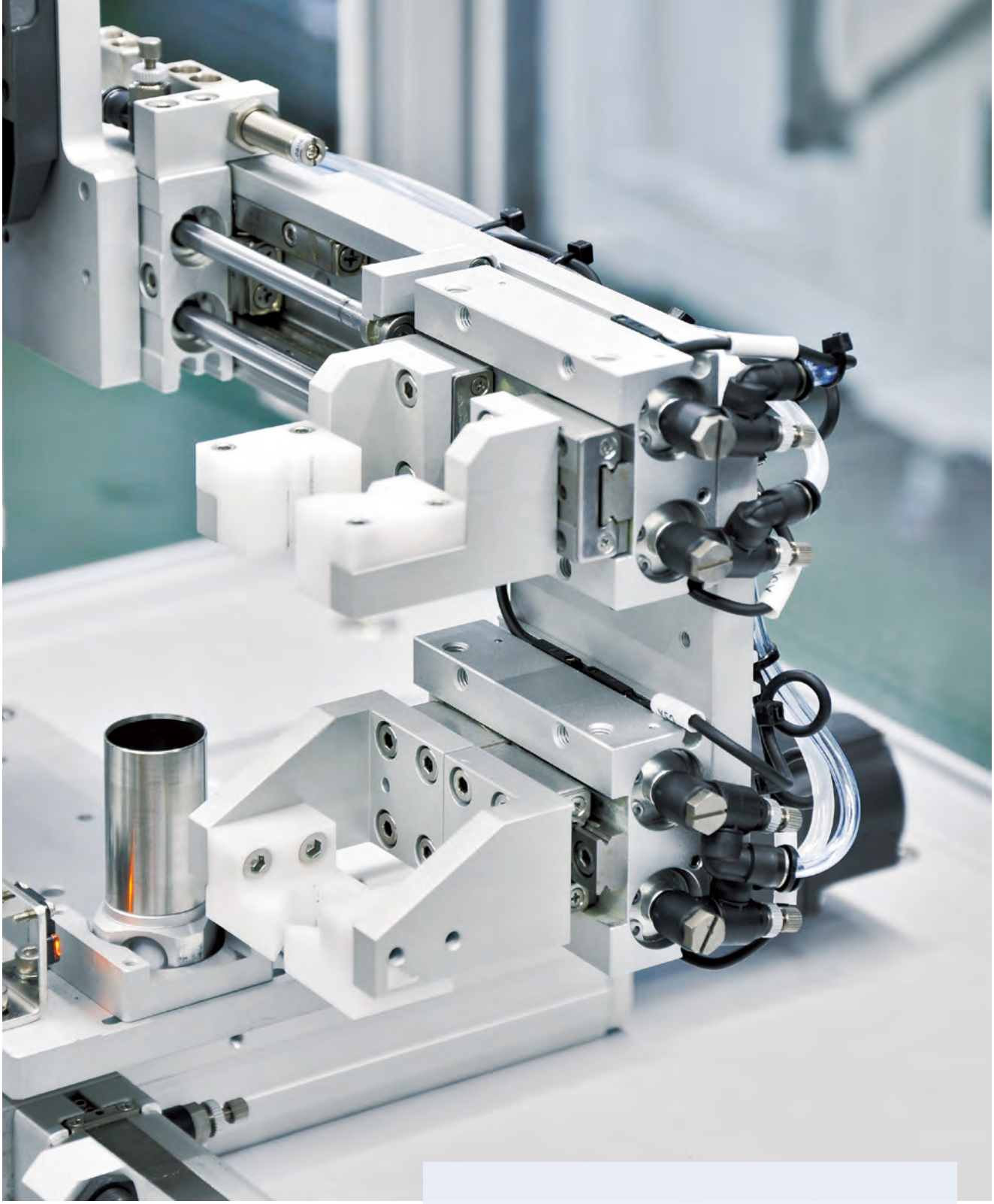
Order example of repair kits

Tube I.D.	Repair kits
ø12	**PS-MCHB-12**
ø16	**PS-MCHB-16**
ø20	**PS-MCHB-20**
ø25	**PS-MCHB-25**
ø32	**PS-MCHB-32**



Code / Tube I.D.	A	B	C	D	E	F	G1	G2	H	I	J	K	L	M	N	O	P	Q	R	S
12	63.5	50.5	28	16	20	M3×0.5×5 depth	27	21	4	18	17	10	13	10	M3×0.5	16	M3×0.5×5 depth	7	3	6
16	73.5	58.5	34	22	25.5	M4×0.7×11 depth	33	25	5	24	26	14	15	14	M3×0.5	21	M5×0.8×5 depth	11	3	8
20	88.5	69.5	45	26	25	M5×0.8×8 depth	44	32	6	30	35	16	19	16	M4×0.7	19	M5×0.8×5 depth	12	4	10
25	102.5	78.5	52	32	28	M6×1.0×10 depth	51	37	8	36	40	20	24	20	M5×0.8	22	M5×0.8×5 depth	14	5	12
32	120.5	90.5	60	40	34	M6×1.0×10 depth	59	43	10	44	46	24	30	26	M6×1.0	26	M5×0.8×5 depth	20	7	15

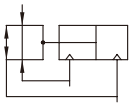
Code / Tube I.D.	T	U	V	W	X
12	23	10.2	7.5	M3×0.5×5 depth	M3×0.5×5 depth
16	22	12	7.5	M4×0.7×7 depth	M4×0.7×7 depth
20	26	13	8	M5×0.8×8 depth	M5×0.8×8 depth
25	29	18	8.5	M6×1.0×10 depth	M6×1.0×10 depth
32	35	24	10.5	M6×1.0×10 depth	M6×1.0×10 depth



Connect with

AIR CYLINDER

Connect gripper with cylinder to achieve regular workpiece gripping.



Features

- Low profile design saves space and reduces bending moments, improved accuracy with smooth operation.
- Improved mounting repeatability, easy positioning for mounting.
- Double piston construction achieves compact design with strong gripping force.
- High rigidity and high precision with martensitic stainless steel.
- Grooves on the body for sensor switch to be inserted into.
- Standard with magnet.

Specification

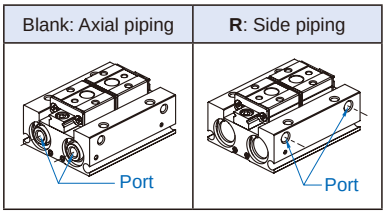
Model		MCHD			
Acting type		Double acting			
Tube I.D. (mm)		8	12	16	20
Port size		M3×0.5	M5×0.8		
Medium		Air			
Operating pressure range		0.15~0.7	0.1~0.7 MPa		
Ambient temperature		-10~+60°C (No freezing)			
Repeatability		± 0.05 mm (*1)			
Max. frequency	Short	120 c.p.m			
	Medium	120 c.p.m			
	Long	60 c.p.m			
Lubricator		Not required			
Sensor switch (*2)	2 wire	**RDFE(V)**: Non-contact			
	3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP			
Attached bolt		2 pcs	—		

* 1. This is the value when no offset load is applied to the finger. When an offset load is applied to the finger, the maximum value is ±0.15mm due to the influence of backlash of the rack and pinion.
* 2. R*FE(V) specification, please refer to page 86.

Order example

MCHD — 20R — □

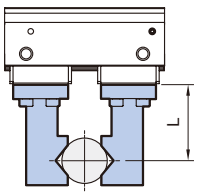
- MODEL
- TUBE I.D. **8, 12, 16, 20**
- PIPING TYPE
  - Blank: Axial piping
  - **R**: Side piping
- STROKE *
  - Blank: Short
  - **1**: Medium
  - **2**: Long



* Stroke selection

Tube I.D. / Stroke (mm)	8	12	16	20
Short stroke	8	12	16	20
Medium stroke	16	24	32	40
Long stroke	32	48	64	80

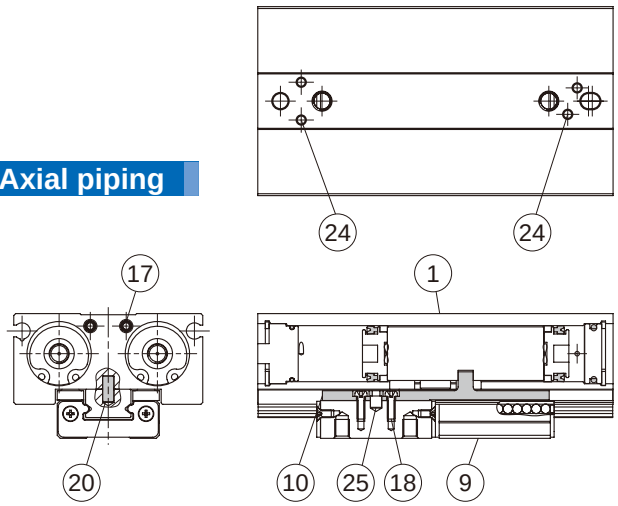
Gripping force



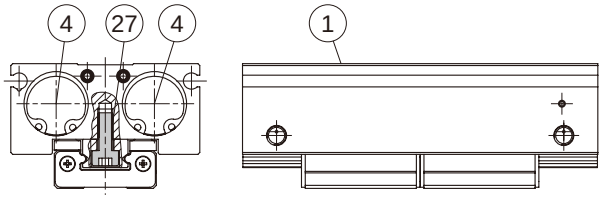
Model	Gripping force per finger effective value (N) (*)	Weight (g)
MCHD-8	19	65
MCHD-8-1		79.1
MCHD-8-2		113.3
MCHD-12	48	150
MCHD-12-1		191.3
MCHD-12-2		291.2
MCHD-16	90	350
MCHD-16-1		454.2
MCHD-16-2		678.3
MCHD-20	141	660
MCHD-20-1		869
MCHD-20-2		1310.6

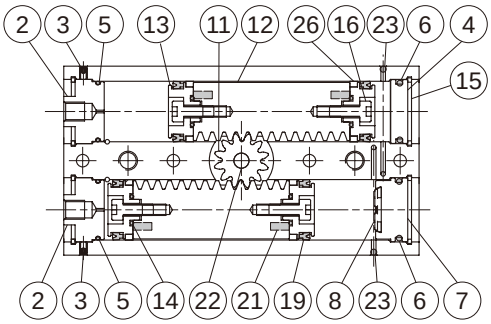
* Values based on pressure of 0.5 MPa, gripping point L=20mm, at center of stroke.

Axial piping



Side piping





Order example of repair kits

Tube I.D.	Repair kits
ø8	**PS-MCHD-8**
	PS-MCHD-8R
ø12	**PS-MCHD-12**
	PS-MCHD-12R

Tube I.D.	Repair kits
ø16	**PS-MCHD-16**
	PS-MCHD-16R
ø20	**PS-MCHD-20**
	PS-MCHD-20R

Material

No.	Tube I.D. / Part name	Material 8	12	16	20	Q'y Axial	Side	Repair kits (inclusion)
1	Body	Aluminum alloy				1	1	
2	Cover A	Aluminum alloy				2	0	
3	Hexgon screw	Stainless steel				2	0	
4	Cover B	Aluminum alloy				1	3	
5	O-ring	NBR				2	0	●
6	O-ring	NBR				2	4	●
7	Cover C	Aluminum alloy				1	1	
8	Cushion pad	TPU				1	1	●
9	Guide set	Stainless steel				1	1	
10	Lever	Stainless steel				2	2	
11	Pinion	SCM				1	1	
12	Pinion piston	Stainless steel				2	2	
13	Piston	*1	Aluminum alloy			4	2	
14	O-ring	NBR				4	4	●
15	Snap ring	Stainless steel				4	4	
16	Bolt	–	Stainless steel			4	4	
17	Screw	Stainless steel				4	4	
18	Screw	Stainless steel				4	4	

No.	Tube I.D. / Part name	Material 8	12	16	20	Q'y Axial	Side	Repair kits (inclusion)
19	Piston packing	NBR				4	4	●
20	Pin	Stainless steel				2	2	
21	Magnet	Magnet material				4	4	
22	Needle	Stainless steel				1	1	
23	Ball	Stainless steel				2	2	
24	Ball	Stainless steel				4	4	
25	Needle	Stainless steel				2	2	
26	Wear ring *2	Teflon				4	4	
27	Bolt *3	Stainless steel				**K**	**K**	

*1. Stainless steel
*2. Model MCHD-8(R)(-1), MCHD-12(R)(-1) without wear ring.

*3. **Bolt** Q'y

Model	K
MCHD-8	2
MCHD-8-1	2
MCHD-8-2	4
MCHD-12	2
MCHD-12-1	4
MCHD-12-2	4

Model	K
MCHD-16	2
MCHD-16-1	4
MCHD-16-2	4
MCHD-20	2
MCHD-20-1	4
MCHD-20-2	4

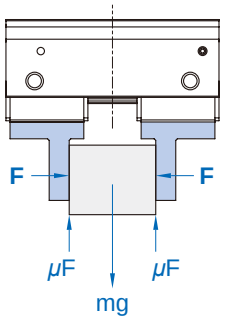
Model selection

Please select your model according to the weight of workpiece

- Although conditions differ according to the work piece shape and the coefficient of friction between the attachments and the workpiece, select a model that can provide a gripping force of 10 to 20 times the workpiece weight, or more.
- If high acceleration, deceleration or impact forces are encountered during motion, a further margin of safety should be considered.

When gripping a workpiece as in the figure as shown above:

F: Gripping force (N)
μ: Coefficient of friction between the attachments and the workpiece
m: Workpiece mass (kg)
g : Gravitational acceleration (=9.8m/s^2)
mg : Workpiece weight (N)



the conditions under which the workpiece will not drop are,

$$2\times\mu F > mg$$

(2 → Number of fingers)

Therefore,

$$F > \frac{mg}{2\times\mu}$$

With"a"representing the extra margin, "F" is determined by the following formula:

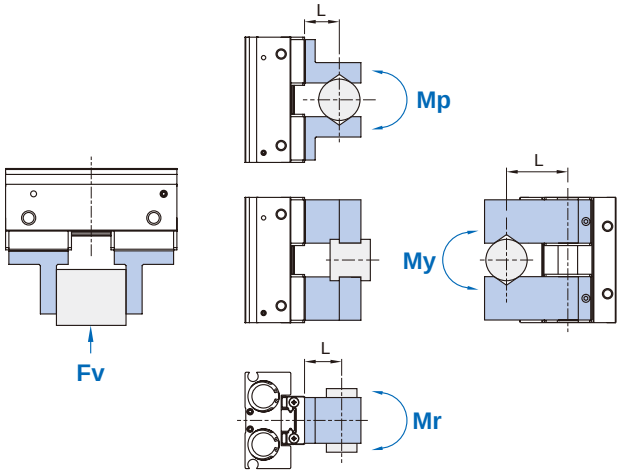
$$F = \frac{mg}{2\times\mu}\times a$$

The "10 to 20 times or more of the workpiece weight" is calculated with a safety margin of a=4, which allows for impacts that occur during normal transportation, etc.

μ=0.2	μ=0.1
$F = \frac{mg}{2\times0.2}\times 4$ $= 10\times mg$	$F = \frac{mg}{2\times0.1}\times 4$ $= 20\times mg$
10×workpiece weight	20×workpiece weight

* 1. Even in cases where the coefficient of friction is greater than μ=0.2, for reasons of safety, please select a gripping force which is at least 10 to 20 times greater than the workpiece weight.
* 2. If high acceleration, deceleration or impact forces are encountered during motion, a further margin of safety should be considered.

Confirmation of external force on fingers



L: Distance to the point at which the load is applied (mm)

Tube I.D. (mm)	Allowable vertical load Fv(N)	Maximum allowable moment		
		Pitch moment Mp(N-m)	Yaw moment My(N-m)	Roll moment Mr(N-m)
8	58	0.26	0.26	0.53
12	98	0.68	0.68	1.4
16	176	1.4	1.4	2.8
20	294	2	2	4

* Values for load and moment in the table indicate static values.

Allowable load calculation

$$\text{Allowable load } F(N) = \frac{M(\text{maximum allowable moment})(N\cdot m)}{L(m)}$$

Example
When a static load of f=20N is operating, which applies pitch moment to point L=25mm from the **MCHD-16** guide.

$$\text{Allowable load } F(N) = \frac{1.4\ (N\cdot m)}{25\times10^{-3}(m)}$$

$$= 56\ (N)$$

Load f=20 (N) < 56 (N), so can be used.

Model selection example

In the motion process did not produce high acceleration, deceleration or impact forces,
Workpiece mass: 300g , Gripping method: External gripping,
Operating pressure: 0.5 MPa, Coefficient of friction (μ): 0.1,
Holding position: 20mm (no overhang)

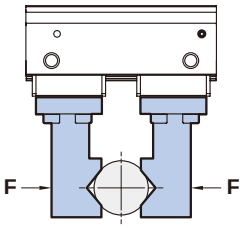
1. The conditions under which the workpiece will not drop are,

$$F = \frac{0.3}{2\times0.1}\times 4 = 6\ (kgf) \approx 60\ (N)$$

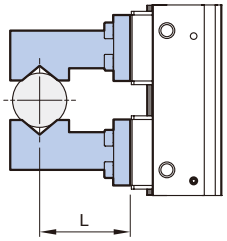
2. From Effective Gripping Force Fig,
Operating pressure: 0.5 MPa; Holding position: 20 mm
Effective gripping force is greater than 60 (N)
So selected **MCHD-16** grippers.

Effective gripping force (Double acting)

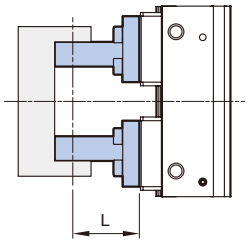
Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



1N=0.102 kgf
1MPa=10.2 kgf/cm^2

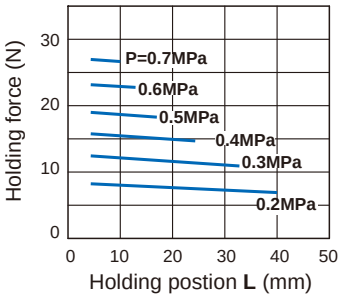


External grip

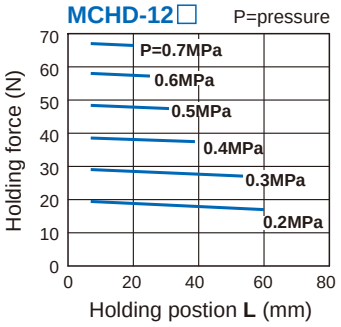


Internal grip

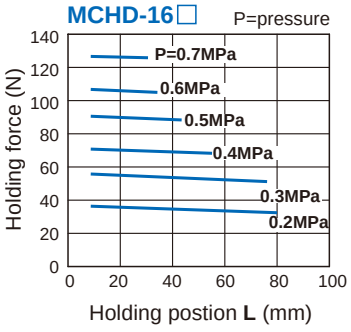
MCHD-8□ P=pressure



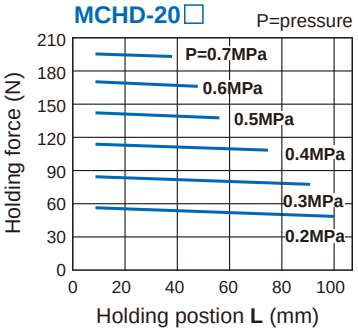
MCHD-12□ P=pressure



MCHD-16□ P=pressure

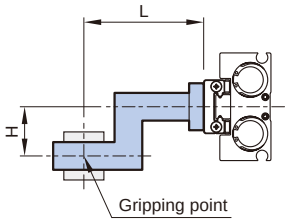


MCHD-20□ P=pressure

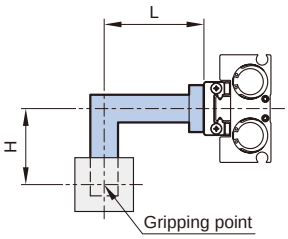


Confirmation of gripping point

- The air gripper should be operated so that the workpiece gripping point "L " and the amount of overhang "H" stay within the range shown for each operating pressure given in the graphs.
- If the workpiece gripping point goes beyond the range limits, this will have an adverse effect on the life the air gripper.

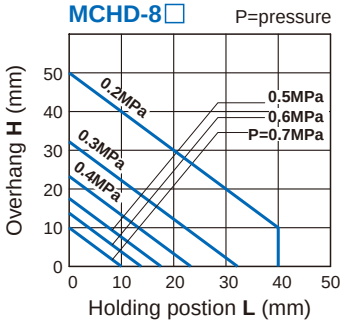


External grip

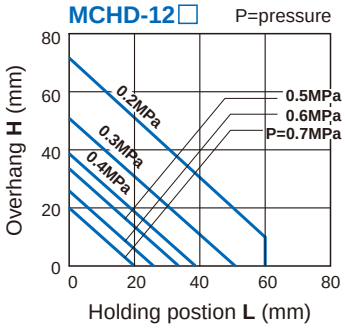


Internal grip

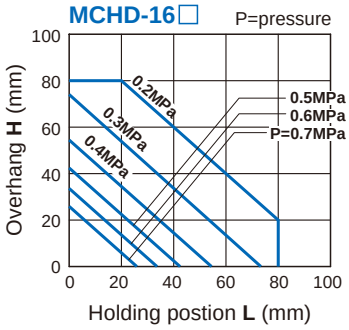
MCHD-8□ P=pressure



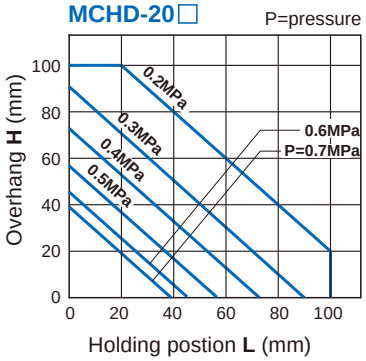
MCHD-12□ P=pressure



MCHD-16□ P=pressure



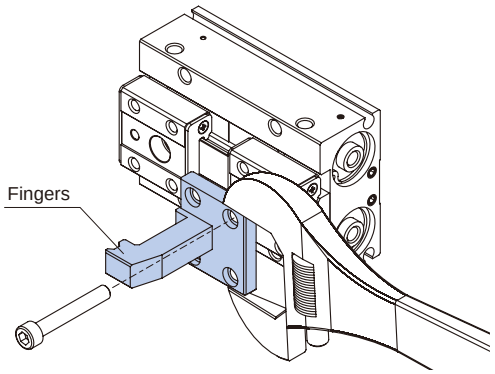
MCHD-20□ P=pressure



Product precautions

Before mount the fingers, sure be refer the tightening torque values in the table below.

Tube I.D. (mm)	Bolt	Max. tightening torque (N.m)
8	M2.5×0.45	0.36
12	M3×0.5	0.63
16	M4×0.7	1.5
20	M4×0.7	1.5



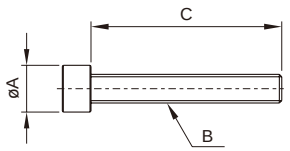
Order example of attached bolt

* One set includes 2 pcs, long stroke type need two sets (4 pcs).

BOLT — MCHD — 8

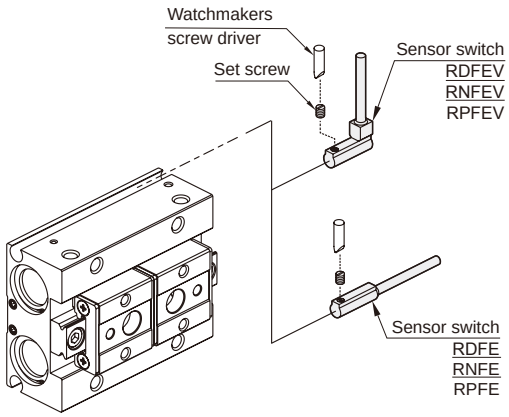
ATTACHED BOLT

TUBE I.D.
8
12



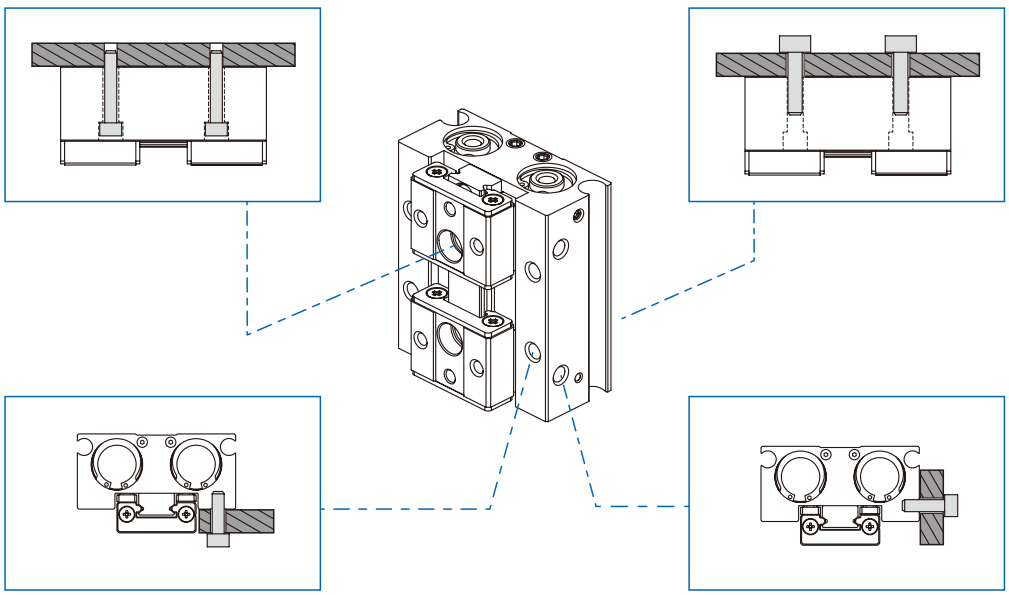
Code / Tube I.D.	A	B	C
8	3.8	M2.5×0.45	15
12	4.9	M3×0.5	20

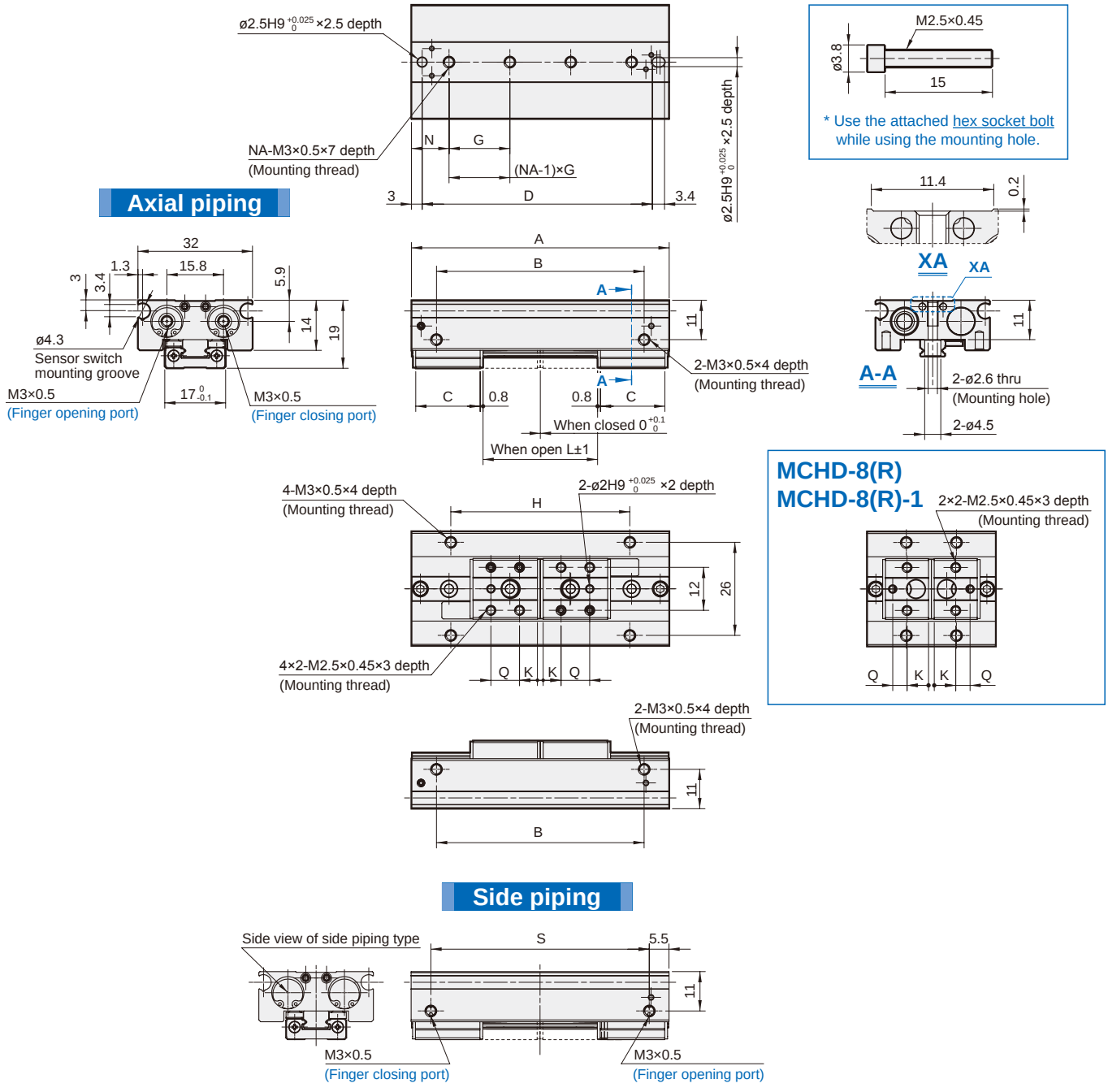
Installation of sensor switch



High degree of mounting flexibility

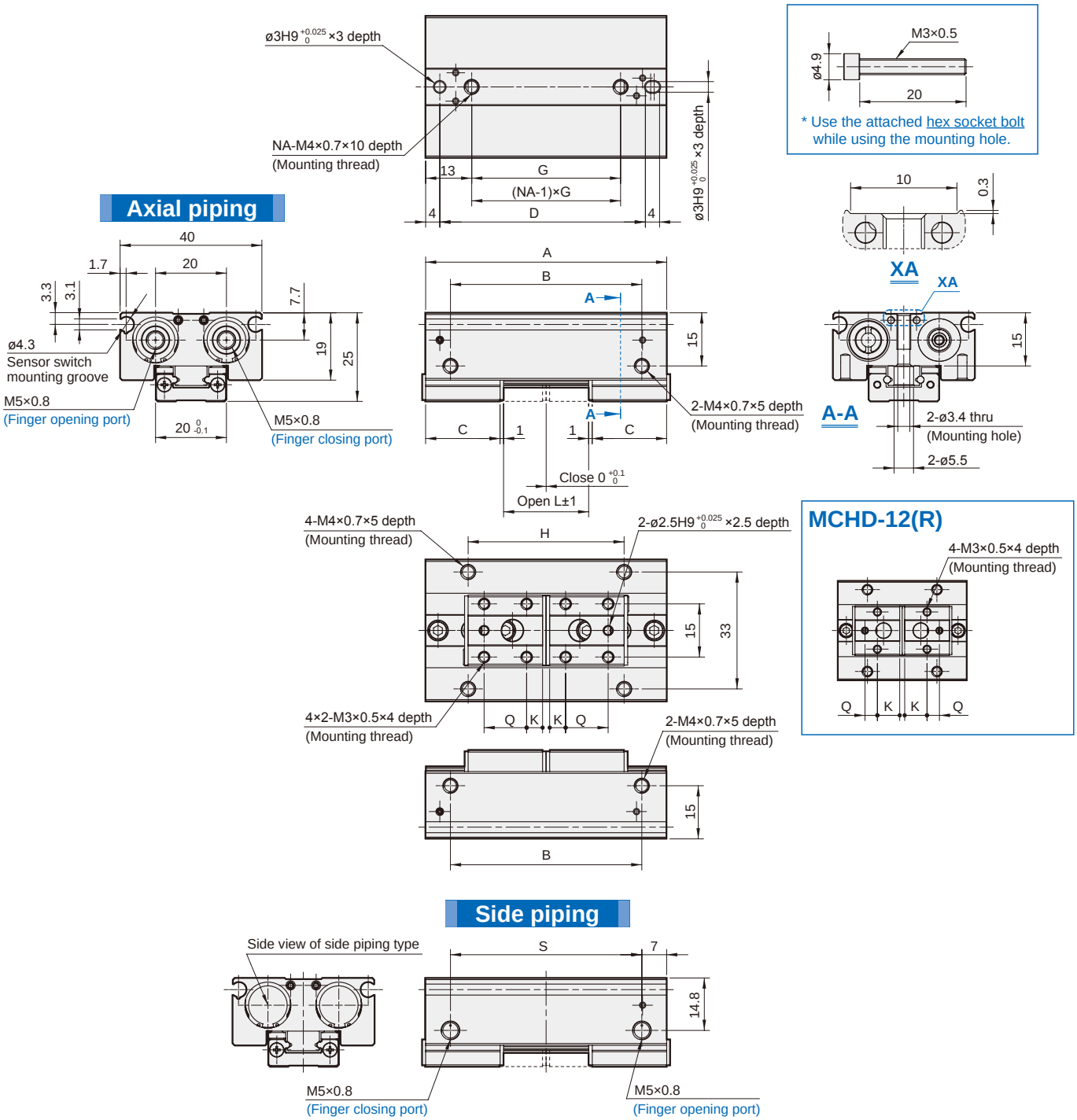
* Use the attached bolt for mounting in tube I.D. ø8, ø12.





