



**Almega Friendly series II**

# Multipurpose Robot

**NEW FD-V8LH**

Multipurpose specification



## Fast, Slim, User-Friendly

Improved with all performances!



Long arm with a max.  
payload 8kg  
Optimized for the  
high-speed operation.

PICKING	SPOT WELDING
CUTTING	Used for... ASSEMBLY
LOAD/ UNLOAD	FINISHING
ARC WELDING	SORTING

## Improved with all performances!

### Fast

Industry leading level speed.  
Reduce cycle time

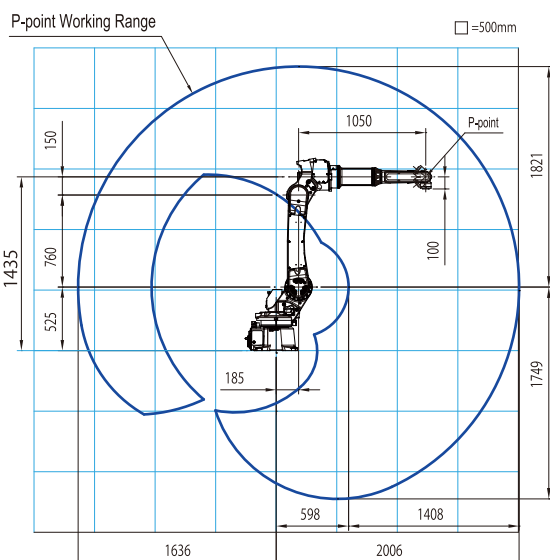