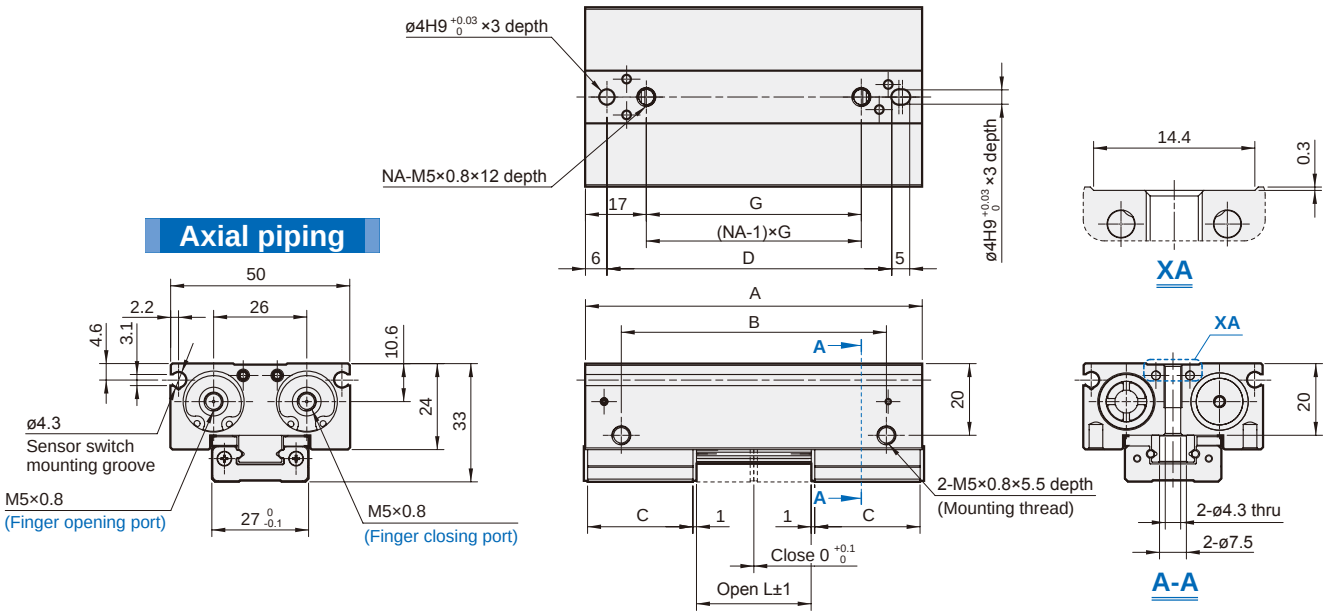
Unit: mm

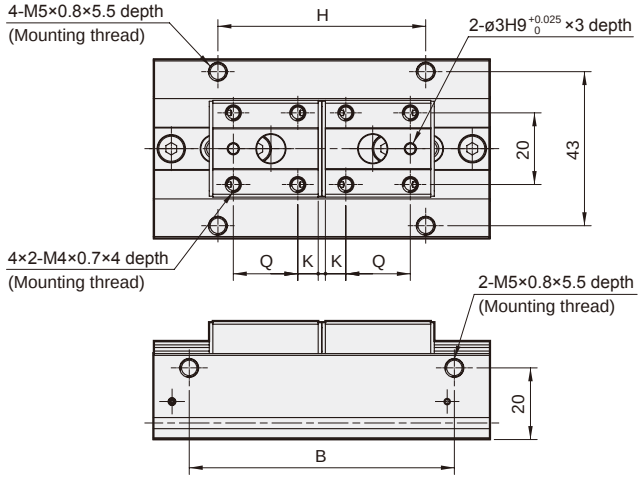
Code / Model	A	B	C	D	G	H	K	L	N	NA	Q	S
MCHD-8(R)	36	22	12	28.3	16	14	6	8	10	2	4	25
MCHD-8(R)-1	48	34	14	40.3	28	26	7	16	10	2	4	37
MCHD-8(R)-2	72	58	18	64.3	17	50	5	32	10.5	4	8	61

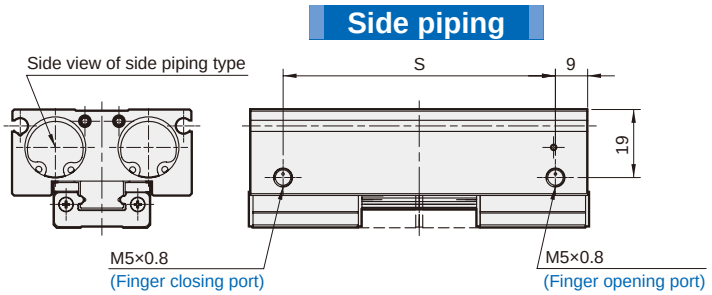


Unit: mm

Code / Model	A	B	C	D	G	H	K	L	NA	Q	S
MCHD-12(R)	52	38	18	42	26	28	9	12	2	5	38
MCHD-12(R)-1	68	54	21	58	42	44	4.5	24	2	12	54
MCHD-12(R)-2	104	90	27	94	26	80	4.5	48	4	18	90

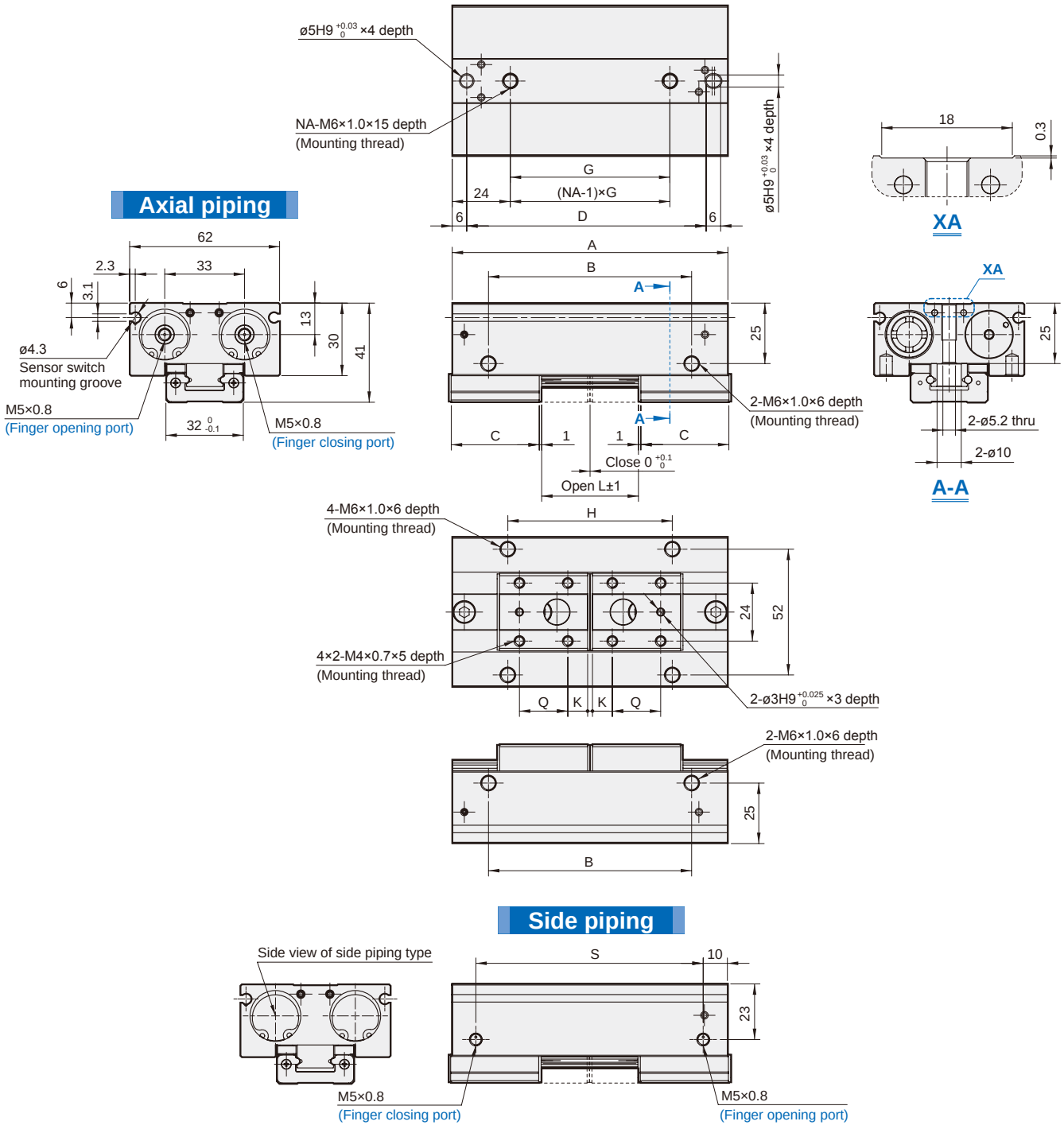






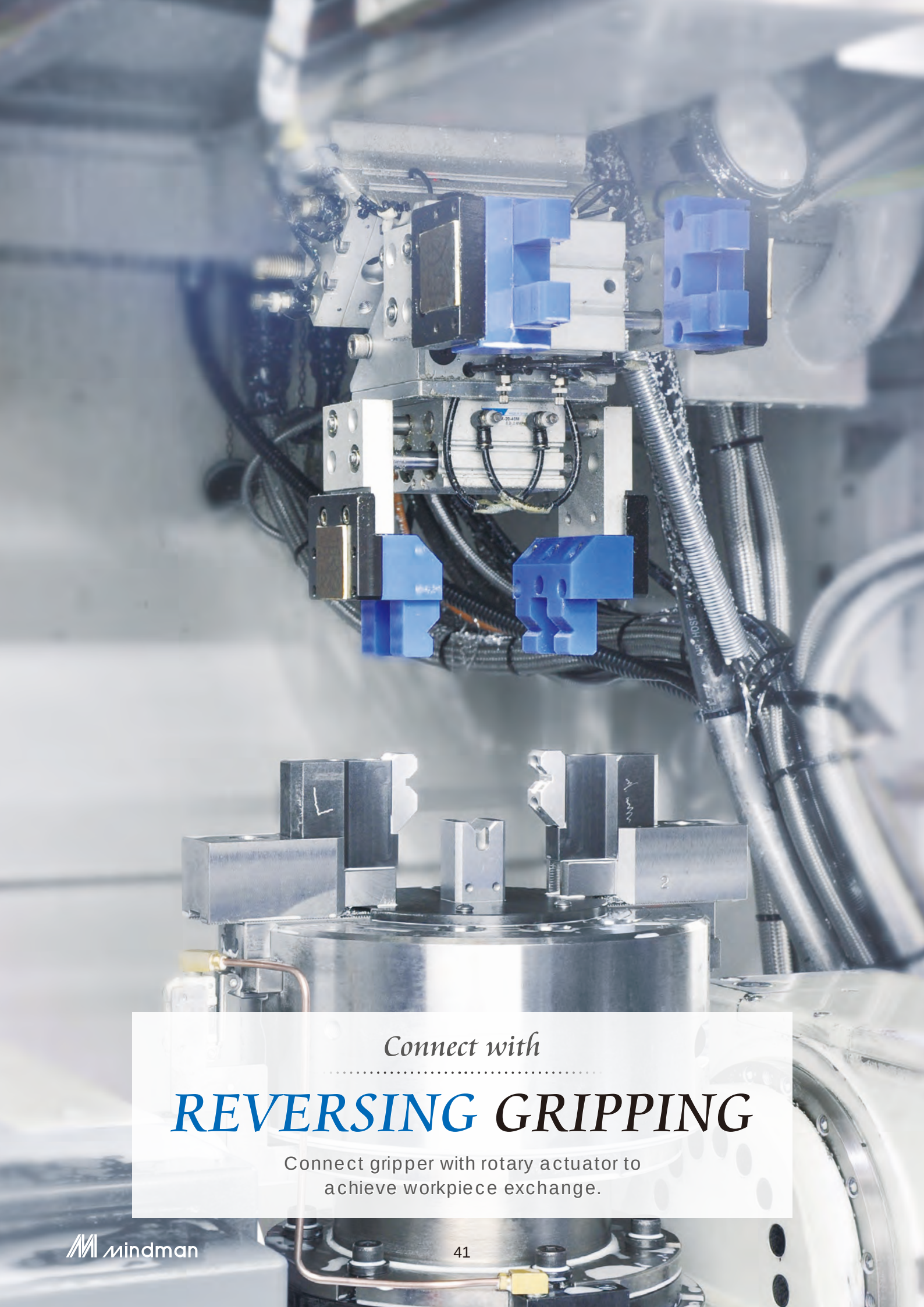
Unit: mm

Code / Model	A	B	C	D	G	H	K	L	NA	Q	S
MCHD-16(R)	72	52	25.4	57.5	38	36	5.2	16	2	15	54
MCHD-16(R)-1	94	74	29.4	79.5	60	58	5.7	32	2	18	76
MCHD-16(R)-2	142	122	37.4	127.5	36	106	5.7	64	4	26	124



Unit: mm

Code / Model	A	B	C	D	G	H	K	L	NA	Q	S
MCHD-20(R)	86	56	31.4	71	38	40	7.7	20	2	16	66
MCHD-20(R)-1	114	84	36.4	99	66	68	8.2	40	2	20	94
MCHD-20(R)-2	174	144	46.4	159	42	128	8.2	80	4	30	154



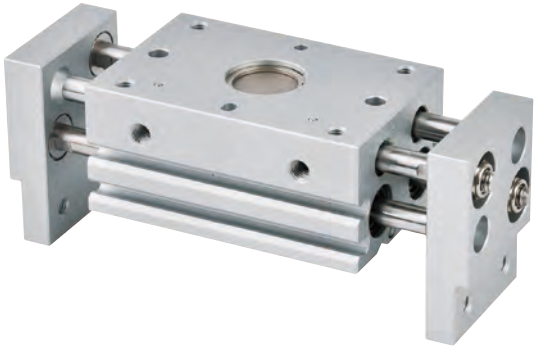
Connect with

REVERSING GRIPPING

Connect gripper with rotary actuator to
achieve workpiece exchange.

MCHX series

WIDE TYPE **PARALLEL GRIPPER** (2-Finger)



Features

- Rack and pinion construction enable synchronisation of both jaws enabling smooth and consistent gripping force.
- Wide range of strokes available.
- Dust seals protect all internal parts from ingress of dirt.
- Proximity and reed switches can be used with this unit.
- Magnetic as standard.

Specification

Model	MCHX				
Acting type	Double acting				
Tube I.D. (mm)	10	16	20	25	32
Stroke	20,40,60	30,60,80	40,80,100	50,100,120	70,120,160
Medium	Air				
Operating pressure range	0.2~0.6 MPa				
Ambient temperature	-5~+60°C (No freezing)				
Lubrication (*1)	Not required				
Repeatability	±0.1 mm				
Sensor switch (*2) 2 wire	**RDFE(V)**: Non-contact				
Sensor switch (*2) 3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP				

*1. Sliding area of jaws need scheduled relubrication.

*2. R*FE(V) specification, please refer to page 86.

Order example

MCHX — 16 — 30 M

MODEL

TUBE I.D.	STROKE
10	**20, 40, 60**
16	**30, 60, 80**
20	**40, 80, 100**
25	**50, 100, 120**
32	**70, 120, 160**

M: Magnet

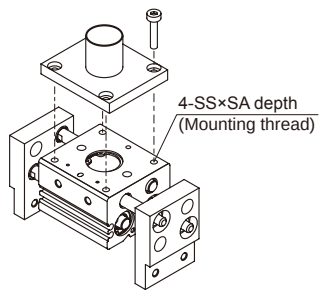
* Magnetic as standard.

Weight

Model	MCHX-10			MCHX-16			MCHX-20			MCHX-25			MCHX-32		
Stroke (mm)	20	40	60	30	60	80	40	80	100	50	100	120	70	120	160
Max. operating frequency (c.p.m)	60	40	40	60	40	40	60	40	40	60	40	40	30	20	20
Weight (kg)	0.28	0.35	0.44	0.56	0.8	0.94	1.0	1.5	1.68	1.69	2.8	3.0	3.15	4.36	5.02

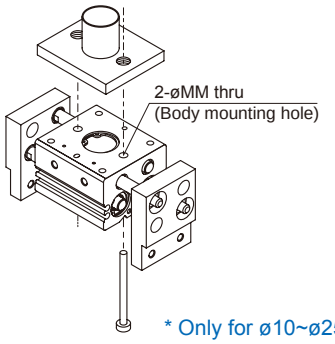
Mounting

Axial mounting



Model	SA	SS	Max. tightening torque (N.m)
MCHX-10	8	M4×0.7	2.1
MCHX-16	10	M5×0.8	4.3
MCHX-20	12	M6×1.0	7.3
MCHX-25	16	M8×1.25	17.7
MCHX-32	16	M8×1.25	18

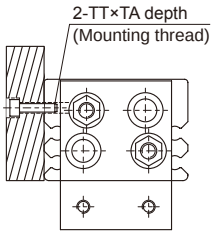
Axial mounting



* Only for ø10~ø25.

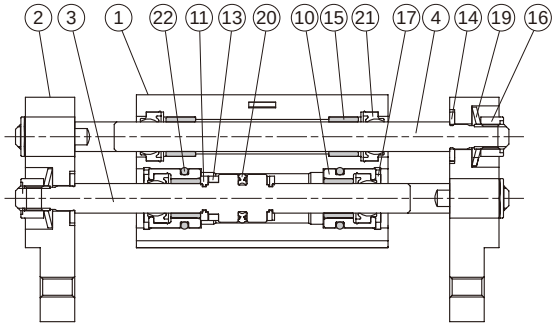
Model	MM	Bolt	Max. tightening torque (N.m)
MCHX-10	4.5	M4×0.7	2.1
MCHX-16	5.5	M5×0.8	4.3
MCHX-20	6.6	M6×1.0	7.3
MCHX-25	9	M8×1.25	17.7
MCHX-32	–	–	–

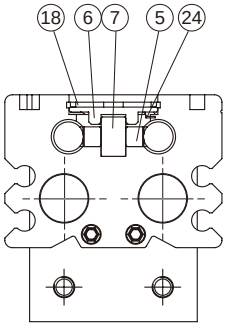
Lateral mounting



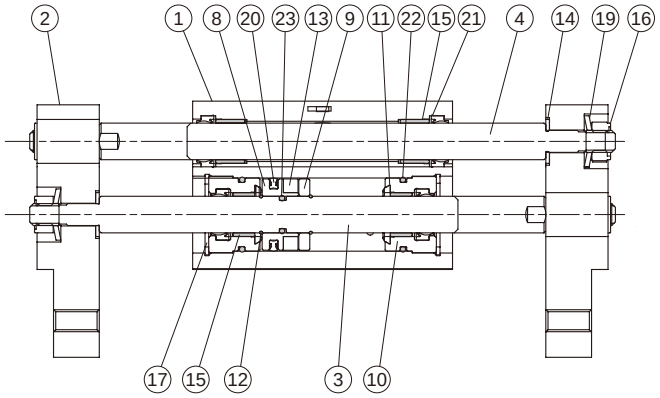
Model	TA	TT	Max. tightening torque (N.m)
MCHX-10	5	M4×0.7	1.4
MCHX-16	7	M5×0.8	2.8
MCHX-20	7	M6×1.0	4.8
MCHX-25	7	M8×1.25	12
MCHX-32	11	M8×1.25	12

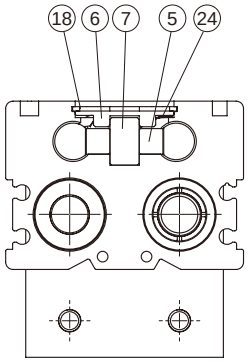
ø10





ø16~ø32





Material

No.	Tube I.D. / Part name	10	16	20	25	32	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy					1	
2	Finger	Aluminum alloy					2	
3	Piston rod	Stainless steel					2	
4	Rack	Stainless steel					2	
5	Pinion	Carbon steel					1	
6	Pinion cover	Carbon steel					1	
7	Pinion axis	Stainless steel					1	
8	Piston	–	Brass				2	
9	Magnet holder	–	Brass				2	
10	Rod cover	Aluminum alloy					4	
11	Damper	NBR	PU	NBR			4	●
12	Stop ring	–	Spring steel		*1	*2	4	
13	Magnet	Magnet material					2	
14	Washer	Stainless steel			Carbon steel		4	
15	Bearing	Oil containing polyacetal with back metal					8	
16	U nut	Carbon steel					4	
17	R-shape snap ring	*3	*1	Carbon steel			4	
18	C-shape snap ring	Carbon steel					1	
19	Conical spring washer	Stainless steel					4	
20	Piston packing	NBR					2	●
21	Rod packing	NBR					8	●
22	O-ring	NBR					4	●
23	O-ring	–	NBR				2	
24	Wave washer	Carbon steel					1	

Order example of repair kits

Tube I.D.	Repair kits
ø10	**PS-MCHX-10**
ø16	**PS-MCHX-16**
ø20	**PS-MCHX-20**
ø25	**PS-MCHX-25**
ø32	**PS-MCHX-32**

*1. Stainless steel
*2. Spring steel
*3. Carbon steel

Model selection example

* Finger selection please refer to page 6.

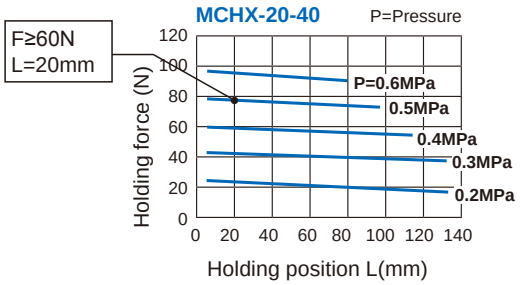
In the motion process did not produce high acceleration, deceleration or impact forces, Workpiece mass: 0.3kg , Gripping method: External gripping, Operating pressure: 0.5 MPa, Coefficient of friction (μ): 0.1, Holding position: L=20mm (no overhang)

1. Based on the above formula, the required gripping force can be derived:

$$F \geq \frac{0.3\times9.8}{2\times0.1} \times 4$$

$$\geq 60(N)$$

2. From Effective Gripping Force Fig, Operating pressure: 0.5 MPa; Holding position: 20 mm Effective gripping force is greater than 60 (N) So selected **MCHX-20-40** grippers.

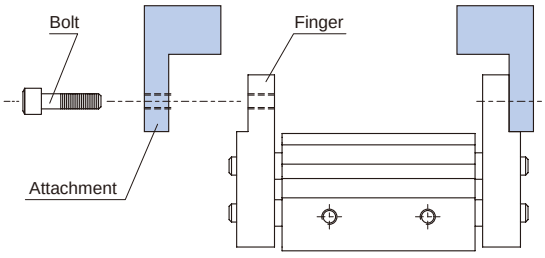


Model selection suggestions

1. For normal gripping and carrying usage, the recommended safe factor (a) is 4.
2. The value of gripping force of single finger can be found at the gripping force table.
3. The safe factor (a) have to be higher if the gripper is using with a great accelerated velocity or impaction condition.

Mounting precautions

1. To prevent bending the piston rod, please mount the attachment when finger is closing.
2. Do not scratch or dent the sliding portion of the piston rod, or it may cause air leaks or faulty operation.
3. Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.



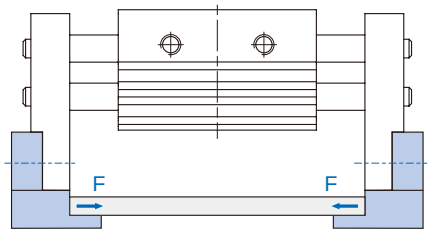
Model	Bolt	Max. tightening torque (N.m)
MCHX-10	M4×0.7	1.4
MCHX-16	M5×0.8	2.8
MCHX-20	M6×1.0	4.8
MCHX-25	M8×1.25	12
MCHX-32	M10×1.5	24

Applications

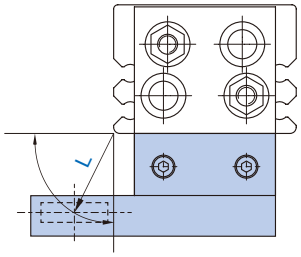
Connect with rotary actuator to roate workpiece in a automatic manufacture line.

Effective gripping force

Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

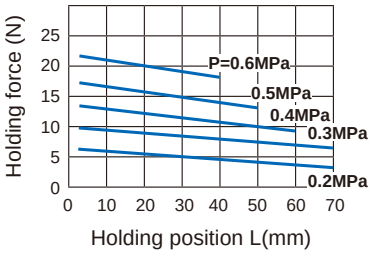


1N=0.102 kgf
1MPa=10.2 kgf/cm^2

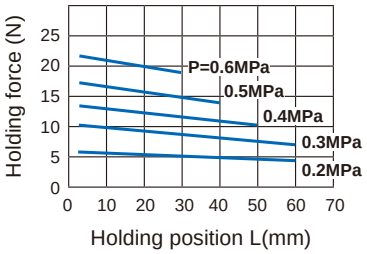


L: Holder position (mm)

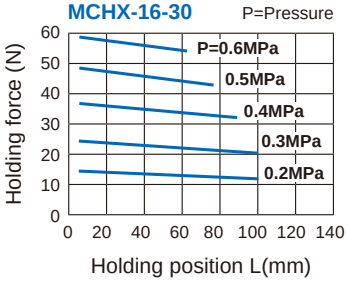
MCHX-10-20 P=Pressure



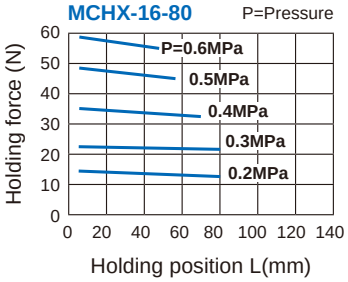
MCHX-10-40
MCHX-10-60 P=Pressure



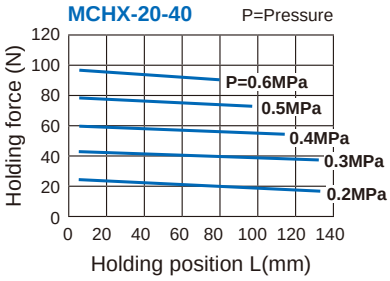
MCHX-16-30 P=Pressure



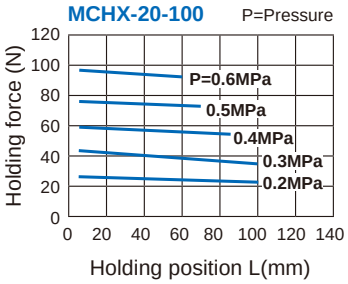
MCHX-16-60
MCHX-16-80 P=Pressure



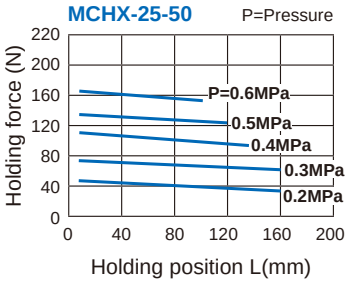
MCHX-20-40 P=Pressure



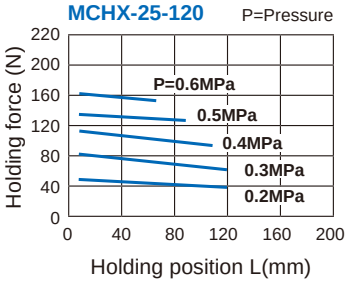
MCHX-20-80
MCHX-20-100 P=Pressure



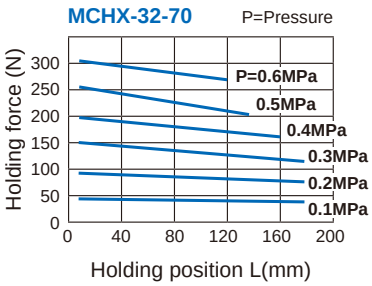
MCHX-25-50 P=Pressure



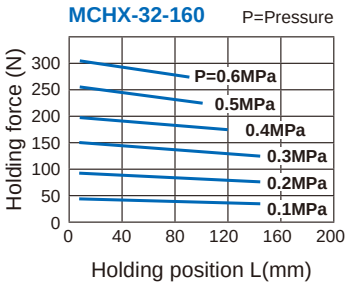
MCHX-25-100
MCHX-25-120 P=Pressure

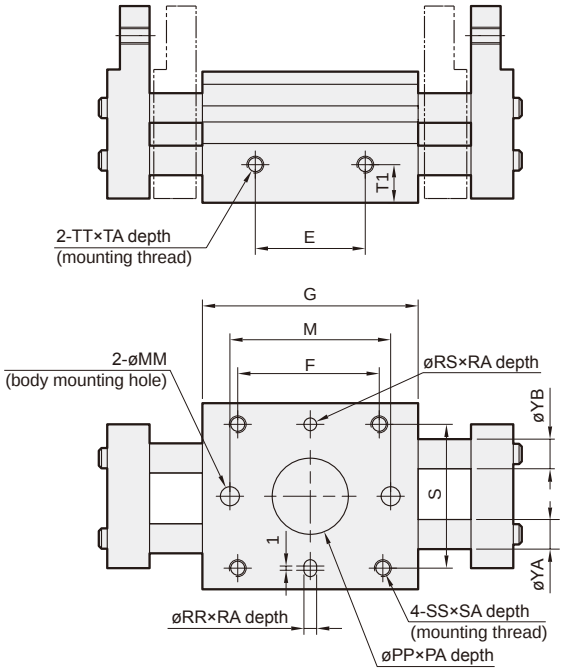


MCHX-32-70 P=Pressure

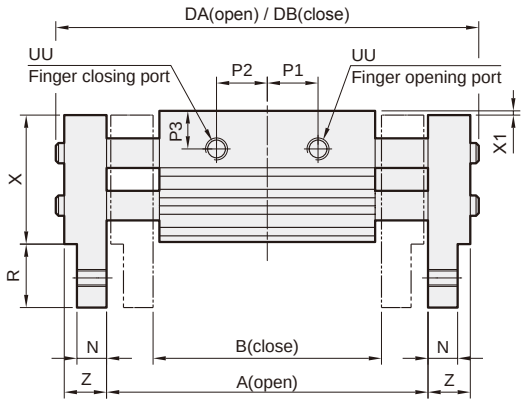


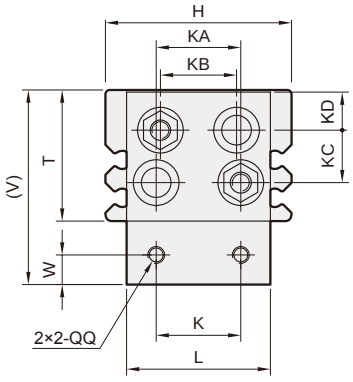
MCHX-32-120
MCHX-32-160 P=Pressure





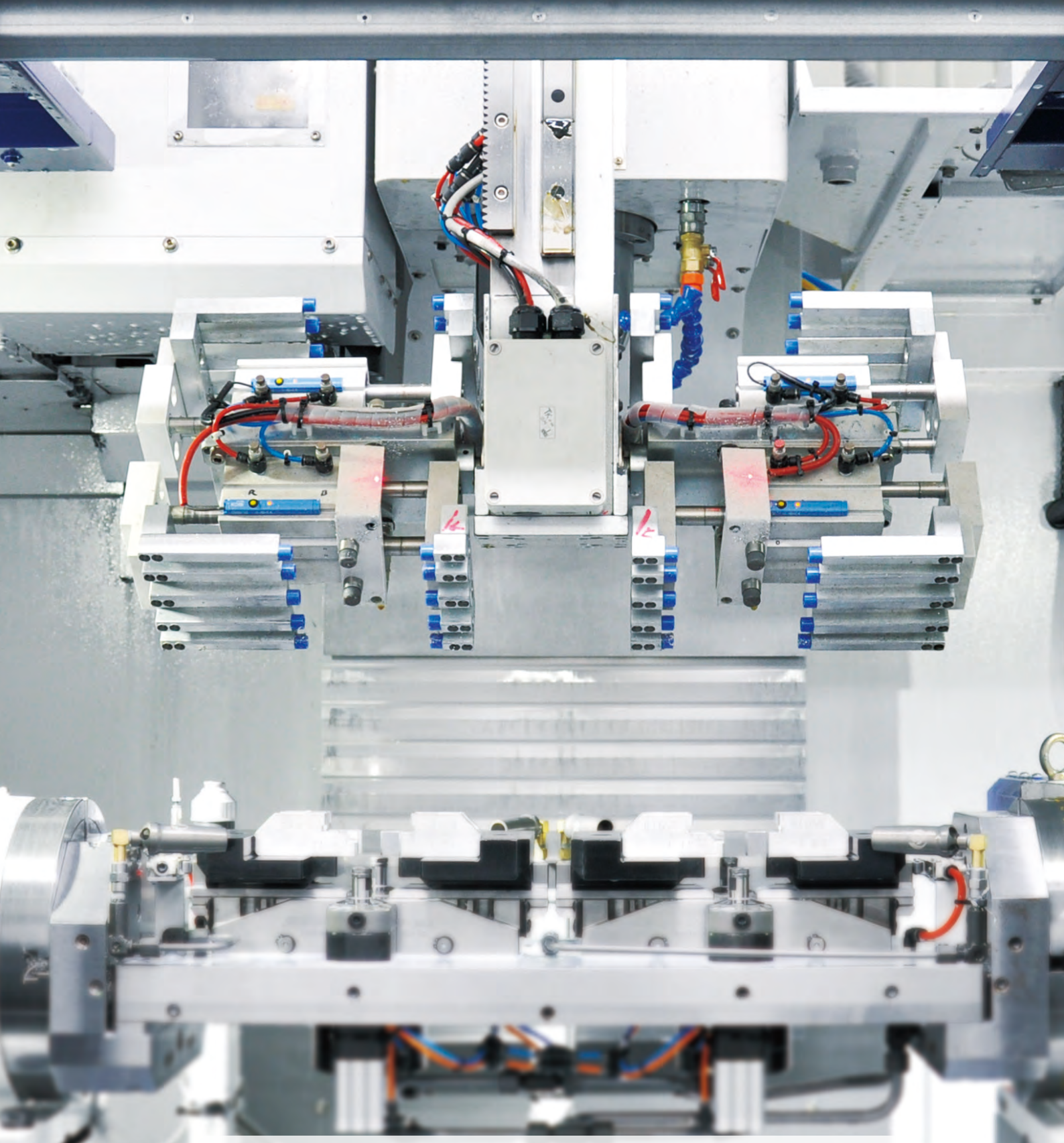
Code / Model	Stroke	A	B	DA	DB	E	F	G	M	P1	P2
MCHX-10	20	76	56	100	80	26	36	51	38	11.5	11.5
	40	118	78	142	108	42	52	67	54	19.5	19.5
	60	156	96	180	146	60	70	85	72	28.5	28.5
MCHX-16	30	98	68	128	98	28	45	60	40	13	13
	60	170	110	200	152	58	75	90	70	25	25
	80	210	130	240	192	78	95	110	90	35	35
MCHX-20	40	122	82	160	120	38	58	71	54	16	16
	80	222	142	260	194	80	100	113	96	34	34
	100	262	162	300	234	100	120	133	116	44	44
MCHX-25	50	150	100	196	146	48	70	88	66	19	19
	100	282	182	328	244	102	124	142	120	43	43
	120	320	200	366	282	120	142	160	138	52	52
MCHX-32	70	220	150	272	202	60	86	110	–	28	28
	120	318	198	370	282	108	134	158	–	52	52
	160	402	242	454	366	152	178	202	–	74	74





Code / Model	H	K	KA	KB	KC	KD	L	N	MM	PA	PP	P3	QQ	R	RA	RR	RS	S	SA	SS
MCHX-10	44	20	20	18.2	12.5	8	34	7	4.5	1.5	18	9	M4×0.7	15	3	3	3	34	8	M4×0.7
MCHX-16	55	25	25	22.6	16.5	9	43	9	5.5	1.5	23	10	M5×0.8	19	3	3	3	42	10	M5×0.8
MCHX-20	65	30	30	28.2	20	10	54	12.5	6.6	1.5	24	11	M6×1.0	24	4	4	4	52	12	M6×1.0
MCHX-25	76	40	38	33.2	23.5	11.5	64	14	9	1.5	32	16	M8×1.25	29	4.5	4	4	62	16	M8×1.25
MCHX-32	82	50	40	32.2	30	14.5	70	15	-	2.5	35	16	M10×1.5	32	8	6	6	64	16	M8×1.25

Code / Model	T	T1	TA	TT	UU	V	W	X	X1	YA	YB	Z
MCHX-10	31	9	5	M4×0.7	M5×0.8	46	7	30.5	0.5	6	6	10
MCHX-16	39	10	7	M5×0.8	M5×0.8	58	8	38.5	0.5	8	8	13
MCHX-20	46	11	7	M6×1.0	M5×0.8	70	10	45	1	10	10	17
MCHX-25	52	12.5	7	M8×1.25	M5×0.8	81	12	51	1	12	12	21
MCHX-32	68	22	11	M8×1.25	Rc1/8	100	15	67	1	14	16	24



Connect with

MACHINE TOOL

Connect gripper with machine tool to manufacture.

Connect with

AUTOMATIC ASSEMBLY MACHINE

Connect gripper with cylinder to achieve regular workpiece gripping.

Features

- With the same tube I.D., the griping stroke is longer compare with other grippers.
- The plain bearing parts are hardened for longer effective life time.
- Three mounting directions are available.
- Magnetic as standard.

Specification

Model		MCHH		
Acting type		Double acting		
Tube I.D. (mm)		20	25	40
Stroke		16	26	41
Medium		Air		
Operating pressure range		0.3~0.7 MPa		
Ambient temperature		–10~+60°C (No freezing)		
Lubrication (*1)		Not required		
Repeatability		± 0.03 mm		
Sensor switch (*2)	2 wire	**RDFE**(**V**): Non-contact		
	3 wire	**RNFE**(**V**): NPN, **RPFE**(**V**): PNP		
Weight (kg)		0.27	0.59	1.46

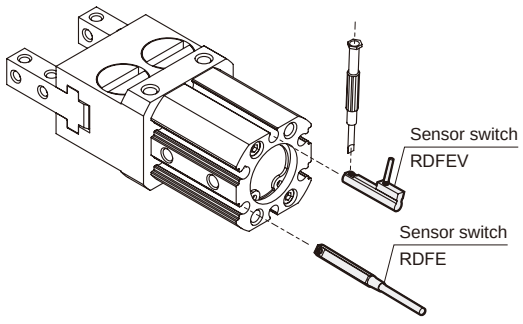
*1. Sliding area of jaws need scheduled relubrication.
*2. R*FE(V) specification, please refer to page 86.

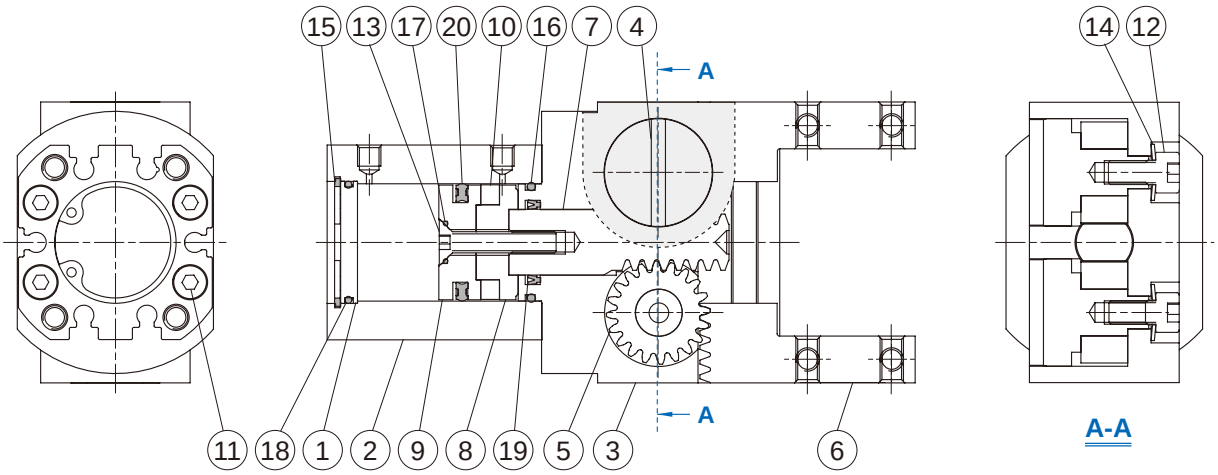
Order example

MCHH — 25 M

- MODEL: MCHH
- TUBE I.D.: 20, 25, 40
- **M**: Magnet
  * Magnetic as standard.

Installation of sensor switch





Material

No.	Part name	Material	Q'y	Repair kits (inclusion)
1	End cover	Aluminum alloy	1	
2	Body	Aluminum alloy	1	
3	Finger rail	Aluminum alloy	1	
4	Pinion holder	Carbon steel	2	
5	Pinion	Alloy steel	2	
6	Finger	Alloy steel	2	
7	Piston rod	Alloy steel	1	
8	Magnet holder	Aluminum alloy	1	
9	Piston	Aluminum alloy	1	
10	Magnet ring	Magnet material	1	
11	Hexgon bolt (*)	Steel	2 or 4	
12	Hexgon bolt	Steel	2	
13	Countersink bolt	Steel	1	
14	Washer	Spring steel	2	
15	Snap ring	Spring steel	1	
16	O-ring	NBR	1	●
17	O-ring	NBR	1	●
18	O-ring	NBR	1	●
19	Rod packing	NBR	1	●
20	Piston packing	NBR	1	●

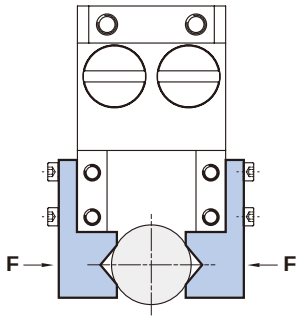
* ø20 Q'y: 2 pcs, ø25 & ø40 Q'y: 4 pcs

Order example of repair kits

Tube I.D.	Repair kits
ø20	**PS-MCHH-20**
ø25	**PS-MCHH-25**
ø40	**PS-MCHH-40**

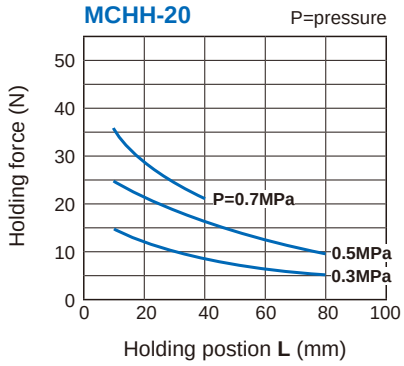
Effective gripping force

Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

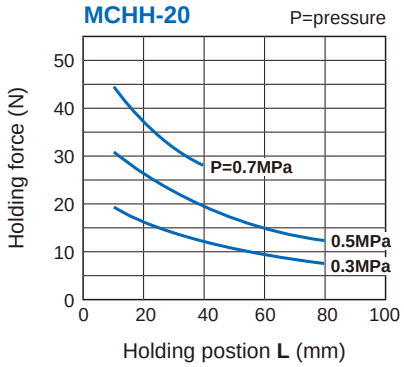


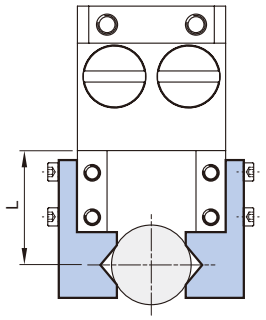
1N=0.102 kgf
1MPa=10.2 kgf/cm^2

External grip

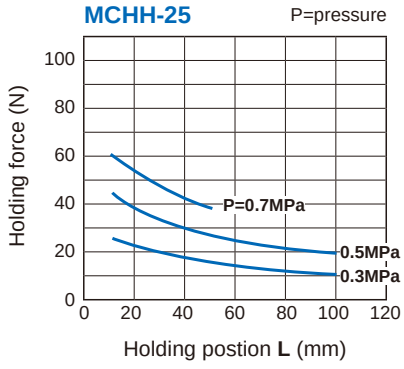


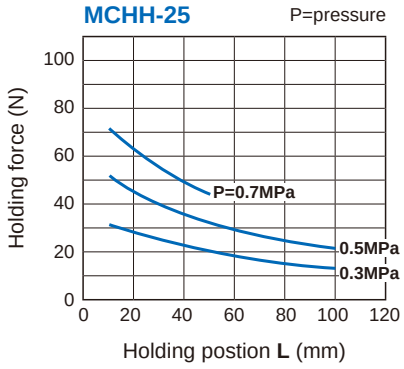
Internal grip

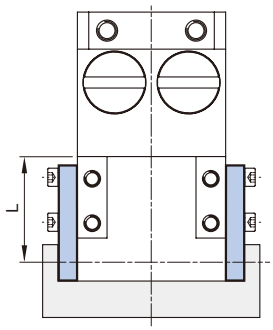




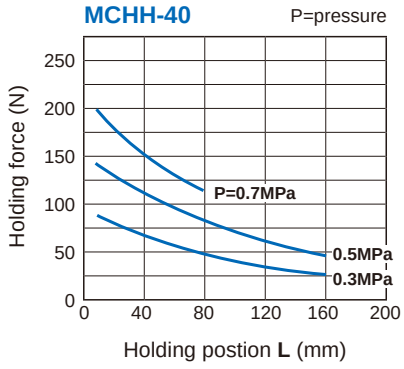
External grip

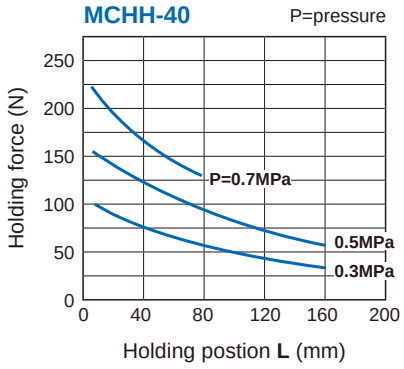




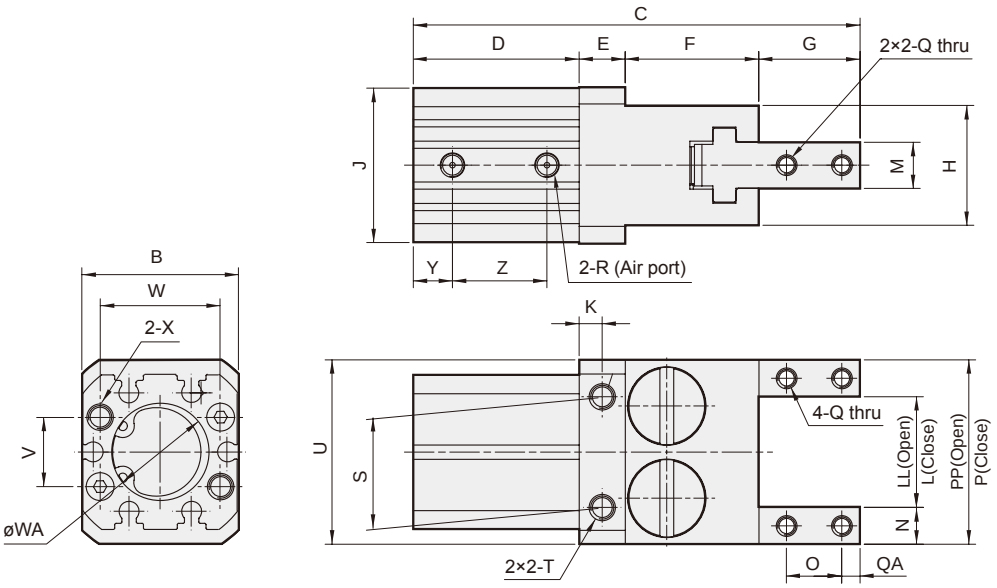


Internal grip

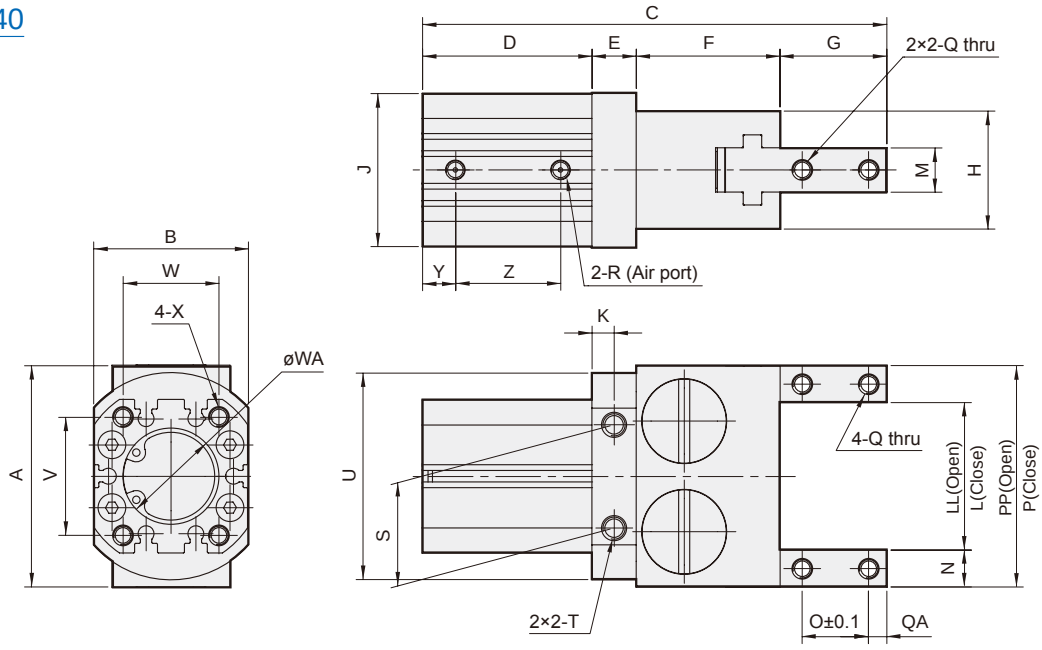




ø20



ø25, ø40



Code / Model	A	B	C	D	E	F	G	H	J	K	L	LL	M	N	O	P	PP	Q	QA	R	S	T	U
MCHH-20	–	34	97	36	10	29	22	26	33.5	5	8	24	$10^{-0.01}_{-0.06}$	8	12	24	40	M4×0.7	4	M5×0.8	24	M5×0.8×12 dp	40
MCHH-25	60	42	126	46	12	39	29	32	41.5	6	14	40	$12^{-0.01}_{-0.06}$	10	18	34	60	M5×0.8	5	M5×0.8	28	M6×1.0×14 dp	ø56
MCHH-40	92	60	167	57	15	58	37	38	58	8	26	68	$14^{-0.01}_{-0.06}$	12	20	50	92	M6×1.0	7	Rc1/8	42	M8×1.25×14 dp	ø82

Code / Model	V	W	WA	X	Y	Z
MCHH-20	15	26	$ø22^{+0.05}_{0}$×1.5 dp	M5×0.8×10 dp	8.5	20.5
MCHH-25	32	26	$ø26^{+0.05}_{0}$×1.5 dp	M5×0.8×10 dp	9	28.5
MCHH-40	44	34	$ø42^{+0.05}_{0}$×2 dp	M6×1.0×12 dp	11	28.5

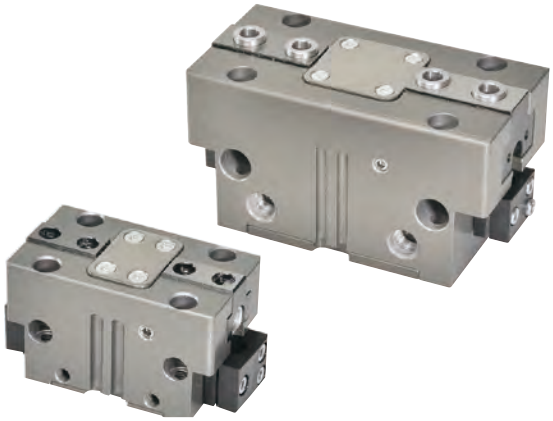
Connect with

ELECTRIC ACTUATOR

Connect gripper with electric actuator to achieve workpiece displacement.

MCHS series

PARALLEL GRIPPER (2-Finger)



Features

- Compact design to ensure minimum interference while operating; robust T rail design, ensure accurate gripping.
- Can reach maximum torque suitable for long jaws design.
- Oval piston-driven design ensure maximum gripping force.
- Hose-free direct connection: Air supply channel can connect directly without piping or through tread to assure the flexibility of supplying compressed air on any kind of automation system.

Order example

MCHS — 50

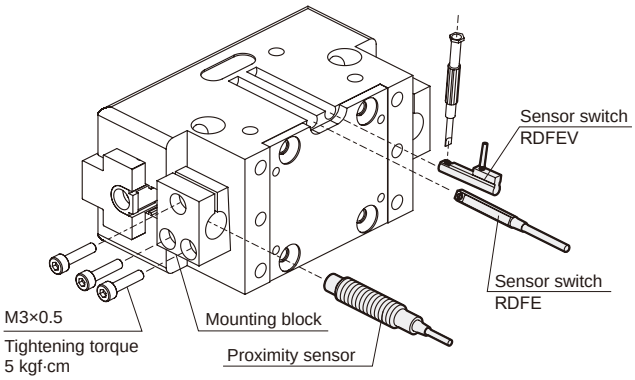
- MODEL
- BODY SPECIFICATION
  50, 66, 80, 100, 125, 160, 200, 300

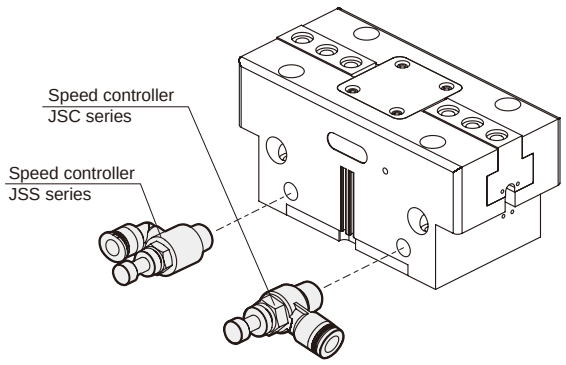
Specification

Model		MCHS							
Acting type		Double acting							
Body specification		50	66	80	100	125	160	200	300
Stroke per-jaw(mm)		4	6	8	10	12	16	20	30
Closing force(N)		170	300	550	740	1290	1860	3175	6675
Opening force(N)		185	325	590	795	1370	1960	3330	6830
Close/Open time(s)		0.02	0.03	0.04	0.07	0.1	0.1	0.35	0.4
Medium		Air							
Operating pressure range		0.3~0.8 MPa							
Compressed air consumption(cm^3)		4.1	10.1	23.6	39.3	85	85	330	1000
Ambient temperature		+5°C~ +80°C							
Lubrication		Not required							
Sensor switch (*)	2 wire	**RDFE(V)**: Non-contact							
	3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP							
Accessories		Mounting block, Centering sleeve							
Weight (kg)		0.14	0.27	0.495	0.85	1.6	3.0	5.7	14.2
Recom. workpiece weight (kg)		0.85	1.4	2.6	3.6	6.3	9.2	15	32

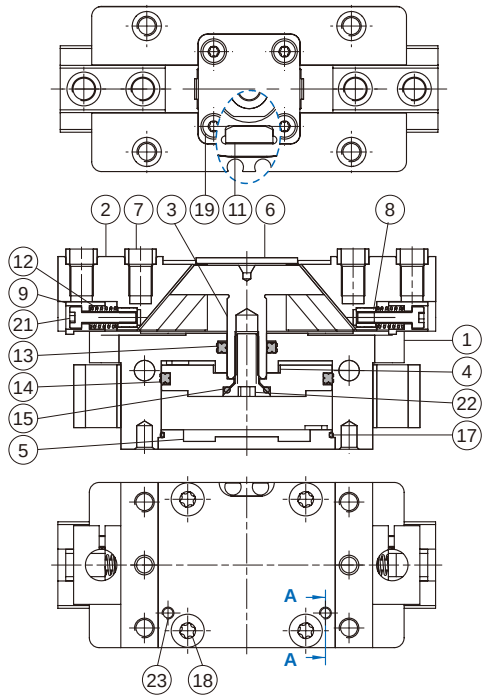
* R*FE(V) specification, please refer to page 86.

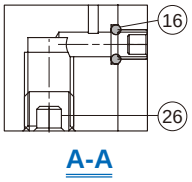
Installation of sensor switch & speed controller





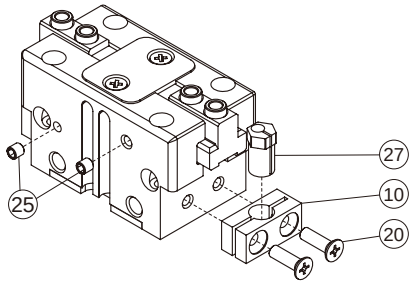
* Each gripper needs at least two speed control valves to control speed.
* Speed controller specification, please refer to Mindman website.



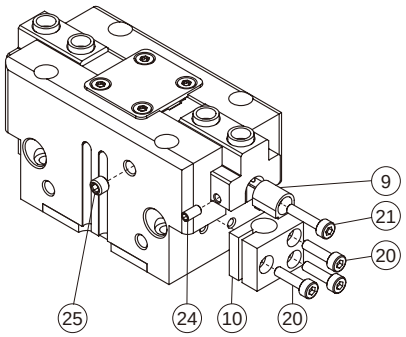


A-A

50



66~160



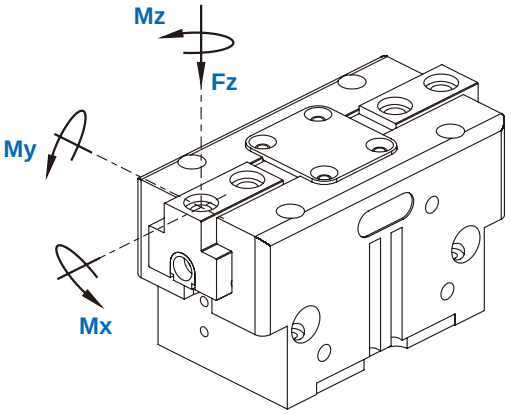
Material

No.	Part name	Material	Body spec & Q'y						Repair kits (inclusion)
			50	66	80	100	125	160	
1	Body	Aluminum alloy	1						
2	Finger	Mid carbon steel	2						
3	Rod	Mid carbon steel	1						
4	Piston	Aluminum alloy	1						
5	End cover	Aluminum alloy	1						
6	Plate cover	Stainless steel	1						
7	Centering sleeve	Stainless steel	4						
8	Thread insert	Brass	–		2				
9	Sensor adj block	Aluminum alloy	–	2					
10	Magnet holder	PBT+30%GF	2						
11	Magnet	Magnet material	1						
12	Spring	SWP	–	2					
13	Rod packing	NBR	1						●
14	Piston packing	NBR	1						●
15	O-ring	NBR	1						●
16	O-ring	NBR	3		4		2		●
17	O-ring	NBR	1						●
18	Screw	Carbon steel	4						
19	Screw	Carbon steel	2	4					
20	Bolt	Stainless steel	4	6					
21	Hex bolt	Stainless steel	–	2					
22	Hex bolt	Stainless steel	1						
23	Hex screw	Stainless steel	2						
24	Hex screw	Carbon steel	4						
25	Hex screw	Stainless steel	2						
26	Hex screw	Stainless steel	2						
27	Adjust socket	Stainless steel	2	–					

Order example of repair kits

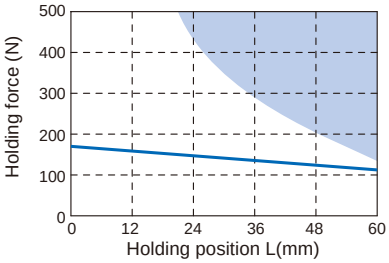
Model	Repair kits
MCHS-50	**PS-MCHS-50**
MCHS-66	**PS-MCHS-66**
MCHS-80	**PS-MCHS-80**
MCHS-100	**PS-MCHS-100**
MCHS-125	**PS-MCHS-125**
MCHS-160	**PS-MCHS-160**

Holding force

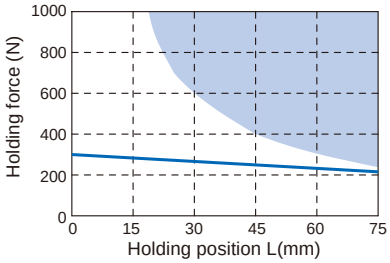


Code / Model	Mx max. (Nm)	My max. (Nm)	Mz max. (Nm)	Fz max. (N)
MCHS-50	15	15	8	700
MCHS-66	50	45	35	1200
MCHS-80	80	60	50	1800
MCHS-100	100	90	75	2500
MCHS-125	120	120	100	3200
MCHS-160	160	180	140	5000
MCHS-200	180	220	170	7000
MCHS-300	275	300	200	9000

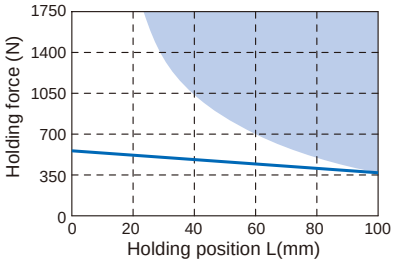
MCHS-50



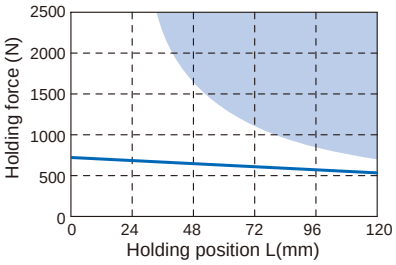
MCHS-66



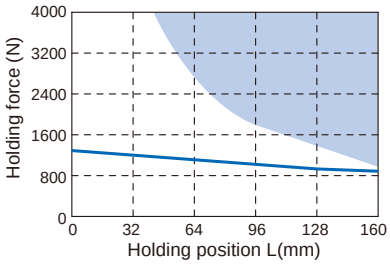
MCHS-80



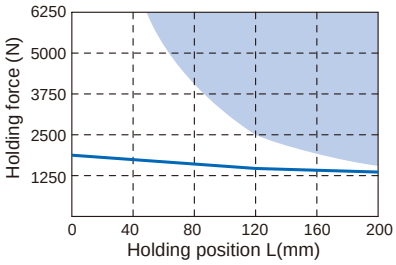
MCHS-100



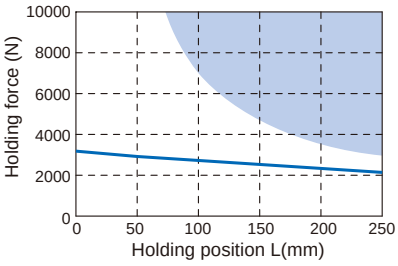
MCHS-125



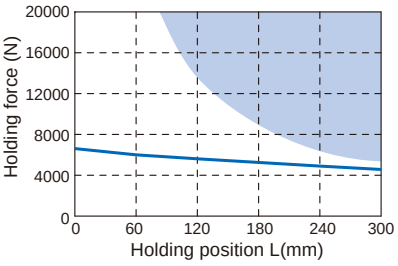
MCHS-160



MCHS-200

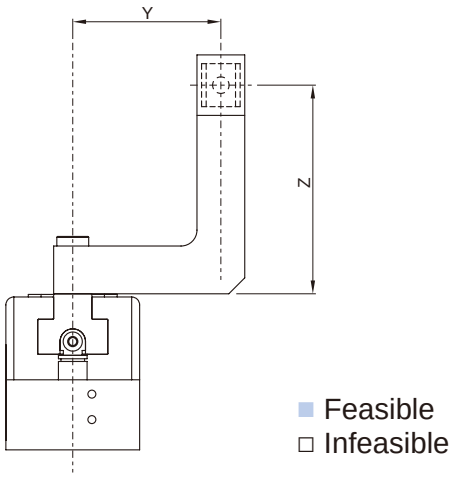


MCHS-300

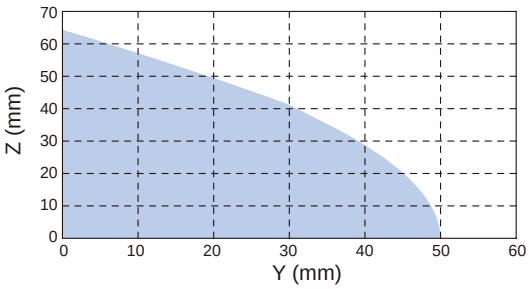


* Blue area: Less durable performance can be expected.

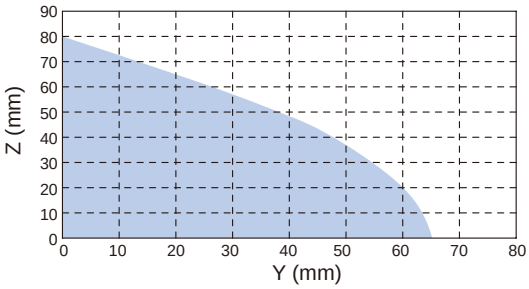
Max. feasible centrifugal degree



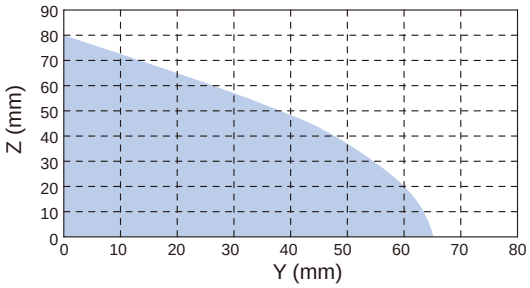
MCHS-50



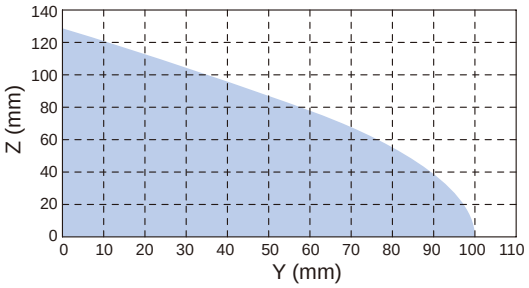
MCHS-66



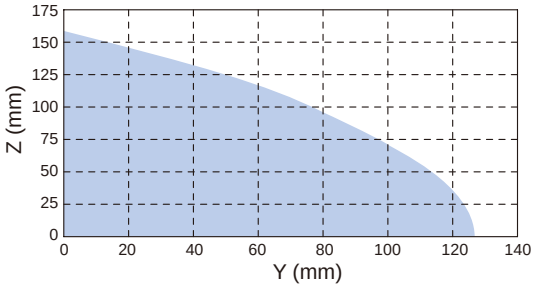
MCHS-80



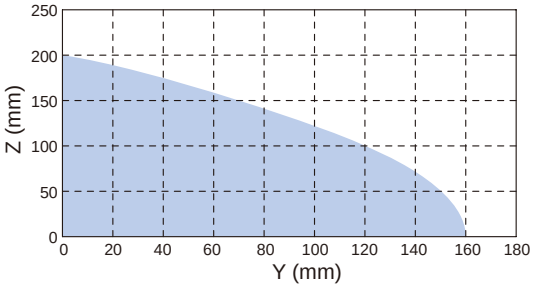
MCHS-100



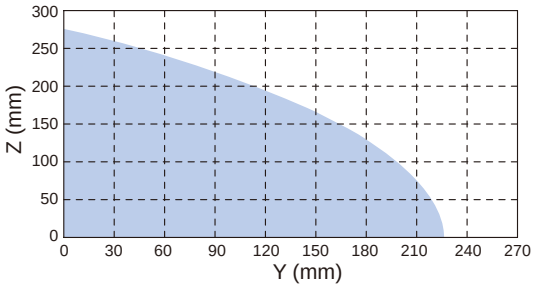
MCHS-125



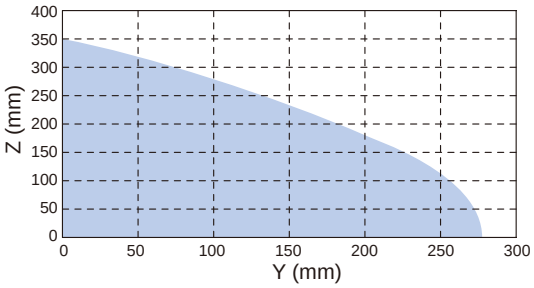
MCHS-160



MCHS-200

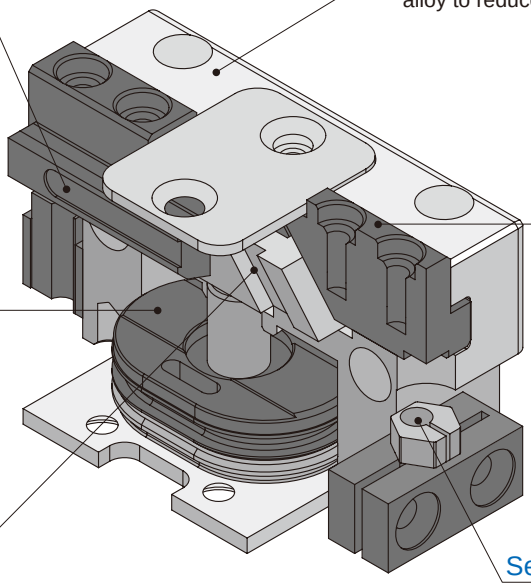


MCHS-300



Internal structure & Movement description

Compressed air will push or press the oval piston.
By tilting the working surface, the wedge hook will transfer the movement to side movement, and initiate the action of the two base jaws simultaneously.



Material
Anodized high rigid aluminum alloy to reduce weight.

Rail
Bearing rails load the base jaw, which ensure the minimal vibration of long jaw.

Base jaw
Jaws connected to work piece.

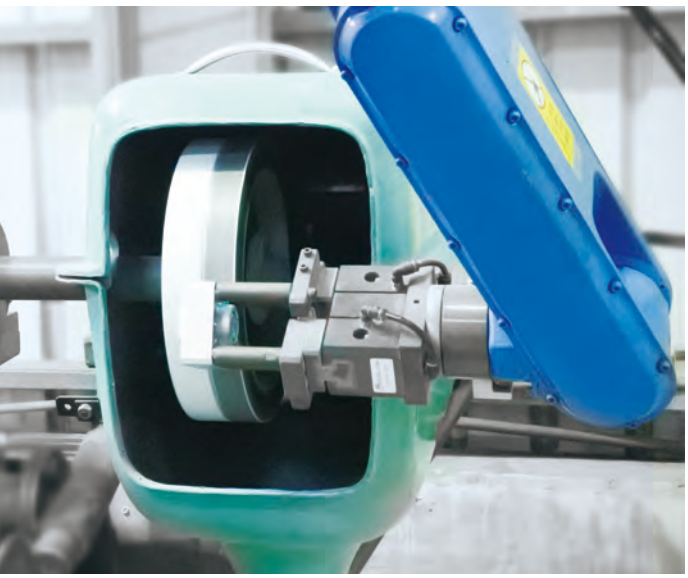
Large oval piston
Generate larger structural strength.

Wedge hook
High power transmission center jaws.

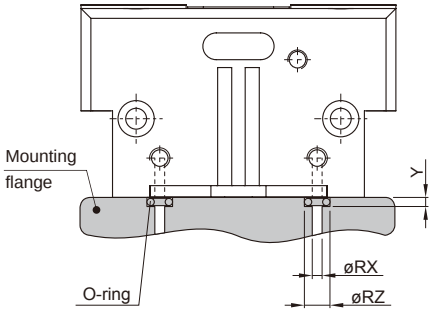
Sensor system
Sensor switch or proximity sensor are available.

Application examples

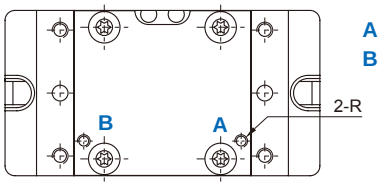
Connect gripper with robot to achieve burr removal.



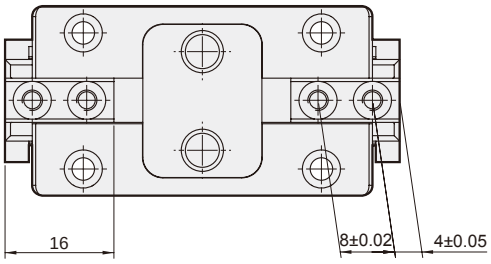
Hose-free direct connection

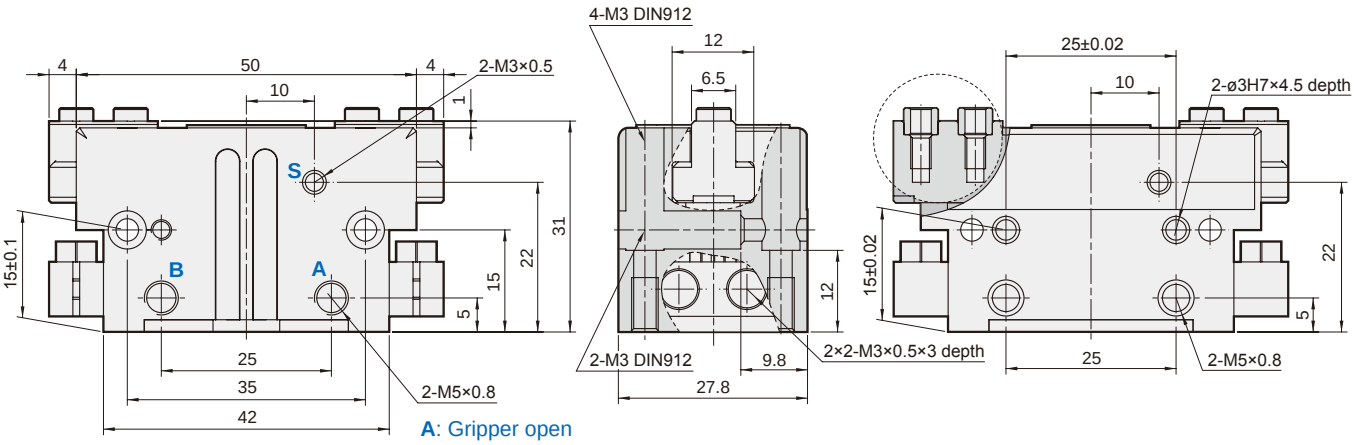


Code / Model	R	RX	RZ	Y
MCHS-50	M2	2	4	0.7
MCHS-66	M3	3	5	0.7
MCHS-80	M3	3	5	1.1
MCHS-100	M5	5	8	1.1
MCHS-125	M5	5	8	1.1
MCHS-160	M5	5	8	1.1
MCHS-200	M5	5	8	1.1
MCHS-300	M5	5	8	1.1

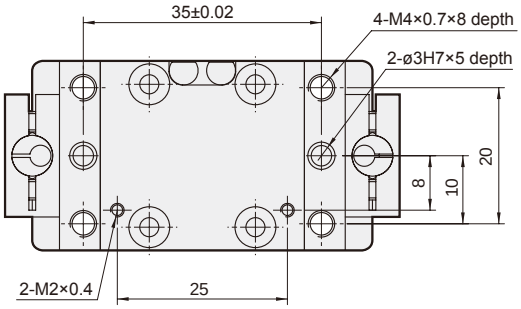


A : Gripper open
B : Gripper close

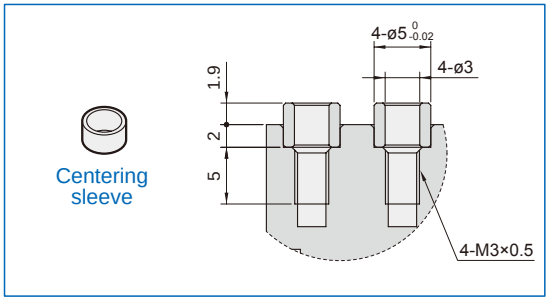




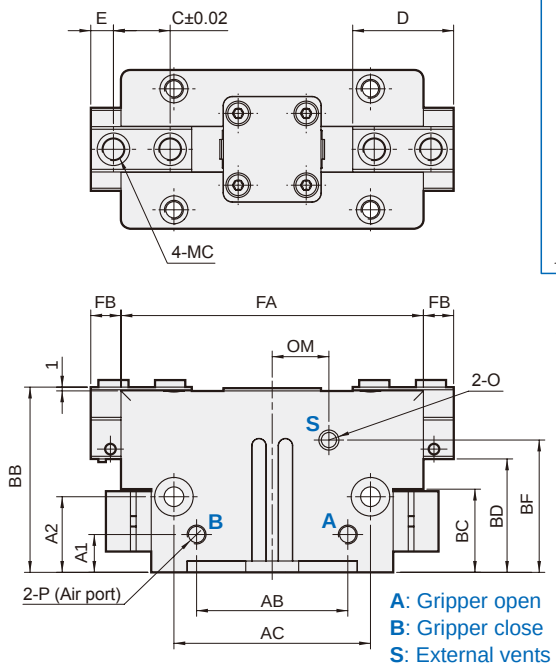
A: Gripper open
B: Gripper close
S: External vents



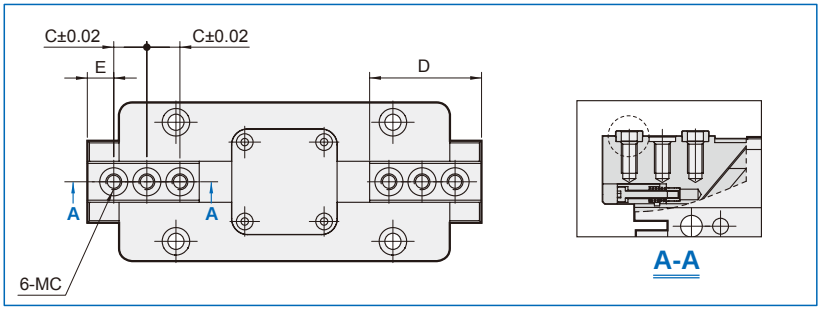
Centering sleeve

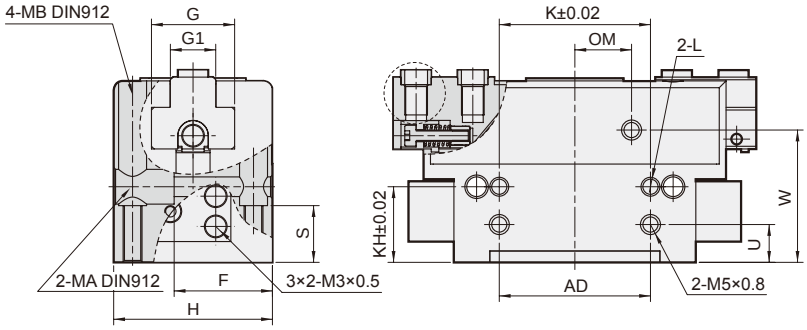


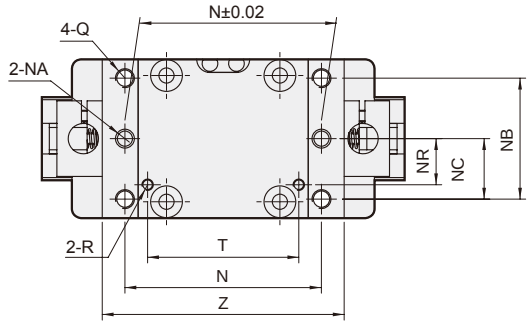
66~100



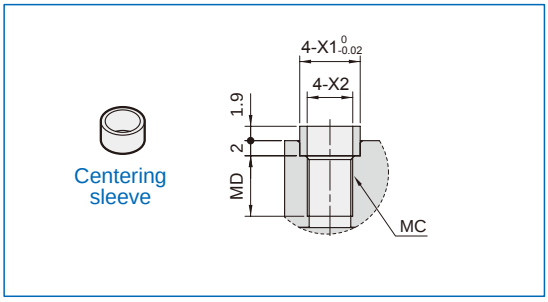
125~160





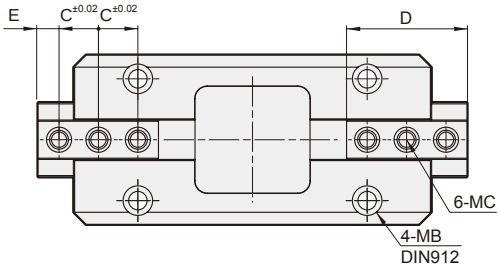


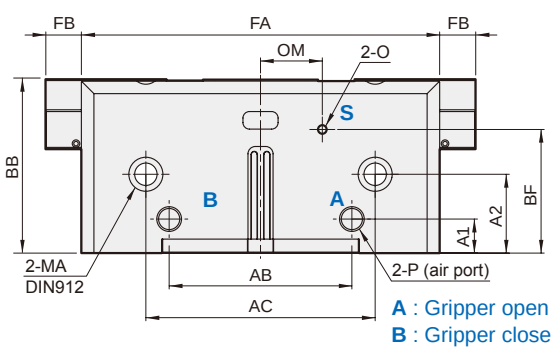
Centering sleeve



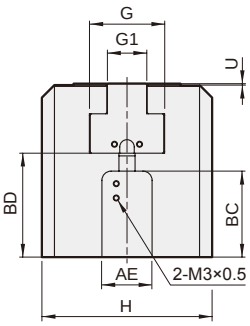
Code / Model	A1	A2	AB	AC	AD	BB	BC	BD	BF	C	D	E	F	FA	FB	G	G1	H	K	KH	L	MA	MB
MCHS-66	5	18	28	42	28	39	18.5	23	27.5	12	22	5	23	64	6	17	10	36	20	18	ø4H7×4dp	M4	M4
MCHS-80	10	20	40	52	40	49	22	30	35	15	26.7	6	26	80	8	22	12	42	40	20	ø4H7×6dp	M5	M4
MCHS-100	12	25	48	66	54	55	28	33	38	18	34.2	10	22	100	10	26	14	50	50	25	ø5H7×7dp	M6	M5
MCHS-125	13	30	62	82	65	64	32	38.5	45	12.5	42.3	10	26	125	12	31	15.5	60	60	30	ø6H7×8dp	M8	M6
MCHS-160	15.5	28	78	100	82	78	39	46	53	18	54.8	10	47	160	16	39	20	72	76	28	ø6H7×10dp	M8	M6

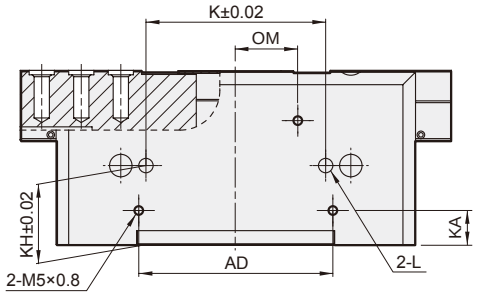
Code / Model	MC	MD	N	NA	NB	NC	NR	O	OM	P	Q	R	S	T	U	W	X1	X2	Z
MCHS-66	M4×0.7	6	42	ø4H7×6 dp	27	13.5	11	M5×0.8	12	M5×0.8	M5×0.8×14 dp	M3×0.5	14	28	5	27.5	ø6	ø4	52
MCHS-80	M6×1.0	8	52	ø4H7×6 dp	32	16	12.2	M5×0.8	15	M5×0.8	M5×0.8×15 dp	M3×0.5	15	40	10	35	ø8	ø6	64
MCHS-100	M6×1.0	10	66	ø5H7×8 dp	38	19	16	M5×0.8	16	G1/8	M6×1.0×10 dp	M5×0.8	32.5	48	12	38	ø10	ø6	80
MCHS-125	M6×1.0	12	82	ø6H7×8 dp	45	22.5	18	M5×0.8	20	G1/8	M8×1.25×10 dp	M5×0.8	23	46	13	45	ø10	ø6	100
MCHS-160	M8×1.25	12	100	ø6H7×8 dp	56	28	22	M5×0.8	27	G1/8	M8×1.25×12 dp	M5×0.8	40	76	15.5	53	ø12	ø8	125

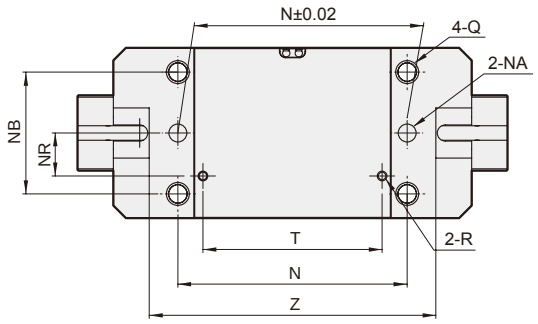




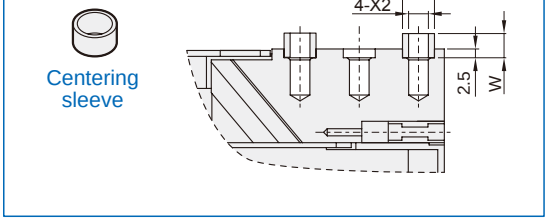
A : Gripper open
B : Gripper close
S : External vents







Centering sleeve



Code / Model	A1	A2	AB	AC	AD	AE	BB	BC	BD	BF	C	D	E	FA	FB	G	G1	H	K	KA	KH	L
MCHS-200	19	44	102	128	108	28	97	48	58	69	22	67.5	12	200	20	42	22	95	100	19	44	ø8H7×8 dp
MCHS-300	19	66	150	180	152	30	130	67	78	92	30	91.0	15	260	30	66	32	139	140	19	66	ø10H7×12 dp

Code / Model	MA	MB	MC	MD	N	NA	NB	NR	O	OM	P	Q	R	T	U	W	X1	X2	Z
MCHS-200	M12	M10	M10×20 dp	20	128	ø10H7×10 dp	68	24	M5	34.5	G1/4	M12×17 dp	M5	100	0.8	4.9	ø14h7	ø11	160
MCHS-300	M12	M10	M12×20 dp	20	180	ø10H7×12 dp	100	24	M5	43	G1/4	M12×16 dp	M5	150	0.8	4.9	ø18h7	ø12.5	220

Connect with

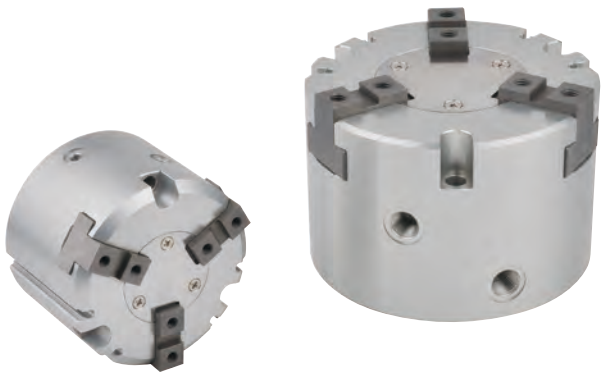
ELECTRIC ACTUATOR

Connect gripper with electric actuator to achieve workpiece displacement.

MCHG2 series

PARALLEL GRIPPER (3-Finger)

mindman



Features

- Through holes in body enable simple mounting.
- Body manufactured from high tensile, anodised aluminum giving good resistance to corrosion.
- Available with sensors.
- Magnetic as standard.

Order example

MCHG2 — 16 M — □

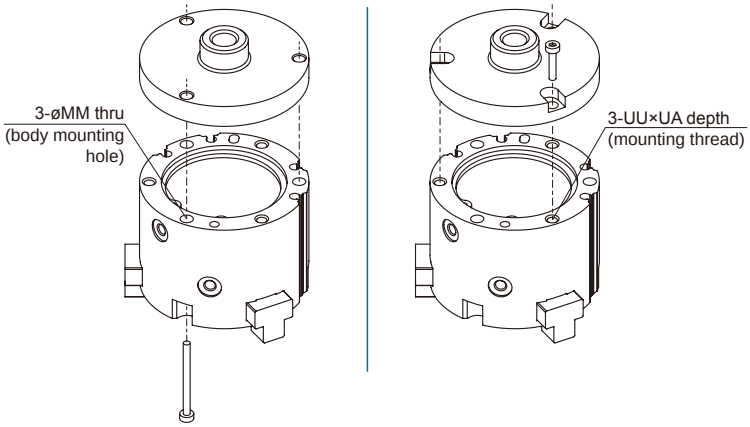
- MCHG2 — MODEL
- 16 — TUBE I.D. **16, 20, 25, 32, 40, 50, 63, 80, 100, 125**
- M — **M**: Magnet * Magnetic as standard.
- □ — PORT THREAD
  - Blank: M thread (only for ø16~ø63)
  - Blank: Rc thread
  - **G**: G thread
  - **NPT**: NPT thread (only for ø80~ø125)

Specification

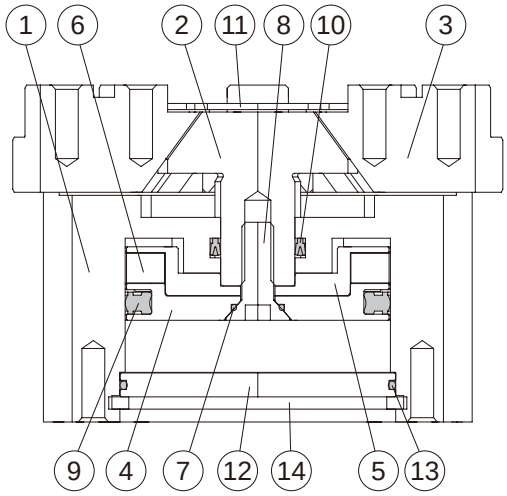
Model		MCHG2									
Acting type		Double acting									
Tube I.D. (mm)		16	20	25	32	40	50	63	80	100	125
Stroke (mm)		4	4	6	8	8	12	16	20	24	32
Port size		M3×0.5	M5×0.8						Rc1/8	Rc1/4	Rc3/8
Medium		Air									
Operating pressure (MPa)		0.2~0.6			0.1~0.6						
Ambient temperature		-10~+60°C (No freezing)									
Repeatability		±0.01 mm									
Max. operating frequency (c.p.m)		120			60				30		
Lubrication		Not required									
Effective gripping force N (lbf) at (0.5 MPa) (*)	External	14(3.1)	25(5.6)	42(9.4)	74(16.6)	118(26.5)	187(42)	335(75)	500(112)	750(169)	1270(285)
	Internal	16(3.6)	28(6.3)	47(10.6)	82(18.4)	130(29)	204(46)	359(81)	525(118)	780(175)	1320(297)
Sensor switch	2 wire	**RDFE(V)**: Non-contact (Please refer to page 86)									
	3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP									
Weight (g)		80	110	150	240	400	540	1020	1880	3300	6200

* Open and closed diameter values apply for external gripping of work pieces.

Installation



Model	MM	UU×UA	Bolt
MCHG2-16	3.4	M3×0.5×4.5	M3×0.5
MCHG2-20	3.4	M3×0.5×6	M3×0.5
MCHG2-25	4.5	M4×0.7×6	M4×0.7
MCHG2-32	4.5	M4×0.7×6	M4×0.7
MCHG2-40	5.5	M5×0.8×7.5	M5×0.8
MCHG2-50	5.5	M5×0.8×10	M5×0.8
MCHG2-63	6.6	M6×1.0×9	M6×1.0
MCHG2-80	6.6	M6×1.0×12	M6×1.0
MCHG2-100	9	M8×1.25×16	M8×1.25
MCHG2-125	11	M10×1.5×20	M10×1.5



Material

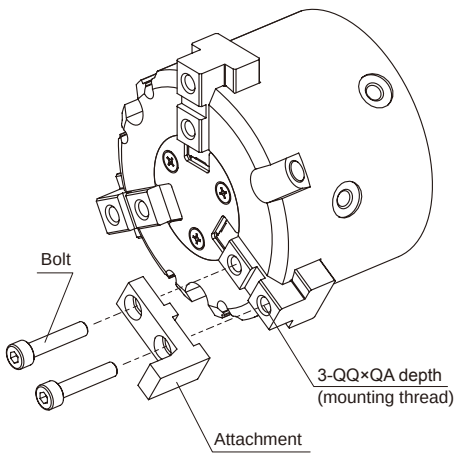
No.	Part name	Material
1	Body	Aluminum alloy
2	Lever	Carbon steel
3	Slider	Carbon steel
4	Piston	Aluminum alloy
5	Piston-R	Aluminum alloy
6	Magnet ring	Magnet material
7	O-ring	NBR

No.	Part name	Material
8	Piston bolt	Carbon steel
9	Piston packing	NBR
10	Rod packing	NBR
11	Table	Stainless steel
12	End plate	Aluminum alloy
13	O-ring	NBR
14	Snap ring	Carbon steel

Mounting precautions

The tightening torque of slider mounting bolt, please refer to the table below.

Model	QQ×QA	Bolt	Max. tightening torque (N.m)
MCHG2-16	M3×0.5×5	M3×0.5	0.59
MCHG2-20	M3×0.5×6	M3×0.5	0.59
MCHG2-25	M3×0.5×6	M3×0.5	0.59
MCHG2-32	M4×0.7×8	M4×0.7	1.4
MCHG2-40	M4×0.7×8	M4×0.7	1.4
MCHG2-50	M5×0.8×8	M5×0.8	2.8
MCHG2-63	M5×0.8×8	M5×0.8	2.8
MCHG2-80	M6×1.0×12	M6×1.0	4.8
MCHG2-100	M8×1.25×16	M8×1.25	12
MCHG2-125	M10×1.5×20	M10×1.5	24

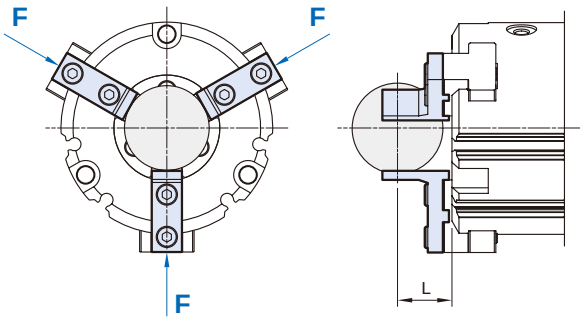


Effective gripping force

* Finger selection please refer to page 6.

Indication of effective gripping force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when three fingers and attachments are in full contact with the workpiece as shown in the figure below.

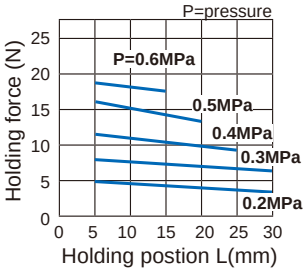
1N=0.102 kgf
1MPa=10.2 kgf/cm^2



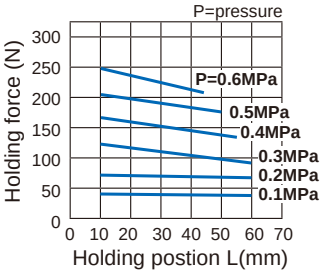
External grip

External gripping force

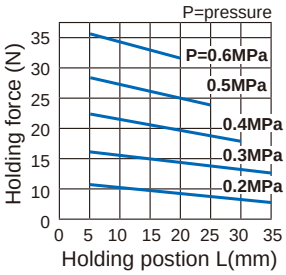
MCHG2-16



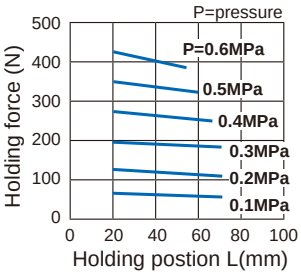
MCHG2-50



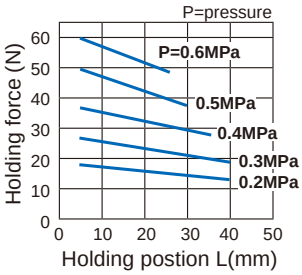
MCHG2-20



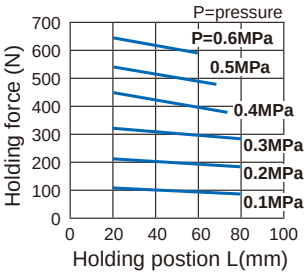
MCHG2-63



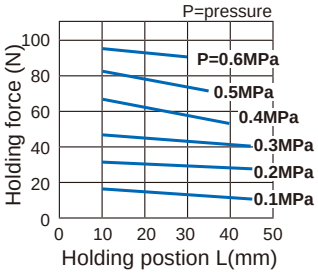
MCHG2-25



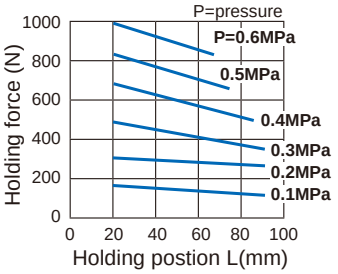
MCHG2-80



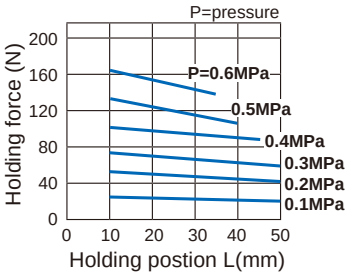
MCHG2-32



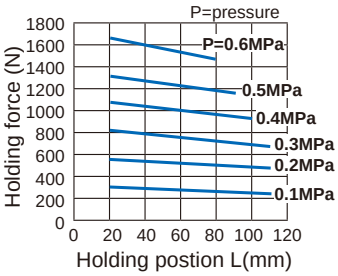
MCHG2-100



MCHG2-40



MCHG2-125

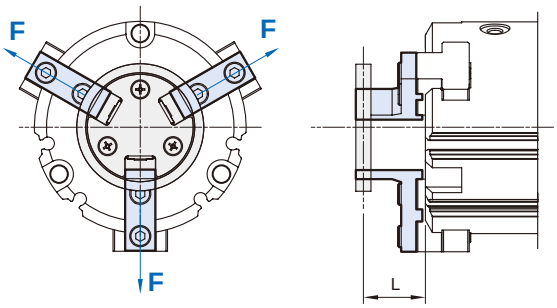


Effective gripping force

* Finger selection please refer to page 6.

Indication of effective gripping force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when three fingers and attachments are in full contact with the workpiece as shown in the figure below.

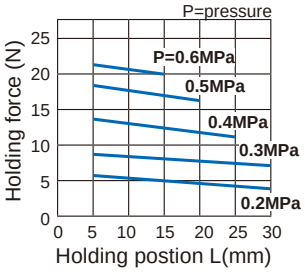
1N=0.102 kgf
1MPa=10.2 kgf/cm^2



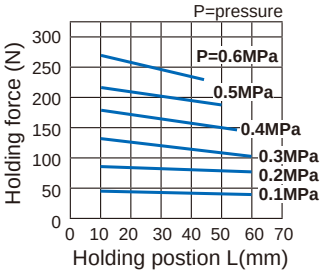
Internal grip

Internal gripping force

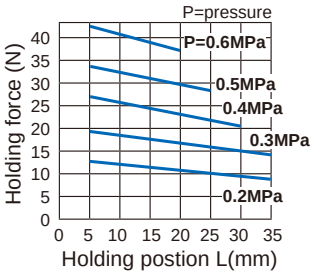
MCHG2-16



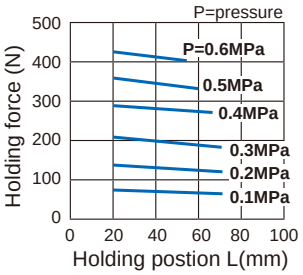
MCHG2-50



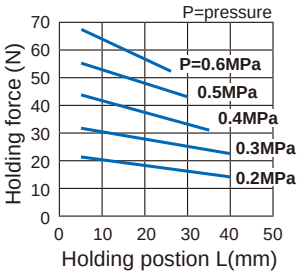
MCHG2-20



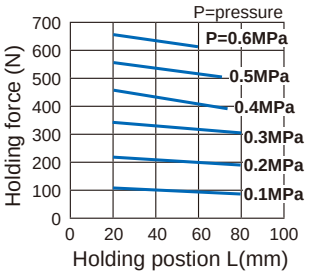
MCHG2-63



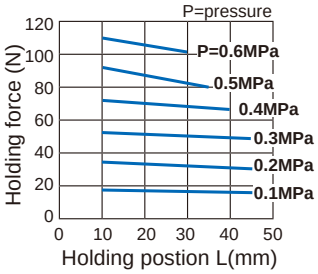
MCHG2-25



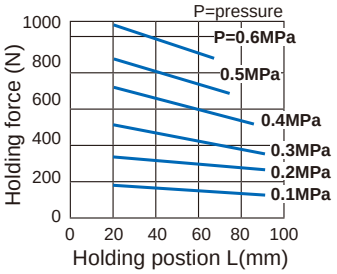
MCHG2-80



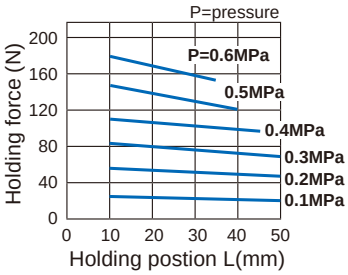
MCHG2-32



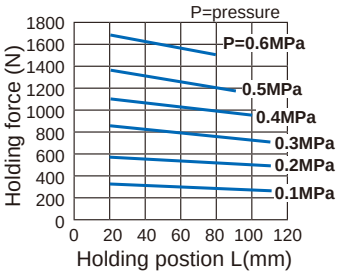
MCHG2-100



MCHG2-40

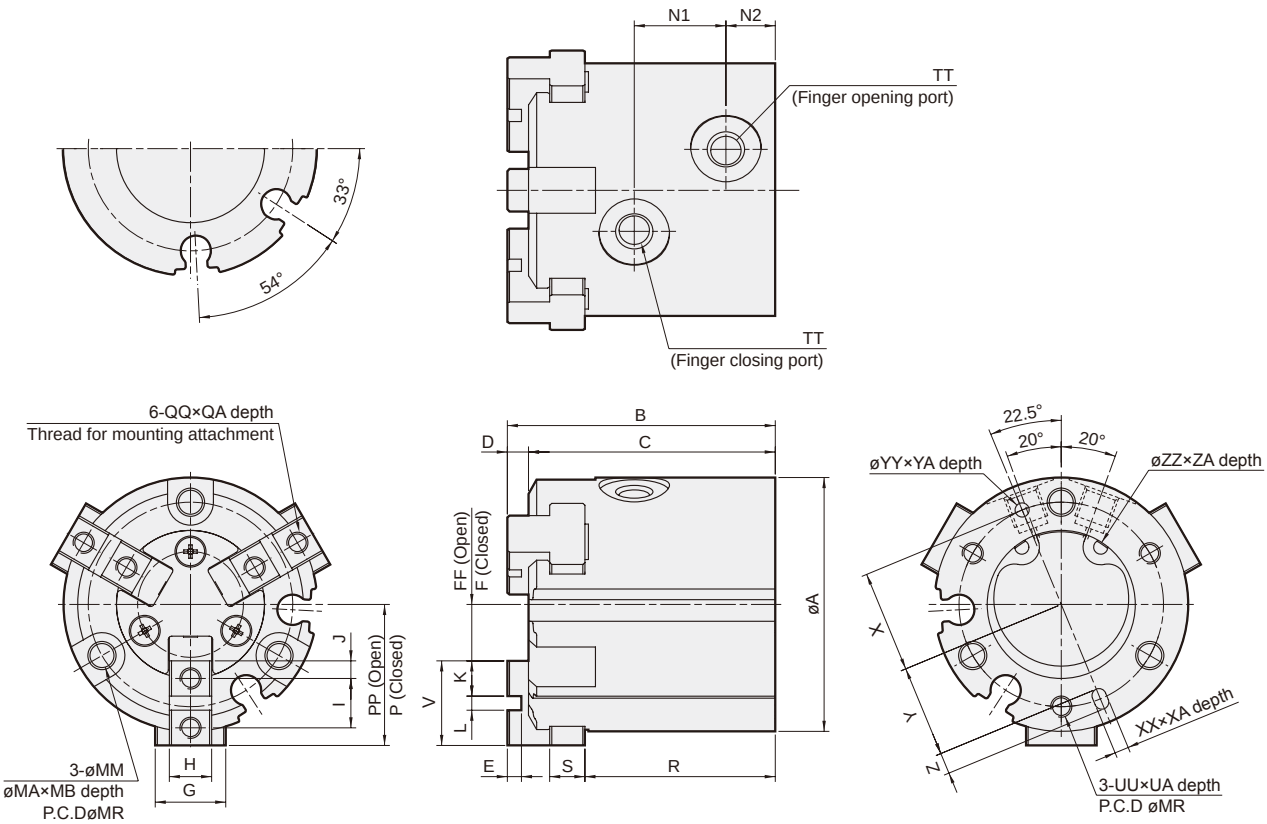


MCHG2-125



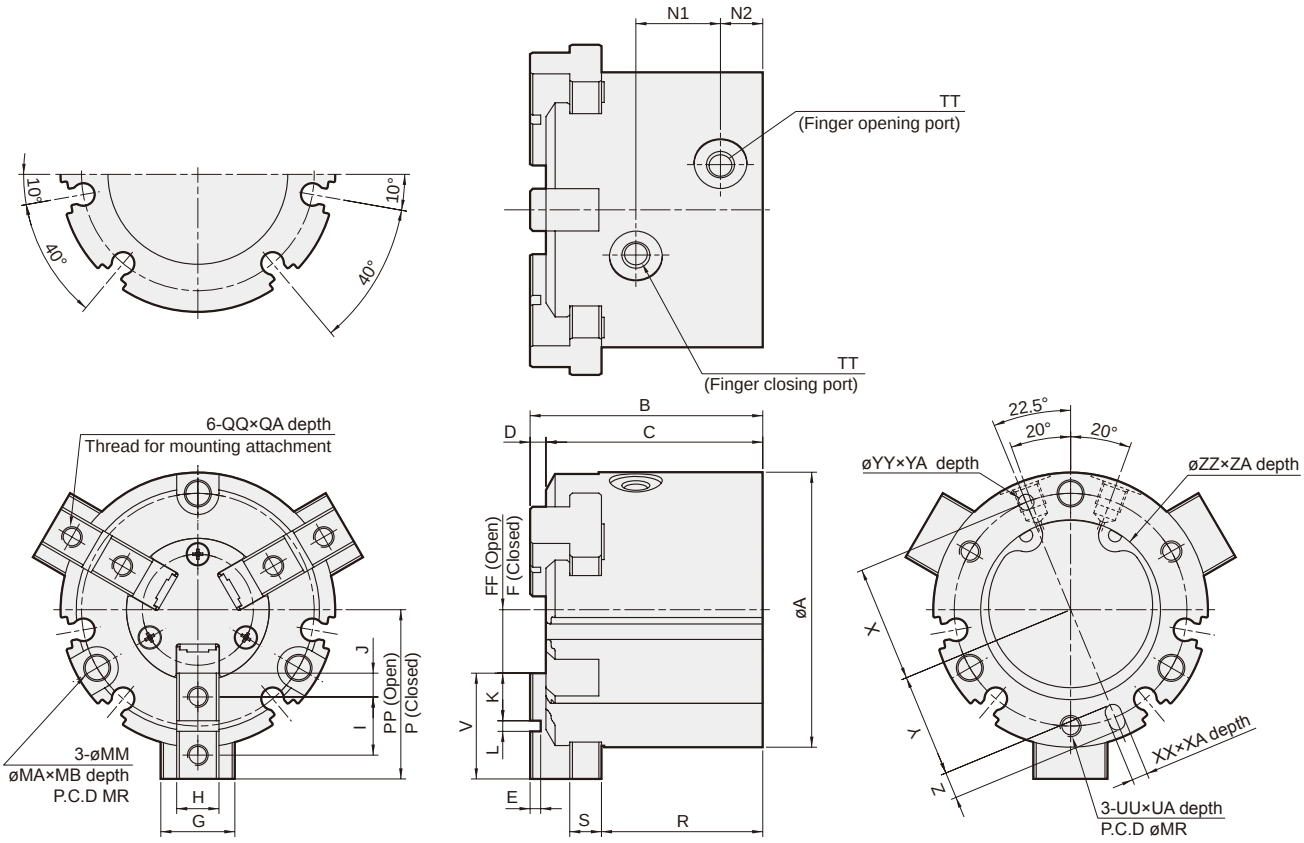
MCHG2 Dimensions ø16~ø25

PARALLEL GRIPPER (3-Finger)



Code / Tube I.D.	A	B	C	D	E	F	FF	G	H	I	J	K	L	MA	MB	MM	MR	N1	N2	P	PP	QA	QQ	R	S	TT
16	30	35	32	3	2	5	7	8	5h9 $^{+0}_{-0.030}$	6	2	4	2H9 $^{+0.025}_{-0}$	6.5	8	3.4	25	11	7	15	17	5	M3×0.5	25	4	M3×0.5
20	36	38	35	3	2	6	8	10	6h9 $^{+0}_{-0.030}$	7	2.5	5	2H9 $^{+0.025}_{-0}$	6.5	9.5	3.4	29	13	7	18	20	6	M3×0.5	27	5	M5×0.8
25	42	40	37	3	2	7	10	12	6h9 $^{+0}_{-0.030}$	8	3	6	2H9 $^{+0.025}_{-0}$	8	10	4.5	34	15	7	21	24	6	M3×0.5	28	5	M5×0.8

Code / Tube I.D.	UA	UU	V	X	XA	XX	Y	YA	YY	Z	ZA	ZZ
16	4.5	M3×0.5	10	12.5	2	2H9 $^{+0.025}_{-0}$	11	2	2H9 $^{+0.025}_{-0}$	3	1.5	17H9 $^{+0.043}_{-0}$
20	6	M3×0.5	12	14.5	2	2H9 $^{+0.025}_{-0}$	13	2	2H9 $^{+0.025}_{-0}$	3	1.5	21H9 $^{+0.052}_{-0}$
25	6	M4×0.7	14	17	3	3H9 $^{+0.025}_{-0}$	14.5	3	3H9 $^{+0.025}_{-0}$	5	1.5	26H9 $^{+0.052}_{-0}$



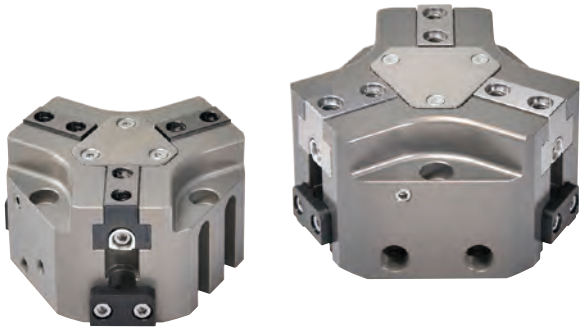
Code / Tube I.D.	A	B	C	D	E	F	FF	G	H	I	J	K	L	MA	MB	MM	MR	N1	N2	P	PP	QA	QQ
32	52	44	41	3	2	8	12	14	8h9 $^{+0}_{-0.036}$	11	4.5	9	2H9 $^{+0.025}_{-0}$	8	9	4.5	44	16	8	28	32	8	M4×0.7
40	62	47	44	3	2	10	14	16	8h9 $^{+0}_{-0.036}$	12	4.5	9	3H9 $^{+0.025}_{-0}$	9.5	9	5.5	53	17	9	31	35	8	M4×0.7
50	70	55	52	3	2	11	17	18	10h9 $^{+0}_{-0.036}$	14	5	10	4H9 $^{+0.030}_{-0}$	9.5	12	5.5	62	20	9	35	41	10	M5×0.8
63	86	66	62	4	3	15	23	24	12h9 $^{+0}_{-0.043}$	17	5.5	11	6H9 $^{+0.030}_{-0}$	11	14	6.6	76	22	12	43	51	10	M5×0.8
80	106	82	77	5	4	21.5	31.5	28	14h9 $^{+0}_{-0.043}$	20	6	12	8H9 $^{+0.036}_{-0}$	11	19	6.6	95	27	13.5	53.5	63.5	12	M6×1.0
100	134	96	90	6	4	28	40	34	18h9 $^{+0}_{-0.043}$	23	7.5	15	8H9 $^{+0.036}_{-0}$	14	21	9	118	30.6	18	66	78	16	M8×1.25
125	166	122	114	8	6	30	46	40	22h9 $^{+0}_{-0.052}$	31	10.5	21	10H9 $^{+0.036}_{-0}$	17.5	34	11	148	38	23.5	82	98	20	M10×1.5

Code / Tube I.D.	R	S	TT	UU	UA	V	X	XA	XX	Y	YY	YA	Z	ZA	ZZ
32	30.5	6	M5×0.8	M4×0.7	6	20	22	3	3H9 $^{+0.025}_{-0}$	19.5	3H9 $^{+0.025}_{-0}$	3	5	2	34H9 $^{+0.062}_{-0}$
40	32	7	M5×0.8	M5×0.8	7.5	21	26.5	4	4H9 $^{+0.030}_{-0}$	23.5	4H9 $^{+0.030}_{-0}$	4	6	2	42H9 $^{+0.062}_{-0}$
50	37.5	9	M5×0.8	M5×0.8	10	24	31	4	4H9 $^{+0.030}_{-0}$	28	4H9 $^{+0.030}_{-0}$	4	6	2	52H9 $^{+0.074}_{-0}$
63	44	11	M5×0.8	M6×1.0	9	28	38	5	5H9 $^{+0.030}_{-0}$	34.5	5H9 $^{+0.030}_{-0}$	5	7	2.5	65H9 $^{+0.074}_{-0}$
80	56	12	Rc1/8	M6×1.0	12	32	47.5	6	6H9 $^{+0.030}_{-0}$	43.5	6H9 $^{+0.030}_{-0}$	6	8	3	82H9 $^{+0.087}_{-0}$
100	63	15	Rc1/4	M8×1.25	16	38	59	6	8H9 $^{+0.036}_{-0}$	54	8H9 $^{+0.036}_{-0}$	6	10	4	102H9 $^{+0.087}_{-0}$
125	84	18	Rc3/8	M10×1.5	20	52	74	8	10H9 $^{+0.036}_{-0}$	68	10H9 $^{+0.036}_{-0}$	8	12	6	130H9 $^{+0.100}_{-0}$

MCHJ series

PARALLEL GRIPPER (3-Finger)

mindman



Features

- Compact design to ensure minimum interference while operating; robust T rail design, ensure accurate gripping.
- Can reach maximum torque suitable for long jaws design.
- Circular piston-driven design ensure maximum clamping force.
- Hose-free direct connection: Air supply channel can connect directly without piping or through tread to assure the flexibility of supplying compressed air on any kind of automation system.

Specification

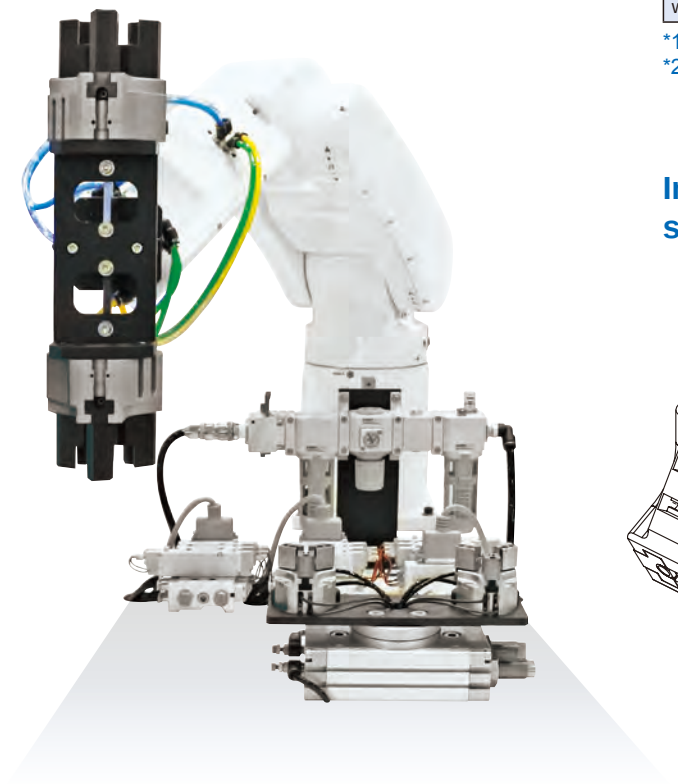
Model	MCHJ							
Acting type	Double acting							
Body specification	50	66	80	100	125	160	200	300
Stroke per-jaw (mm)	4	6	8	10	12	16	20	30
Closing force(N)	450	750	1200	2000	3500	6500	8200	15300
Opening force(N)	500	800	1300	2100	3600	6600	8450	15550
Close/Open time (1/s)	0.025	0.03	0.05	0.1	0.2	0.25	0.35	0.8
Medium	Air							
Operating pressure range	0.2~0.8 MPa							
Compressed air consumption (cm^3)	9.2	21.5	47	100	195	485	850	2300
Ambient temperature	+5°C~ +80°C							
Lubrication	Not required							
Sensor switch (*2) 2 wire	*1	**RDFE(V)**: Non-contact						
Sensor switch (*2) 3 wire	*1	**RNFE(V)**: NPN, **RPFE(V)**: PNP						
Accessories	Mounting block, Centering sleeve							
Weight (kg)	0.22	0.5	0.85	1.6	2.8	5.2	10.8	26.5
Recom. work piece weight (kg)	2.2	3.8	6.1	10.2	17.8	33.1	41.8	78

*1. Body specification 50 use RDGV sensor switch.
*2. R*FE(V), RDGV specification, please refer to page 86, 87.

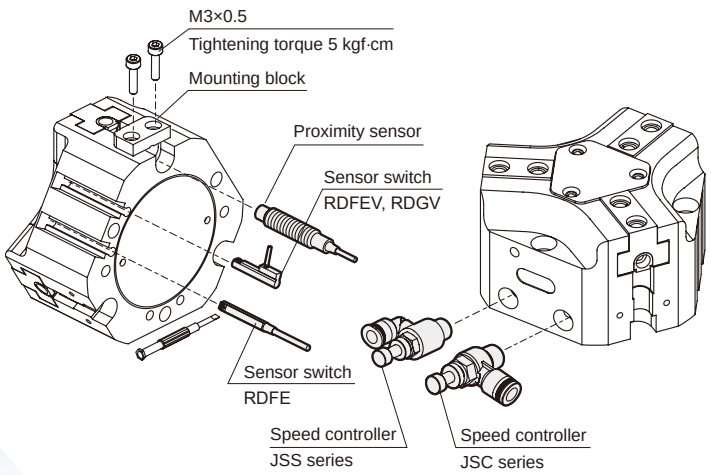
Order example

MCHJ — 50

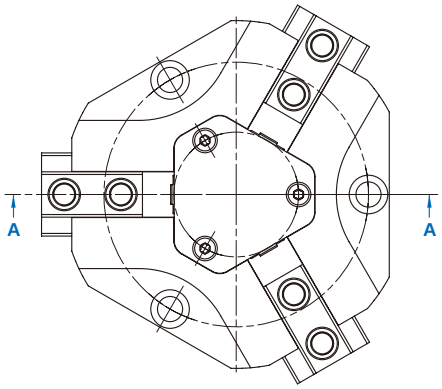
- MCHJ — MODEL
- 50 — BODY SPECIFICATION: **50, 66, 80, 100, 125, 160, 200, 300**



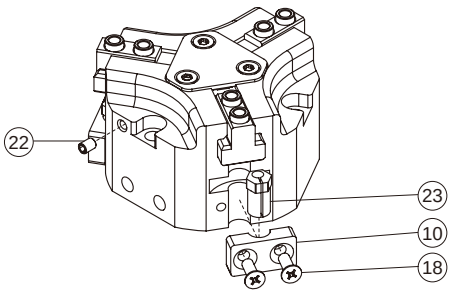
Installation of sensor switch & speed controller



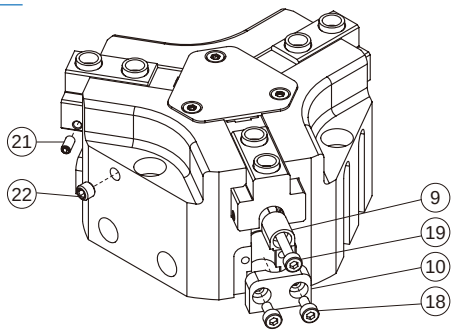
* Each gripper needs at least two speed control valves to control speed.
* Speed controller specification, please refer to Mindman website.

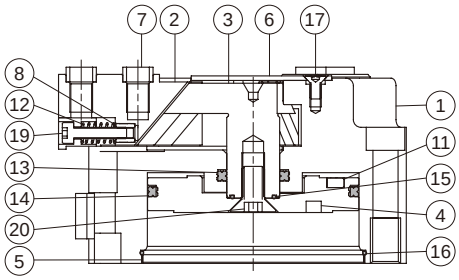


50



66~160





A-A

Material

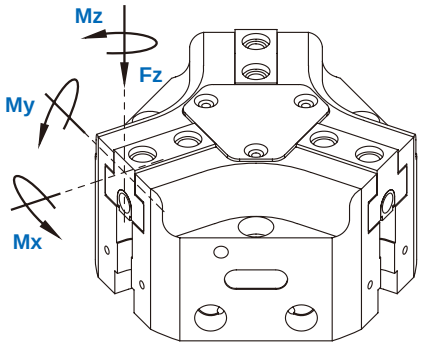
No.	Body spec / Part name	50	66	80	100	125	160	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy						1	
2	Finger	Mid carbon steel						3	
3	Rod	Mid carbon steel						1	
4	Piston	Aluminum alloy						1	
5	End cover	Stainless steel						1	
6	Plate cover	Stainless steel						1	
7	Centering sleeve	Stainless steel						6	
8	Thread insert	–		Brass				3	
9	Sensor adj block	–	Aluminum alloy					2	
10	Magnet holder	PBT+30%GF						2	
11	Magnet	Magnet material						1*	
12	Spring	–	SWP					2	
13	Rod packing	NBR						1	●
14	Piston packing	NBR						1	●
15	O-ring	NBR						1	●
16	O-ring	NBR						1	●
17	Screw	Carbon steel						3	
18	Bolt	Stainless steel						4	
19	Hex bolt	–	Stainless steel					2	
20	Bolt	Stainless steel						1	
21	Hex screw	–	Stainless steel					4	
22	Hex screw	Stainless steel						3	
23	Adjust socket	SUS	–					2	

* Body spec 125 Q'y: 2 pcs

Order example of repair kits

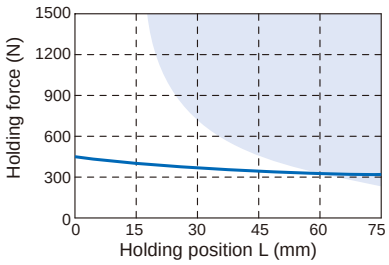
Model	Repair kits
MCHJ-50	**PS-MCHJ-50**
MCHJ-66	**PS-MCHJ-66**
MCHJ-80	**PS-MCHJ-80**
MCHJ-100	**PS-MCHJ-100**
MCHJ-125	**PS-MCHJ-125**
MCHJ-160	**PS-MCHJ-160**

Holding force

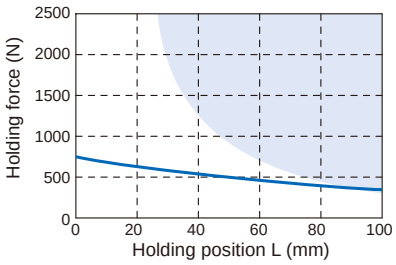


Code / Model	**Mx** max. (Nm)	**My** max. (Nm)	**Mz** max. (Nm)	**Fz** max. (N)
MCHJ-50	15	15	8	700
MCHJ-66	50	45	35	1200
MCHJ-80	80	60	50	1800
MCHJ-100	100	90	75	2500
MCHJ-125	120	120	100	3200
MCHJ-160	160	180	140	5000
MCHJ-200	180	220	170	7000
MCHJ-300	275	300	200	9000

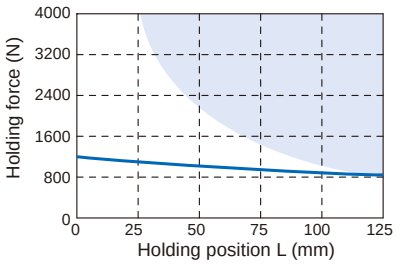
MCHJ-50



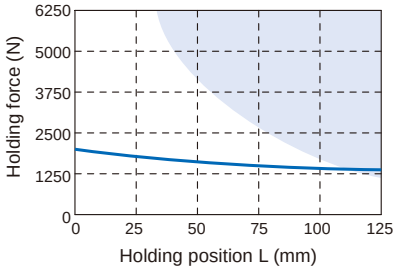
MCHJ-66



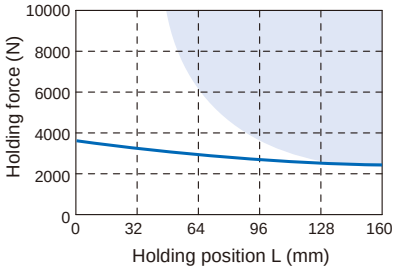
MCHJ-80



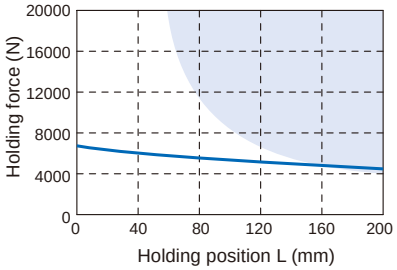
MCHJ-100



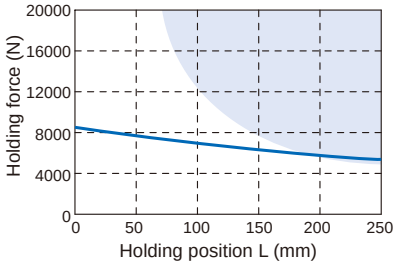
MCHJ-125



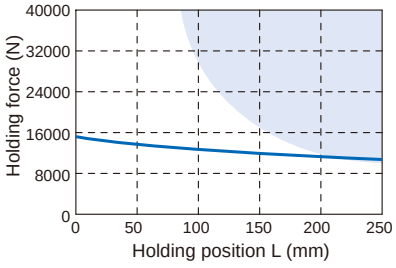
MCHJ-160



MCHJ-200



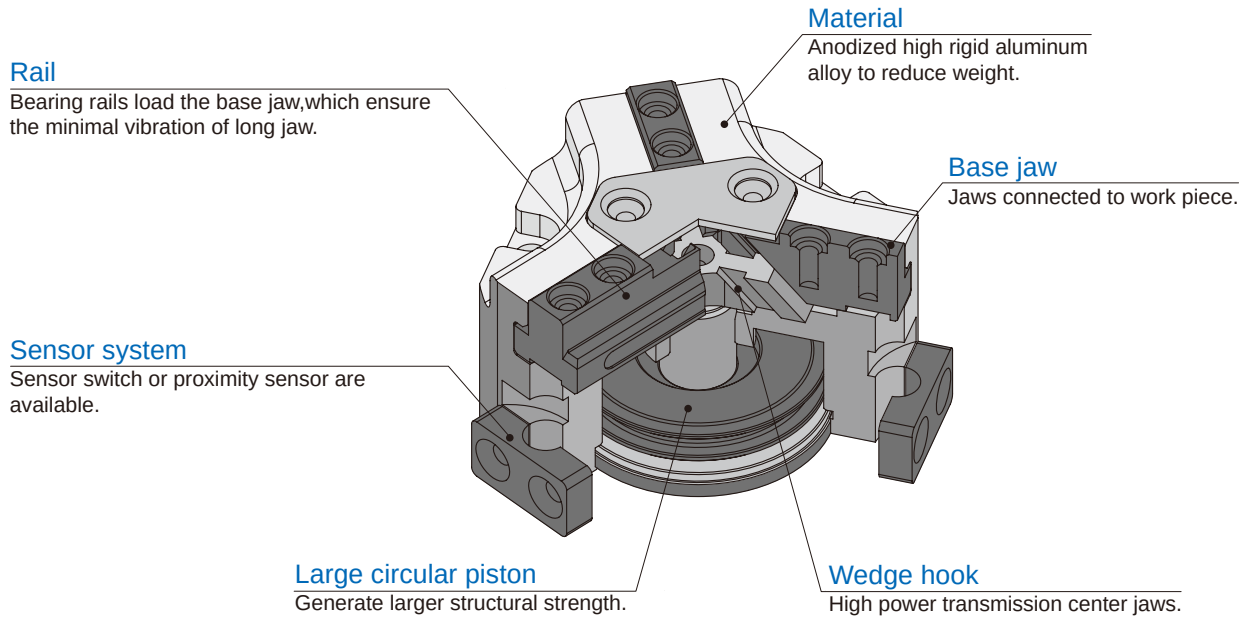
MCHJ-300



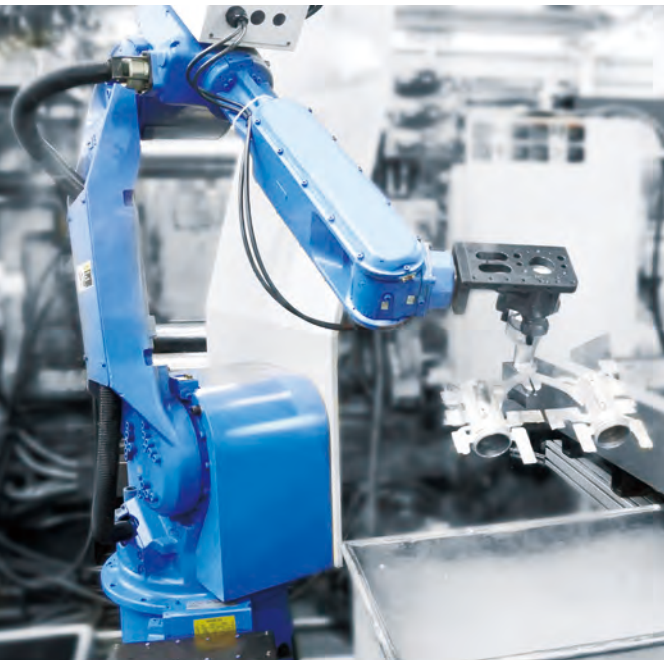
* Blue area: Less durable performance can be expected.

Internal structure & Movement description

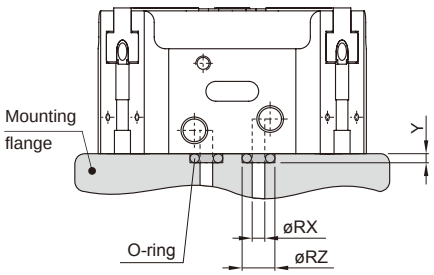
Compressed air will push or press the circular piston.
By tilting the working surface, the wedge hook will transfer the movement to side movement, and initiate the action of the three base jaws simultaneously.

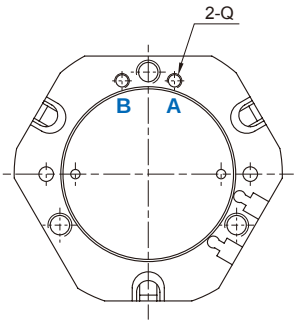


Application examples



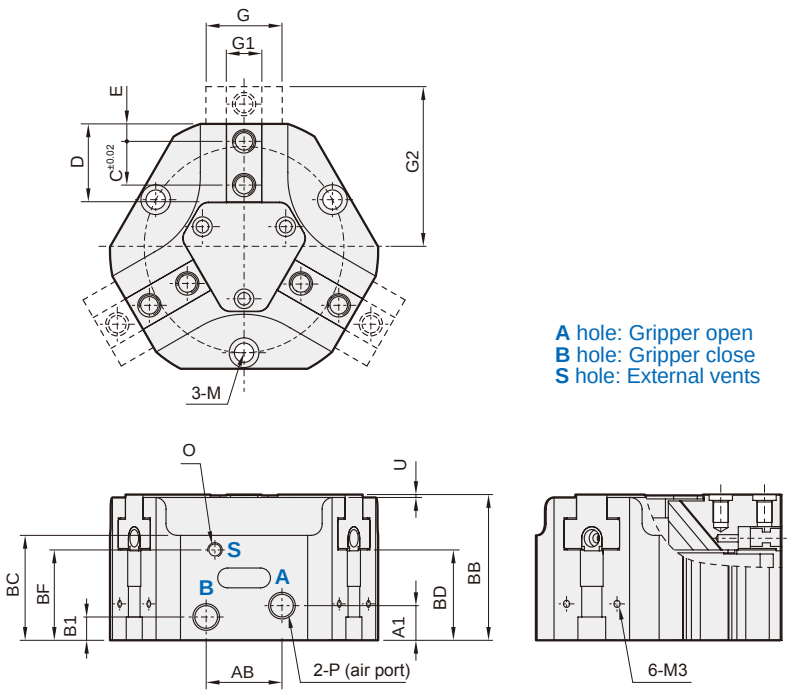
Hose-free direct connection





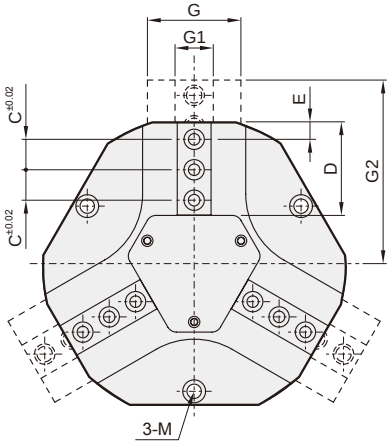
Code / Model	Q	RX	RZ	Y
MCHJ-50	M3	3	5	0.7
MCHJ-66	M5	5	8	1.2
MCHJ-80	M5	5	8	1.2
MCHJ-100	M5	5	8	1.2
MCHJ-125	M5	5	8	1.2
MCHJ-160	M5	5	8	1.2
MCHJ-200	M6	6	9	1.2
MCHJ-300	G1/8	8.5	12.1	1.8

A hole: Gripper open
B hole: Gripper close



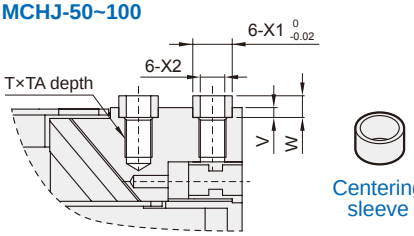
A hole: Gripper open
B hole: Gripper close
S hole: External vents

MCHJ-125~300

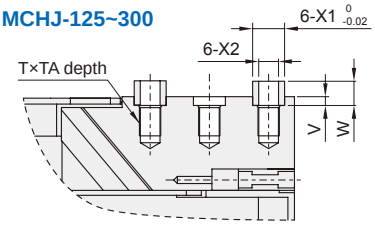


Centering sleeve

MCHJ-50~100

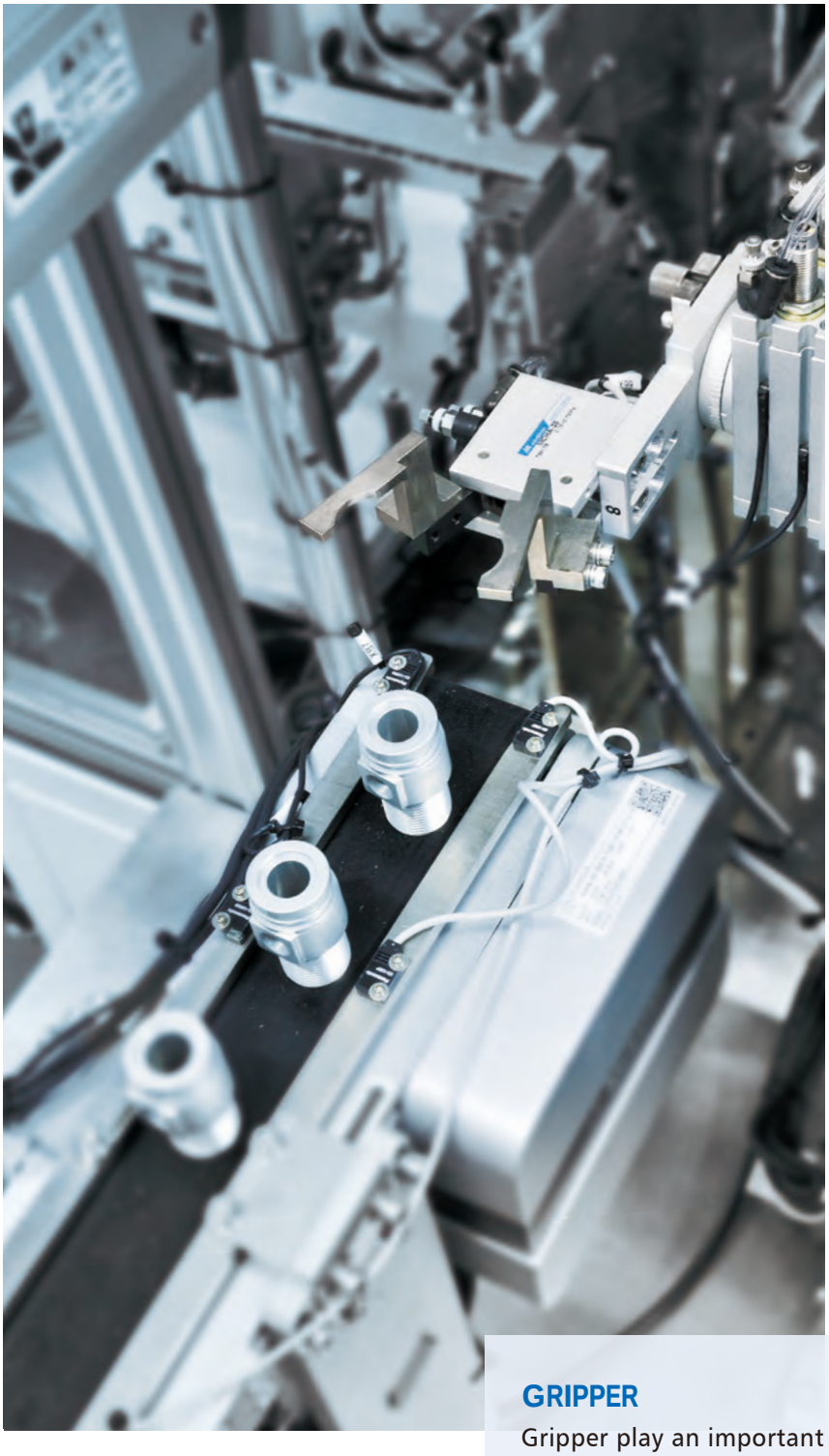


MCHJ-125~300



Code / Model	A1	AB	AC	B1	BB	BC	BD	BF	C	D	E	G	G1	G2	H1	H2	K	L	M
MCHJ-50	5	12	12	5	35	26	23	23	8	16	4	12	6.5	31	26	27	19	45	M4 DIN912
MCHJ-66	11.5	12	18	5	43	32	27	27	12	22	5	17	10	41	33	35	25	56	M5 DIN912
MCHJ-80	8	26	18	8	50	36	31	31	15	26.7	6	22	12	51.5	40.5	43.5	32	70	M6 DIN912
MCHJ-100	13.5	24	24	10	60	41	38	34	18	34.2	10	26	14	64	51	54	42	90	M6 DIN912
MCHJ-125	17	30	30	10	68	49	42.5	37	12.5	42.3	10	31	15.5	79	64	67	53	112	M8 DIN912
MCHJ-160	20	44	38	10.5	80	55	48	43.8	18	54.8	10	39	20	102	81	86	67.5	146	M8 DIN912
MCHJ-200	22	54	54	12.5	100	75	61	57	22	67.5	12	42	22	126	100	106	75	180	M10 DIN912
MCHJ-300	21	80	80	14	138	90	86	72	30	91	15	66	32	172	132.5	142	105	240	M12 DIN912

Code / Model	N	O	P	Q	R	S	T	TA	U	V	W	X1	X2
MCHJ-50	M5×8	M3	M5	M3	57	ø4H7×5	6-M3×0.5	7	1	2	3.9	ø5	ø3
MCHJ-66	M6×10	M5	M5	M5	74	ø4H7×8	6-M4×0.7	8	1	2	3.9	ø6	ø4
MCHJ-80	M8×12	M5	G1/8	M5	92	ø5H7×8	6-M6×1.0	10	1	2	3.9	ø8	ø6
MCHJ-100	M8×12	M5	G1/8	M5	114	ø5H7×8	6-M6×1.0	12	1	2	3.9	ø10	ø6
MCHJ-125	M10×15	M5	G1/8	M5	139	ø6H7×10	9-M6×1.0	14	1	2	3.9	ø10	ø6
MCHJ-160	M10×24	M5	G1/8	M5	179	ø6H7×10	9-M8	17	1	1.9	3.9	ø12	ø8
MCHJ-200	M12×25	M5	G1/4	M6	218	ø10H7×12	9-M10	20	1	2.4	4.9	ø14	ø10
MCHJ-300	M16×39.1	M5	G1/4	G1/8	292	ø10H7×12	9-M12	20	2	2.4	4.9	ø18	ø12



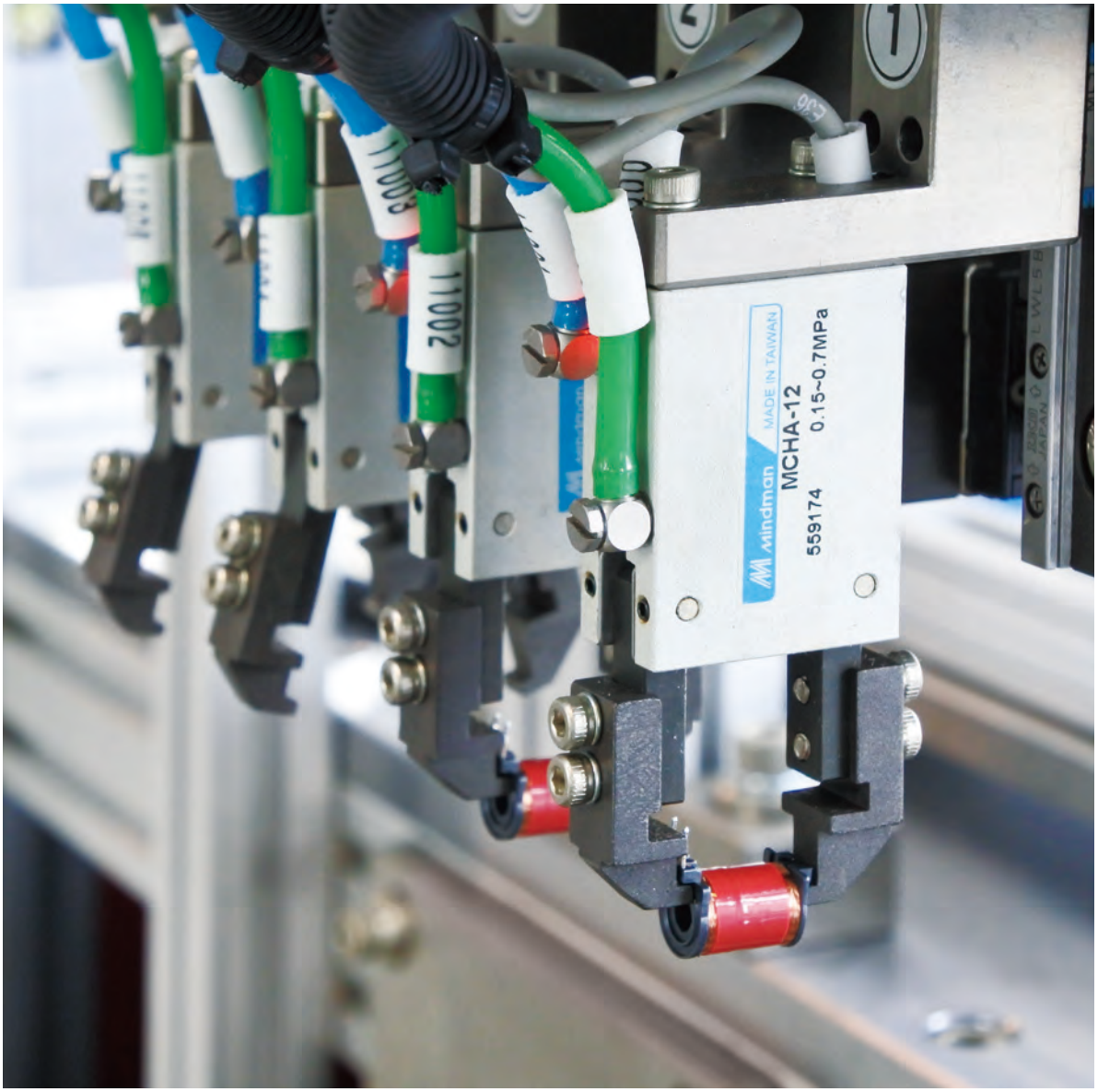
GRIPPER

Gripper play an important role in automation systems. Mindman provides various kinds of stable gripper for different applications.

Connect with

AIR CYLINDER

Connect gripper with cylinder to achieve regular workpiece gripping.



Features

- Hardened gripping fingers for longer service life.
- Simple structure with high stability.
- Magnetic as standard.

Specification

Model		MCHA				
Acting type		Double acting / Single acting (N.O.)				
Tube I.D. (mm)		12	16	20	25	32
Port size		M3×0.5	M5×0.8			
Medium		Air				
Operating pressure range	Double acting	0.15~0.7 MPa				
	Single acting	0.3~0.7	0.2~0.7 MPa			
Ambient temperature		-5~+60°C (No freezing)				
Max. frequency		180 Cycles/min				
Lubrication	Cylinder	Not required				
	Lever	Grease (Joint parts)				
Max. arm length (L) (*1)		30	40	60	70	85
Clamp / Release angle		-10~+30°				
Sensor switch (*2)		RDE, RDE-D: Non-contact				
Weight (g)		53	103	193	327	525

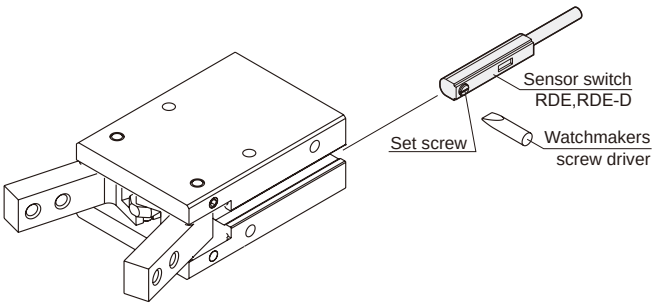
*1. L: Arm length (mm)
*2. RDE, RDE-D specification, please refer to page 85.

Order example

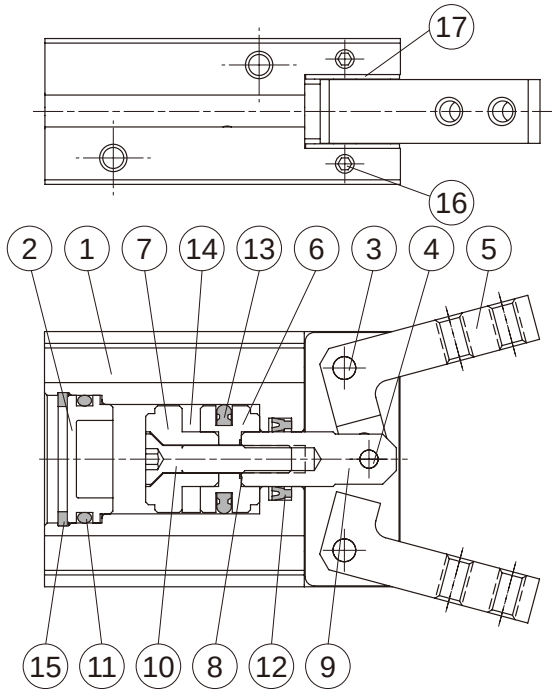
MCHA — 20 — □

- MODEL
- TUBE I.D.
  - **12**
  - **16**
  - **20**
  - **25**
  - **32**
- ACTING TYPE
  - Blank: Double acting
  - **S**: Single acting (Normally open)

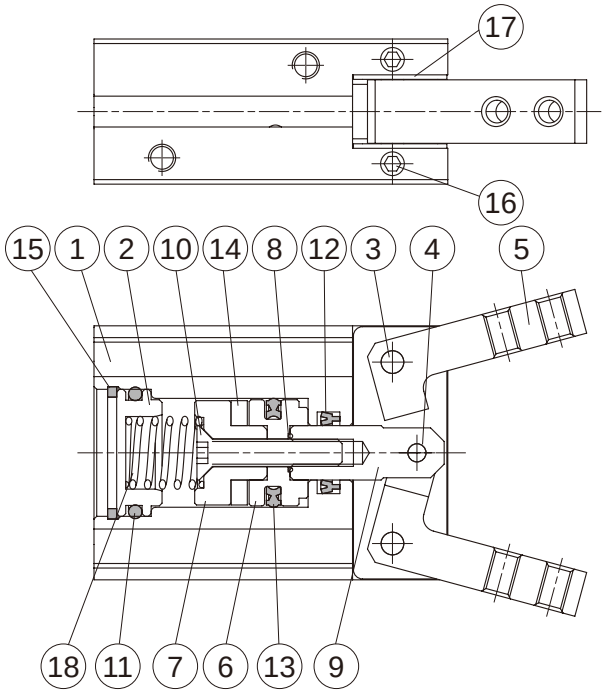
Installation of sensor switch



Double acting



Single acting Normally Open



Material

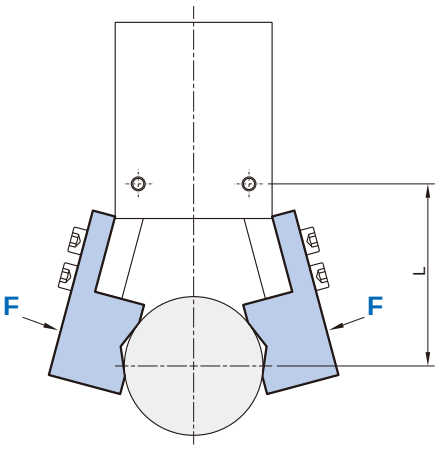
No.	Part name	Material	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy	1	
2	Head cover	Aluminum alloy	1	
3	Grip rivet	Carbon steel	2	
4	Spindle rivet	Bearing steel	1	
5	Y-finger	Medium carbon steel	2	
6	Piston-R	Aluminum alloy	1	
7	Piston-H	Aluminum alloy	1	
8	Gasket	NBR	1	●
9	Piston rod	Stainless steel	1	
10	Screw	Stainless steel	1	
11	Cover ring	NBR	1	●
12	Rod packing	NBR	1	●
13	Piston packing	NBR	1	●
14	Magnet ring	Magnet material	1	
15	Stop ring	Spring steel	1	
16	Screw	SCM	4	
17	Washer	Stainless steel	2	
18	Spring	SWB-P	1	

Order example of repair kits

Tube I.D.	Repair kits
ø12	**PS-MCHA-12**
ø16	**PS-MCHA-16**
ø20	**PS-MCHA-20**
ø25	**PS-MCHA-25**
ø32	**PS-MCHA-32**

Effective gripping force

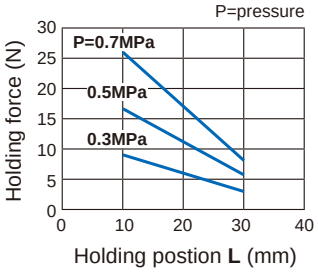
Indication of effective force.
The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



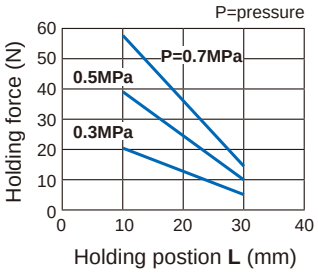
1N=0.102 kgf
1MPa=10.2 kgf/cm^2

Double acting

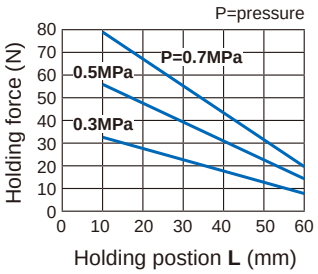
MCHA-12



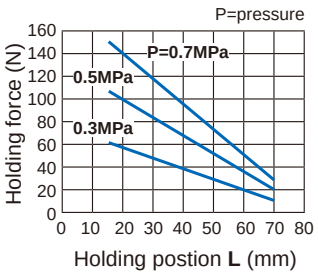
MCHA-16



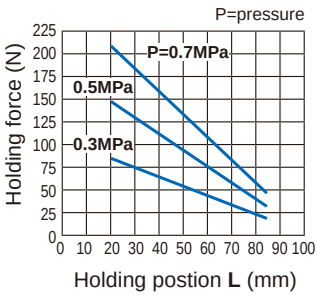
MCHA-20



MCHA-25

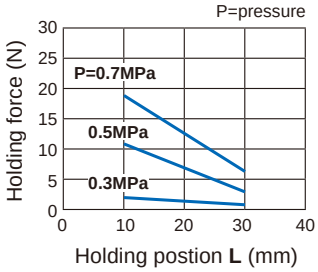


MCHA-32

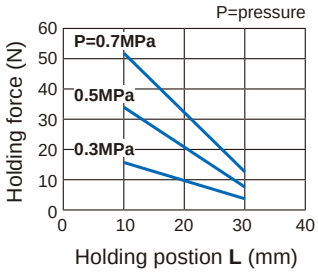


Single acting (Normally open)

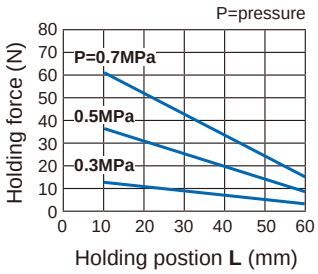
MCHA-12



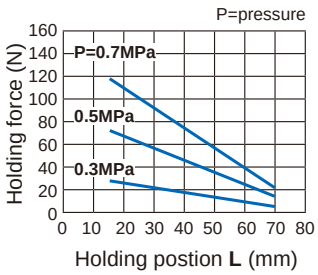
MCHA-16



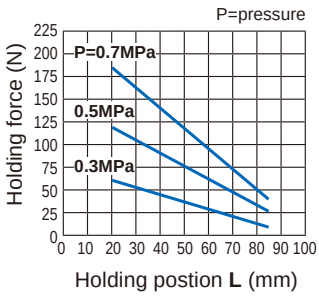
MCHA-20

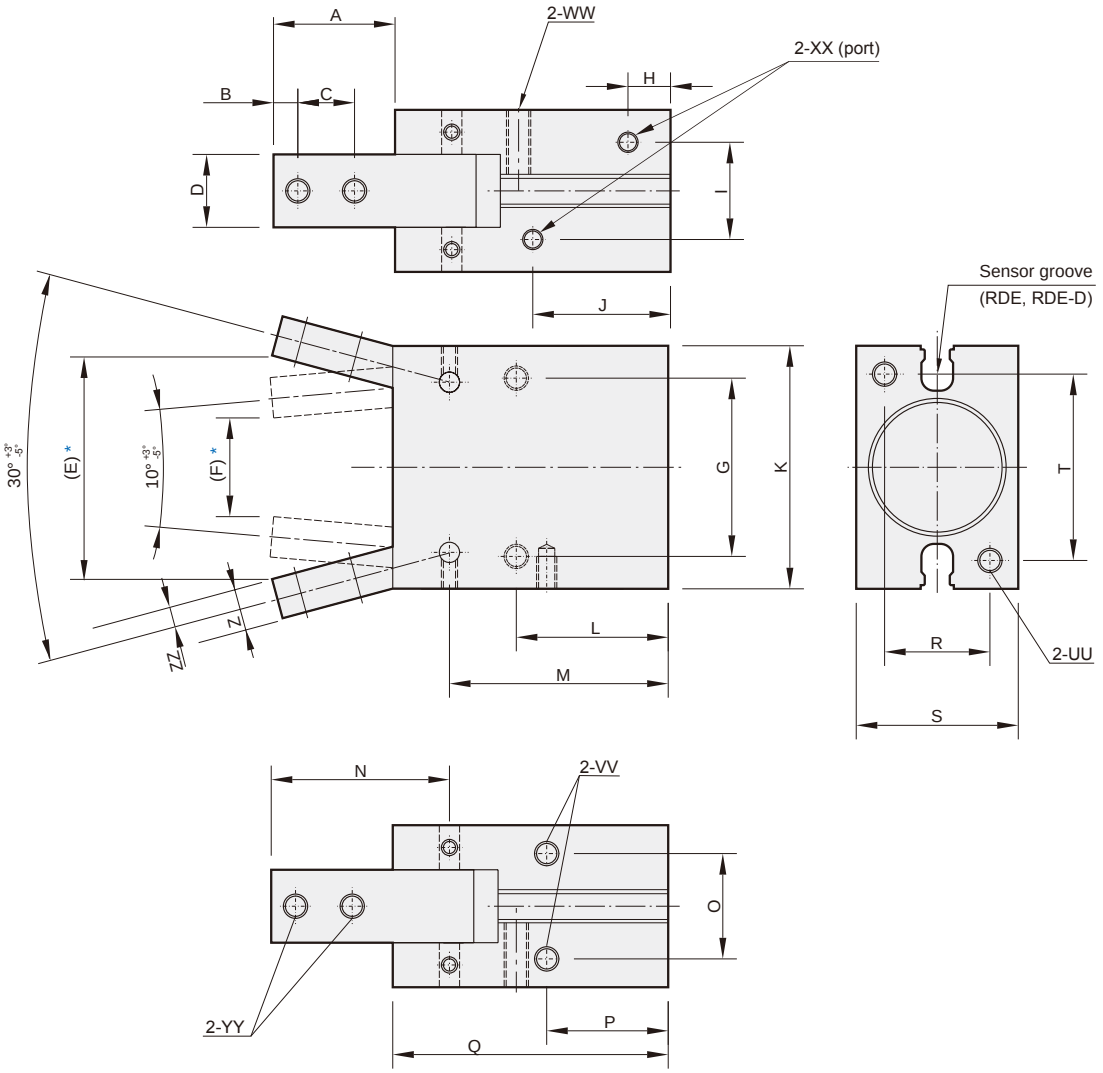


MCHA-25



MCHA-32

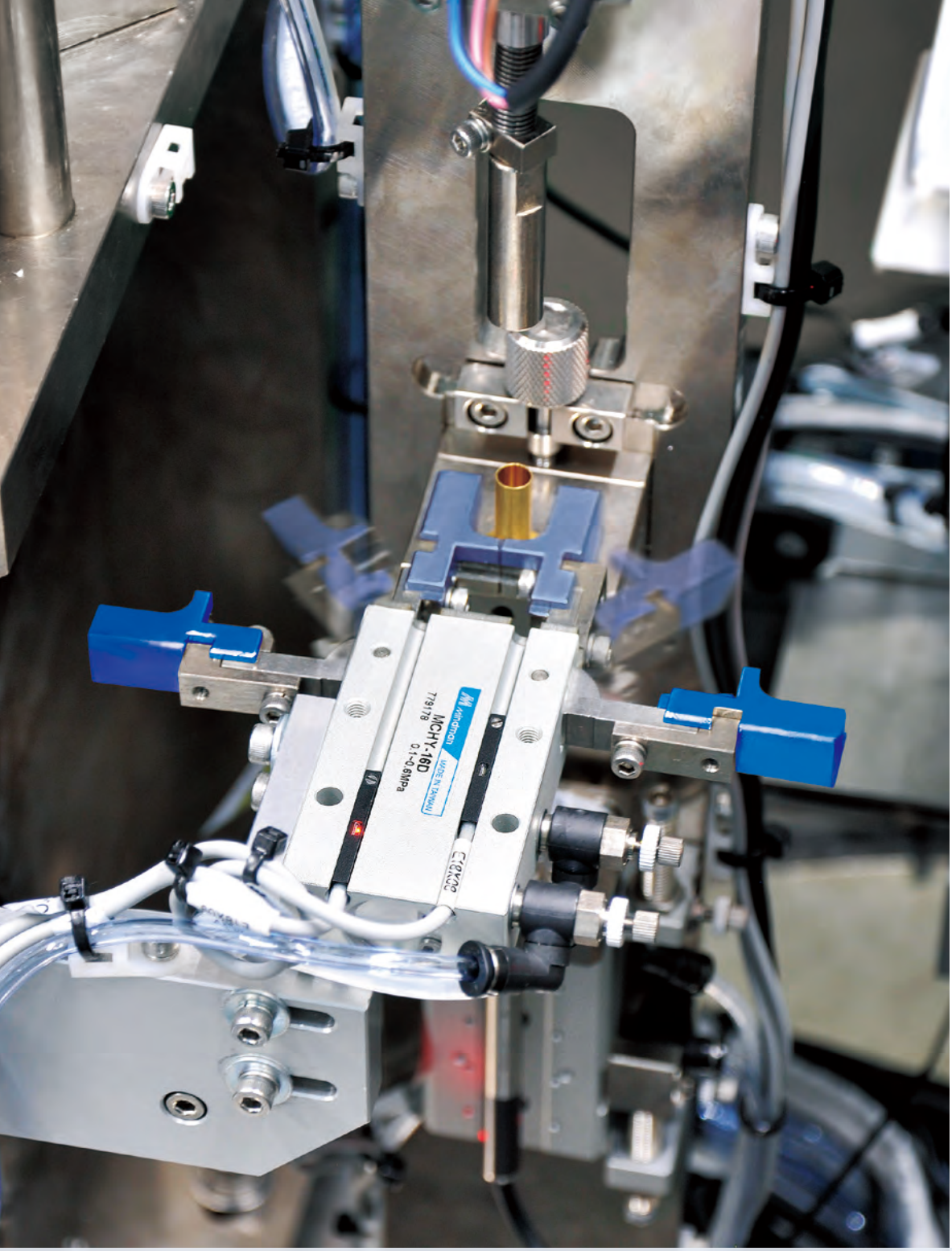




* Reference value.

Code / Tube I.D.	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	UU	VV
12	15.4	3	6	7	26.3	9	20	7.5	10.2	23	28	20	32.9	21.5	10.2	16	39	10	16	22	M3×5 depth	M3×5 depth
16	17.5	3	8	9	31.1	14	24	7.5	12	22	34	22.5	35	25	14	18	42.5	14	22	26	M4×7 depth	M4×7 depth
20	22	4	10	12	40.1	18	30	8.0	13	25	45	25	39.5	32.5	16	19	50	16	26	35	M5×8 depth	M5×8 depth
25	26	5	12	14	47.9	21	36	8.5	18	28	52	28.5	45.5	38.5	20	21.5	58	20	32	40	M6×10 depth	M6×8 depth
32	30	6	14	18	55.1	24	44	10.5	24	34	60	37.5	54	44	26	30	68	26	40	46	M6×10 depth	M6×8 depth

Code / Tube I.D.	WW	XX	YY	Z	ZZ
12	M3×8 depth	M3×5 depth	M3	5	2.5
16	M4×11 depth	M5×5 depth	M3	6	3
20	M5×12 depth	M5×5 depth	M4	7	3.5
25	M6×16 depth	M5×5 depth	M5	9	4
32	M6×20 depth	M5×5 depth	M6	10	5



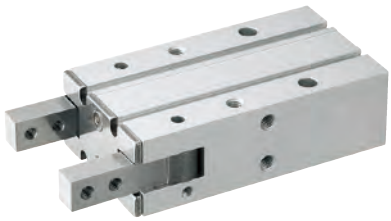
Connect with

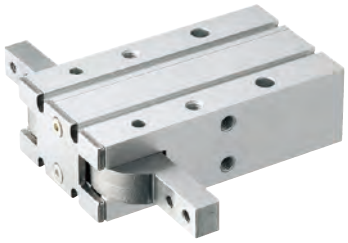
AUTOMATIC ASSEMBLY MACHINE

Connect gripper with cylinder to achieve regular workpiece gripping.

MCHY series

180° ANGULAR **GRIPPER** - CAM STYLE





Features

- Compact design and lightweight construction.
- High gripping forces achieved via internal cams. Reduced required offset while moving gripper. (Fig1).
- Reference points on gripping fingers are standard.
- Sensors can be mounted in any one of four positions.
- Rod seal prevents foreign objects to enter piston.

Specification

Model		MCHY			
Acting Type		Double acting			
Tube I.D. (mm)		10	16	20	25
Medium		Air			
Operating pressure range		0.1~0.6 MPa			
Ambient temperature		-10~+60°C (No freezing)			
Repeatability		±0.2 mm			
Max. operating frequency (c.p.m)		60 (*1)			
Lubrication (*2)		Not required			
Effective force (Nm) at (0.5 MPa)		0.16	0.54	1.1	2.28
Operating angle (both sides)	Opened side	180°~182°			
	Closed side	-3°			
Sensor switch (*3)	2 wire	**RDFE(V)**: Non-contact			
	3 wire	**RNFE(V)**: NPN, **RPFE(V)**: PNP			
Weight (g)		80	150	320	600

*1. Speed adjust components are required while in use.
*2. Sliding area of jaws need scheduled relubrication.
*3. R*FE(V) specification, please refer to page 86.

Order example

MCHY — 16 D 1

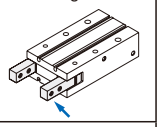
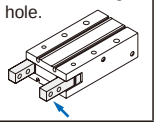
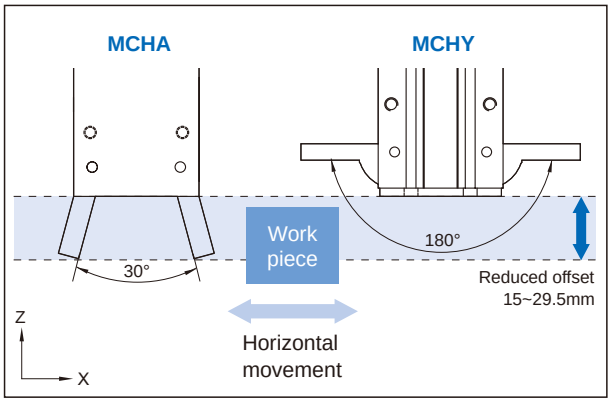
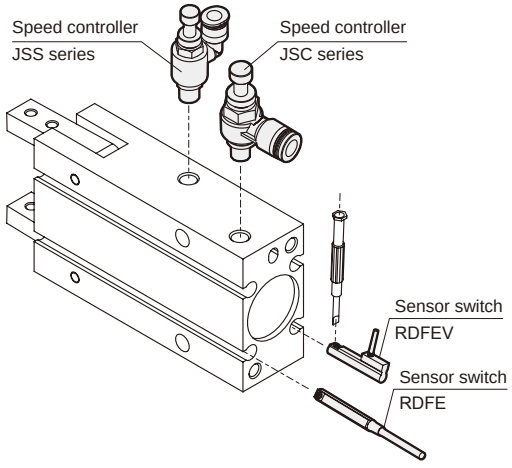
MODEL	TUBE I.D.		D: Double acting	FINGER OPTION	
	10			—	Standard tap mounting 
	16				
	20				
	25			**1**	Opening / closing direction through hole. 

Fig1. Reduced required offset while moving gripper

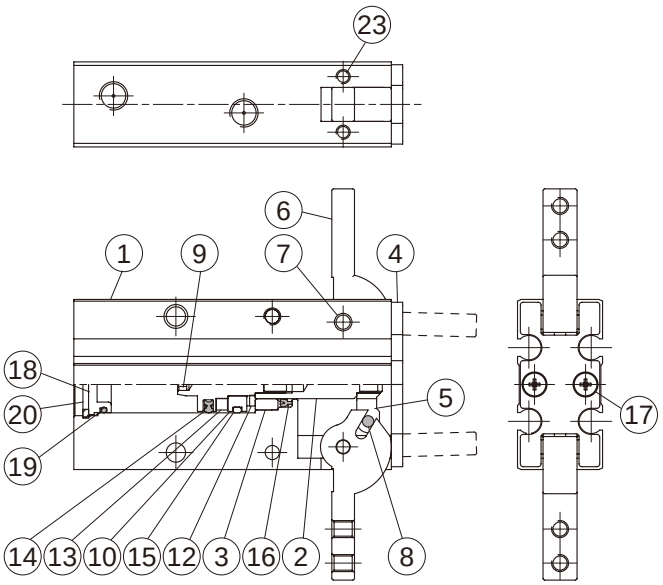


Installation of sensor switch & speed controller

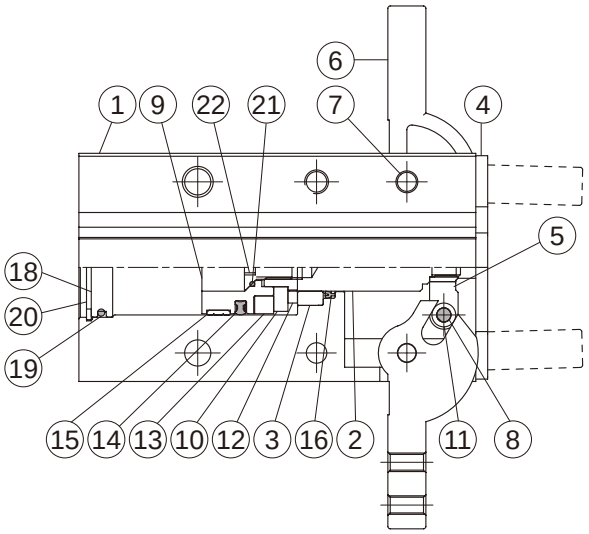


* Each gripper needs at least two speed control valves to operate.
* Speed controller specification, please refer to Mindman website.

ø10



ø16~ø25



Material

No.	Tube I.D. / Part name	10	16	20	25	Q'y	Repair kits (inclusion)
1	Body	Aluminum alloy				1	
2	Piston rod	Stainless steel				1	
3	Bushing	Brass				1	
4	Head cover	Stainless steel				1	
5	Lever	Stainless steel				1	
6	Gripper	Stainless steel				2	
7	Grip rivet	Carbon steel				2	
8	Pin	Carbon steel				2	
9	Piston	*1	Aluminum alloy			1	
10	Magnet holder	Stainless steel				1	
11	Pin bushing	–		SCM		2	
12	Cushion pad	NBR	PU			1	●
13	Magnet ring	Magnet material				1	
14	Piston packing	NBR				1	●
15	Wear ring	Teflon				1	
16	Rod packing	NBR				1	●

No.	Tube I.D. / Part name	10	16	20	25	Q'y	Repair kits (inclusion)
17	Screw	Stainless steel				2	
18	Rod cover	Aluminum alloy				1	
19	O-ring	NBR				1	●
20	Snap ring	*2	Stainless steel			1	
21	O-ring	–	NBR			1	●
22	Hexagon Bolt	–	Stainless steel			1	
23	Scew	Stainless steel				4	

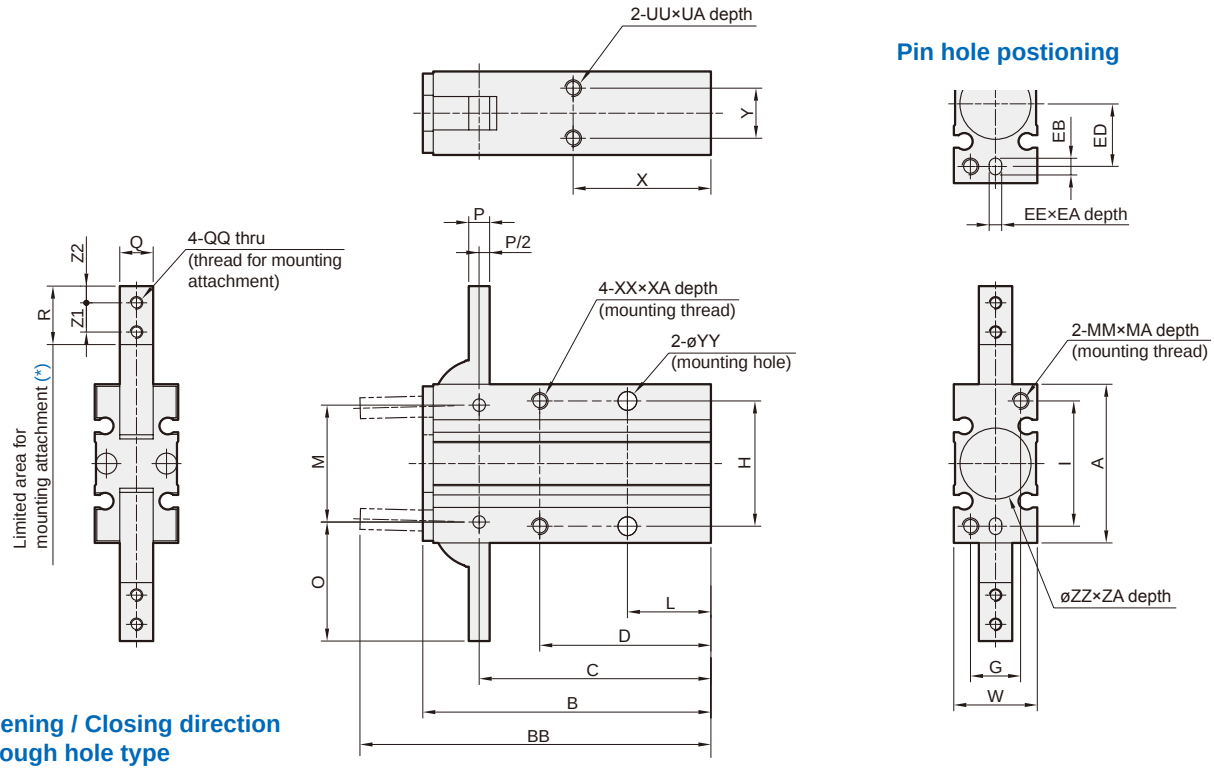
*1. Stainless steel *2. Carbon steel

Order example of repair kits

Tube I.D.	Repair kits
ø10	**PS-MCHY-10**
ø16	**PS-MCHY-16**
ø20	**PS-MCHY-20**
ø25	**PS-MCHY-25**

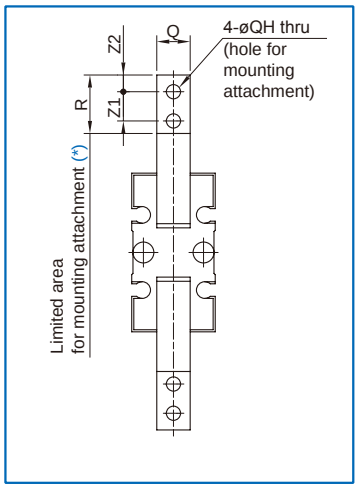
MCHY Dimensions ø10~ø25

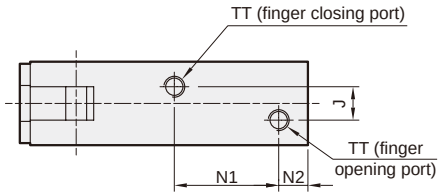
180° ANGULAR **GRIPPER** - CAM STYLE



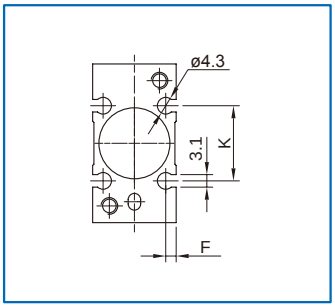
Pin hole postioning

Opening / Closing direction through hole type





Auto switch mounting groove position



* Do not extend the attachment from limited area for mounting to avoid interference with the attachment or main body.

Code / Tube I.D.	A	B	BB	C	D	EE	EA	EB	ED	F	G	H	I	J	K	L	M	MA	MM	N1	N2	O	P	Q	QH	QQ
10	30	58	71	47.5	35	3H9 $^{+0.025}_{-0}$	3	4	9	2	9	24	24	3	13	18	22	6	M3×0.5	23	7	23.5	4	6 $^{-0.005}_{-0.025}$	3.4	M3×0.5
16	38	69	84	55.5	41	3H9 $^{+0.025}_{-0}$	3	4	15	2.5	12	30	30	8	18	20	28	8	M4×0.7	25	7	28.5	5	8 $^{-0.005}_{-0.025}$	3.4	M3×0.5
20	48	86	106	69	50	4H9 $^{+0.030}_{-0}$	4	5	19	3	16	36	38	12	20	25	36	10	M5×0.8	32	8	37	8	10 $^{-0.005}_{-0.025}$	4.5	M4×0.7
25	58	107	131	86	60	4H9 $^{+0.030}_{-0}$	4	5	23	3	18	42	46	14	24	30	45	12	M6×1	42	8	45	10	12 $^{-0.005}_{-0.025}$	5.5	M5×0.8

Code / Tube I.D.	R	TT	UA	UU	W	X	XA	XX	Y	YY	ZA	ZZ	Z1	Z2
10	12	M5×0.8	4	M3×0.5	15	30	6	M3×0.5	9	3.4	1.5	11H9 $^{+0.043}_{-0}$	6	3
16	14	M5×0.8	5	M4×0.7	20	33	8	M4×0.7	12	4.5	1.5	17H9 $^{+0.043}_{-0}$	7	4
20	18	M5×0.8	8	M5×0.8	26	42	10	M5×0.8	14	5.5	1.5	21H9 $^{+0.052}_{-0}$	9	5
25	22.5	M5×0.8	10	M6×1	30	50	12	M6×1	16	6.6	1.5	26H9 $^{+0.052}_{-0}$	12	6

RDE series

SENSOR SWITCH

mindman

Order example

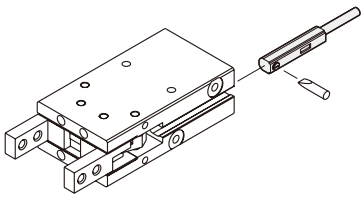
* Special order is available.

RDE – □

MODEL
RCE: Reed Switch
RDE: Non-contact
RDE-D: Non-contact, two indicators
RNE: NPN
RNEE: NPN
RPE: PNP
RPEE: PNP

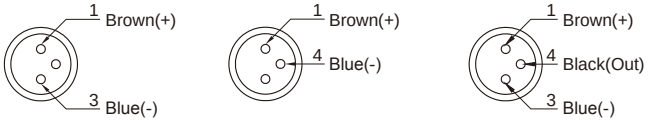
WIRE LENGTH
Blank: L=2000mm
1M: L=1000mm
QD: M8, 3 Pin connector
EQD: M8, 3 Pin connector

Assembling style

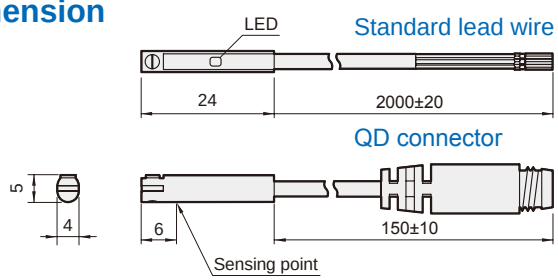
Cylinder type	Mounting clamp
MCHA, MCHB, MCHC	

Wiring of the QD

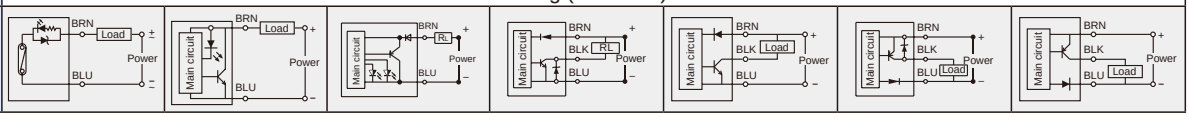
● 2 wire QD wiring ● 2 wire EQD wiring ● 3 wire QD wiring



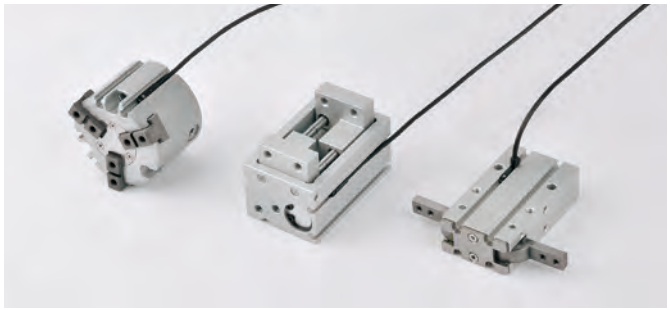
Dimension



Specification

Model	RCE	RDE	RDE-D	RNE	RNEE	RPE	RPEE
Wiring method	2 wire			3 wire			
Switching logic	SPST normally open			Solid state output, normally open			
Switch Type	Reed switch	Non-contact		NPN current sinking		PNP current sourcing	
Operating voltage	5~220V DC/AC	10~28V DC		5~30V DC			
Switching current	50mA max.	50mA max.	80mA max.	50mA max.	200mA max.	50mA max.	200mA max.
Switching rating(*1)	10W max.	1.5W max.	2W max.	1.5W max.	6W max.	1.5W max.	6W max.
Current consumption	—			10 mA@24V DC max.	6 mA@24V DC max.	12 mA@24V DC max.	6 mA@24V DC max.
Voltage drop	3.5V max.		4V max.	0.5V max.		1.5V max.	0.5V max.
Leakage current	—	0.1mA max.	1mA max.	0.01mA max.			
Indicator (LED)	Red		Red/Green	Red		Green	
Cable	ø2.8,2C,PUR	ø2.8,2C,PUR		ø3, 3C, PU			
Temperature range	–10~+70°C (No freezing)						
Shock (*2)	30G	50G					
Vibration (*3)	9G						
Enclosure classification	IEC 60529 IP67						
Protection circuit (*4)	1	3,4	2,3,4	3,4			
Weight	20 g (2m cable)						
Connect diagram							

*1. Warning: Never exceed rating (watt=voltage×amperage). Permanent damage to sensor will occur.
*2. Sin wave / X.Y.Z. 3 directions / 3 times each direction / 11ms each time.
*3. Double amplitude 1.5mm / 10Hz~55Hz~10Hz(Sweep 1min) / X.Y.Z. 3 directions / 1 hour each time.
*4. 1=None / 2=Short-circuit / 3=Power source reverse polarity / 4=Surge suppression
*5. Caution for safety please refer to the page 92.

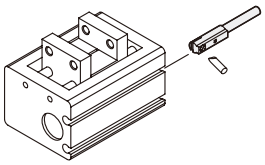


Order example
* Special order is available.

RDF V — □

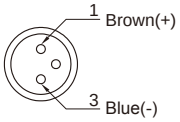
MODEL	AUTO SWITCH TYPE	WIRE LENGTH
RDF: Non-contact **RDFE**: Non-contact **RNF**: NPN **RNFE**: NPN **RPF**: PNP **RPFE**: PNP	Blank: Straight cable **V**: Angle cable	Blank: L=2000mm **1M**: L=1000mm **QD**: M8, 3 Pin connector **EQD**: M8, 3 Pin connector

Assembling style

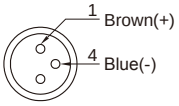
Cylinder type	Mounting clamp
MCHC-6, MCHD, MCHH, MCHU, MCHS, MCHX, MCHG2, MCHJ, MCHY	

Wiring of the QD

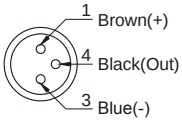
● 2 wire QD wiring



● 2 wire EQD wiring

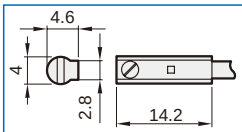


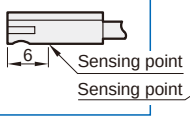
● 3 wire QD wiring



Dimension

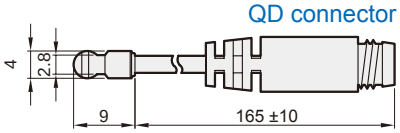
Straight cable



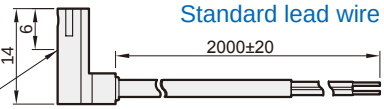


Angle cable

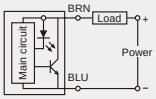
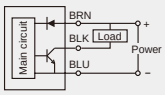
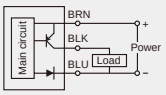
QD connector



Standard lead wire



Specification

Model	RDF / RDFV	RDFE / RDFEV	RNF / RNFV	RNFE / RNFEV	RPF / RPFV	RPFE / RPFEV
Wiring method	2 wire		3 wire			
Switching logic	Solid state output, Normally open					
Switch Type	Non-contact		NPN current sinking		PNP current sourcing	
Operating voltage	10~28V DC	5~30V DC	4.5~28V DC	5~30V DC	4.5~28V DC	5~30V DC
Switching current	4~20mA max.	50mA max.				
Contact rating(*1)	0.6W max.	1.5W max.				
Current consumption	—		10mA @24V DC max.			
Voltage drop	3.5V max.		0.5V @ 50mA max.			
Leakage current	0.8mA max.	0.1mA(40uA) max.	0.01mA max.			
Indicator	Red LED					
Cable	ø2.6, 2C, PVC		ø2.6, 3C, PVC			
Temperature range	–10~+70°C (No freezing)					
Shock (*2)	50G					
Vibration (*3)	9G					
Enclosure classification	IEC 60529 IP67					
Protection circuit (*4)	4	3, 4				
Weight	12.8 g (1m cable) / 23.8 g (2m cable)					
Connect diagram						

*1. Warning: Never exceed rating (watt=voltage×amperage). Permanent damage to sensor will occur.
*2. Sin wave / X.Y.Z. 3 directions / 3 times each direction / 11ms each time.
*3. Double amplitude 1.5mm / 10Hz~55Hz~10Hz(Sweep 1min) / X.Y.Z. 3 directions / 1 hour each time.
*4. 1=None / 2=Short-circuit / 3=Power source reverse polarity / 4=Surge suppression
*5. Caution for safety please refer to page 92.

RDGV series

SENSOR SWITCH

Order example

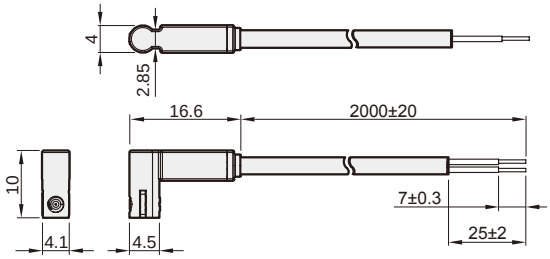
RDGV – □

- SWITCH TYPE
  - **D**: Non-contact
  - **N**: NPN
  - **P**: PNP
- AUTO SWITCH TYPE
  - **V**: Angle cable
- WIRE LENGTH
  - Blank: L=2000mm
  - **1M**: L=1000mm
  - **QD**: M8, 3 Pin connector
  - **EQD**: M8, 3 Pin conncetor

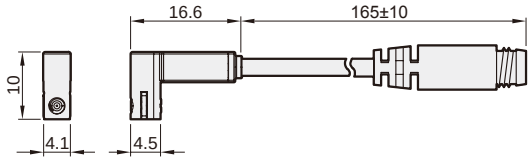
* Special order is available.

Dimension

RDGV / RNGV / RPGV

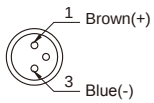


RDGV-QD / RNGV-QD / RPGV-QD

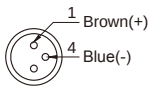


Wiring of the QD

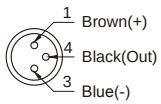
- 2 wire QD wiring



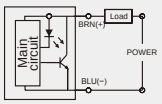
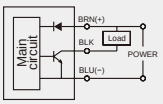
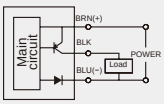
- 2 wire EQD wiring



- 3 wire QD wiring

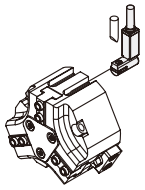


Specification

Model	RDGV	RNGV	RPGV
Wiring method	2 wire	3 wire	
Switching logic	Solid state output, Normally open		
Switch type	Non-contact	NPN current sinking	PNP current sourcing
Operating voltage	10~28V DC	5~28V DC	
Switching current	4~20mA max.	50mA max.	
Contact rating (*1)	0.6W max.	1.5W max.	
Current consumption	—	10mA @24V DC max.	
Voltage drop	3.5V max.	0.5V @ 50mA max.	
Leakage current	0.8mA max.	0.01mA max.	
Indicator	Red LED		
Cable	ø2.6, 2C, PVC	ø2.6, 3C, PVC	
Temperature range	–10°C~+70°C (No freezing)		
Shock (*2)	50G		
Vibration (*3)	9G		
Enclosure classification	IEC 60529 IP67		
Protection circuit (*4)	4	3, 4	
Weight	23 g (2m cable)		
Connect diagram			

* 1. Warning: Never exceed rating (watt=voltage×amperage). Permanent damage to sensor will occur.
* 2. Sin wave / X.Y.Z. 3 Directions / 3 Times each direction / 11ms each time.
* 3. Double amplitude 1.5mm / 10Hz~55Hz~10Hz(Sweep 1min) /X.Y.Z. 3 Directions / 1 Hour each time.
* 4. 1=None / 2=Short-circuit / 3=Power source reverse polarity / 4=Surge suppression.
* 5. Caution for safety please refer to page 92.

Assembling style

Cylinder type	Mounting clamp
MCHJ-50	

MEMO

NOTE

Caution for safety

⚠ ALL PRODUCTS

Before selecting model and servicing of the product, read throughly this CAUTIONS FOR SAFETY for the proper usage.

- The following cautions are for the purpose of preventing your personnel from suffering injury, by following the proper usage of the products.
- Items are classified in three categories, DANGER, WARNING, and CAUTION. All items are crucial for the safety and need to be followed without exception.

DANGER ⚠	Obviously dangerous, which may cause death or serious injury of personnel, and damage or destruction of property.
WARNING ⚠	Not immediately subject to danger, however not avoiding the displayed danger when mishandling the product may cause death or serious injury of personnel and damage or destruction of property.
CAUTION ⚠	Not immediately subject to danger, however not avoiding the displayed danger when mishandling the product may cause injury of personnel and damage or destruction of property.

For the correct handling, please read the instruction manual before installing and servicing of the product.

⚠ DANGER

(Applies to all products on the catalogue)

❶ Do not use any of our products for the purpose of maintenance and care of human life or body.

❷ Do not use any product in the condition or the environment other than stipulated in the specification or where the hazardous stuff exists.

❸ When installing a product, refer to the instruction manual for mounting style and fix securely (including the work carrier). Otherwise products may topple, fall, and operates out of control causing the injury of personnel.

❹ Disassembling and reassembling of products should be made by the personnel who has enough knowledge and experience.
❺ Depressurize products before disassembling or reassembling.

❻ Do not remodel the products.

⚠ WARNING

(Applies to all products on the catalogue)

❶ When servicing, keep within the working pressure range and voltage.
❷ At a place where water or oil drops and where is much dust, cover the equipment. Otherwise damage and trouble will be caused.
❸ Do not operate if the fluid or atmosphere contains the substance which may cause corrosion. Otherwise damage and trouble will be caused.
❹ Do not touch the terminal part or switches, etc. when the product is energized. It may cause the inaccurate operation and the electric shock from the short circuit and the circuit trouble.

❺ Do not stand on, use as a footing, or put things on the product. You may miss your step and fall, and the falling product may cause the injury of personnel. Also the product may get damaged causing the inaccurate operation and hazardous moves out of control.

(Pneumatic Actuator)

❶ When starting operation, pay the full attention to the cylinder's moving direction.
❷ Do not put hands where the cylinder moves.
❸ Cords such as the sensor switch's lead wire should not be damaged. Damaging, forcing, twisting tugging, winding, putting on a heavy object, and pinching will cause fire, electric shock abnormal operation by short circuit or circuit error.
❹ Use cylinder at the speed below 500mm/sec. Otherwise damage and trouble will be caused. However if the load is large and the speed is fast even below the maximum, direct impact on the cylinder must be avoided, by using the external stopper, etc.

(Pneumatic Valve. Pneumatic Accessories. Sensor Switch)

❶ Cords such as the pressure switch's lead wire, solenoid valve's power supply cord should not be damaged. Damaging, forcing, twisting, tugging, winding, putting heavy object on, and pinching will cause fire, electric shock, abnormal operation by short circuit or circuit error.
❷ Do not use filter or lubricator without a case guard.
❸ For filter and lubricator, do not use a flawed or stained case.

Caution for safety

⚠ ALL PRODUCTS

⚠ DANGER

(Applies to all products on the catalogue)

❶ If necessary, use protection glove, protection glasses, and safety shoes to secure the safety when operating products.

❷ For the easy maintenance, enough space around the product should be provided.

❸ When mounting, flush inside throughly to remove chips from piping, and seal tape, rust and dusts, in order to prevent troubles such as air leak.

❹ When screwing in the fittings, fasten with the tie torque of proper size to the connection size.

❺ Use clean air. Equip an air filter near the equipment to remove drain, dusts and etc. Periodically remove drain from the filter.

❻ Spindle oil and machine oil must not be used for lubrication, or the swelled packings will cause operation troubles.

❼ Operation below the temperature 5°C must be paid the full attention since it may cause the freezing of drain.

❽ Magnetic products such as disk card, tape, and tester must be kept away from the magnet-equipped cylinder and solenoid valve's solenoid part.

❾ When the product is no longer available for operation or needed, discard in a proper way as an industrial waste.

❿ Do not throw the product into fire. The product may explode or the toxic gas may be generated.

(Pneumatic Actuator)

❶ Products should be mounted on the plane face. Mounting on the warped face causes poor accuracy, air leak and troubles.

❷ Flaw or dent on the mounting part of the cylinder may make the uneven face.

❸ The chafing parts of piston rod and guide rod must be free from flaw or dent. Otherwise packings got damaged and air will leak.

❹ When the cylinder draws, be careful not to put yourself between the cylinder and the link bar at the top (Twin guide cylinder).

❺ Products do not need lubrication since they are initially lubricated. For lubrication, use turbine oil first class (ISO VG32) or the equivalent.

❻ Sensor switch which senses the cylinder position must not be operated in the magnetically disturbed area. It will react to the magnetism and the sensing accuracy will be disturbed.

❼ If the two switch-equipped cylinders are mounted close in parallel, a switch may react to the another cylinder's moving magnet, and effects on the sensing accuracy.

❽ Avoid the load over the switch 's allowable maximum load.

(Pneumatic Valve. Pneumatic Accessories. Sensor Switch)

❶ Flaw or dent on the mounting part of the cylinder may make the uneven face.

❷ Do not use solenoid valve, pressure switch, flow switch, on foot switch in the environment where the large electric current or the strong magnetism exist.

❸ As for solenoid valve, check in the instruction manual whether the lubrication is needed. If needed, use turbine oil first class ISO VG32 on the equivalent.

❹ In the case of double solenoid valve, do not energize both solenoids.

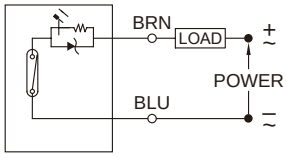
❺ Avoid the load over the switch's allowable maximum load.

Technical information

⚠ WARNING

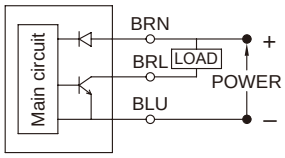
(Do not exceed specification, permanent damage to the sensor may occur.)

❶ For reed switch type sensors, polarity must also be observed for the proper functioning of LED. Connect the brown wire in series with load positive (+) and the blue wire to negative (—) of power source. If the polarity is reversed, reed switch remains functional but LED will remain in "OFF" state.

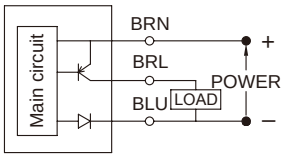


❷ For solid-state type sensors , polarity must also be observed . Connect brown wire to the positive (+) and the blue to the negative (—) of DC power source. The black wire must connect to the load only. If the black wire is accidentally connected to the power source, permanent damage to the sensor may occur.

(NPN Output)

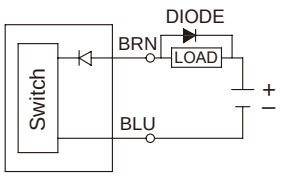


(PNP Output)

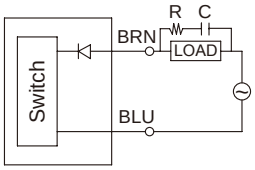


❸ An external protection circuit may be required if the reed switch is used with inductive load, such as relay or solenoid . For DC inductive load, attach an external diode parallel to the load and use R-C circuit parallel with AC inductive load as illustrated below.

DC Power

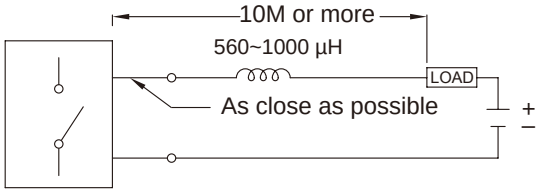


AC Power



R: 2.7KΩ
C: 0.1uf/600V

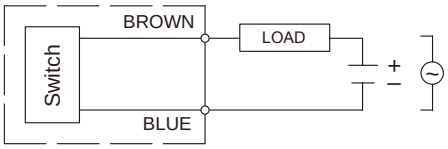
❹ Keep sensors away form stray magnetic field to prevent malfunctions.
❺ When using reed switch with capacitive load or if the lead wire length exceed 10-meter, an inductor must be installed in series with the sensor to prevent damage (Sticking effect).



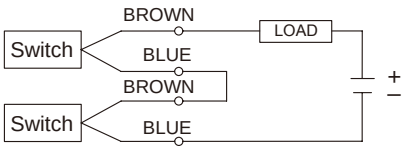
Connection method

2 wire S.W. connection

▶ General connection

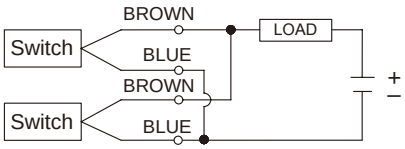


▶ Series connection (AND)



❶ When connecting 2-wire switches in series (AND), don't exceed more than two switches due to the internal voltage drop (Typical V drop=2.5~4V per switch). Excessive Voltage drop will cause non-operation of the load.

▶ Parallel connection (OR)



❶ When connecting non-contact 2-wire switches in parallel (OR),leakage current will increase and cause improper load operation.
❷ When connecting 2-wire reed switches in parallel(OR), possible concurrent operation will cause dim LED illumination due to lower current distribution.

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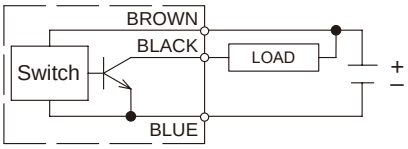
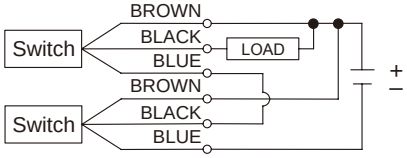
3 wire NPN connection

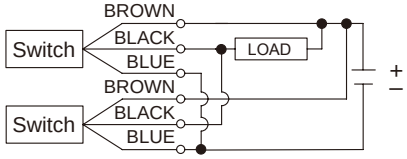
▶ General connection



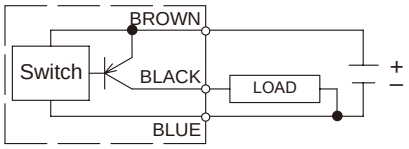
▶ Series connection (AND)

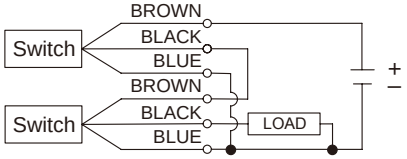


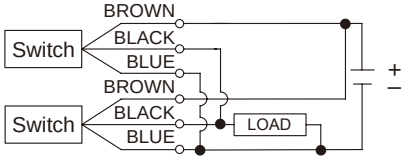
▶ Parallel connection (OR)



3 wire PNP connection







MEMO

NOTE

CONNECTION

QR CODE SCAN

https

Web

2D/3D/PDF download

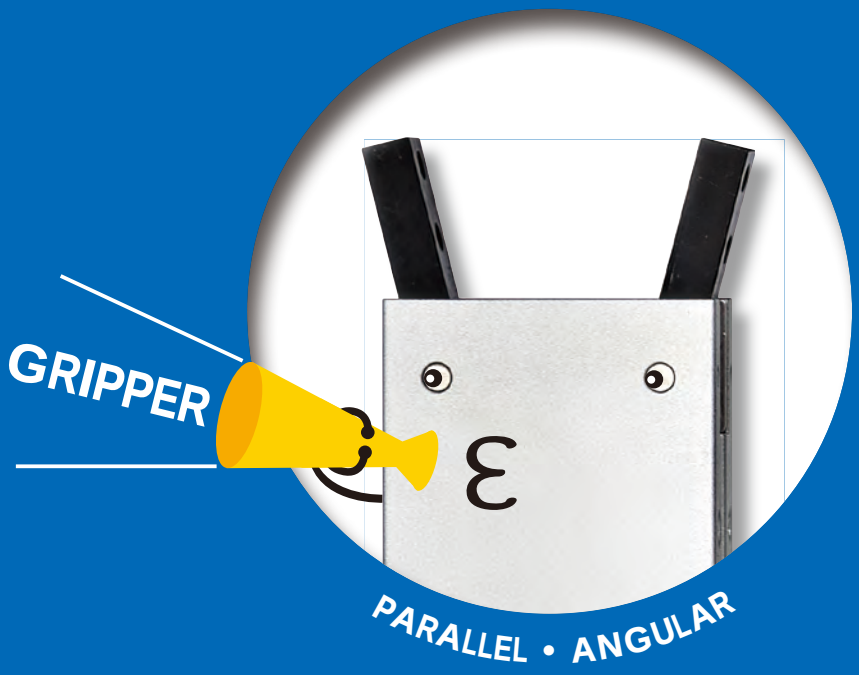
YouTube

Video

Solenoid Valve

Air Treatment Unit

Gripper



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- The specifications are subject to change without advence notice.

CAT. NO: MD-DM1903-E

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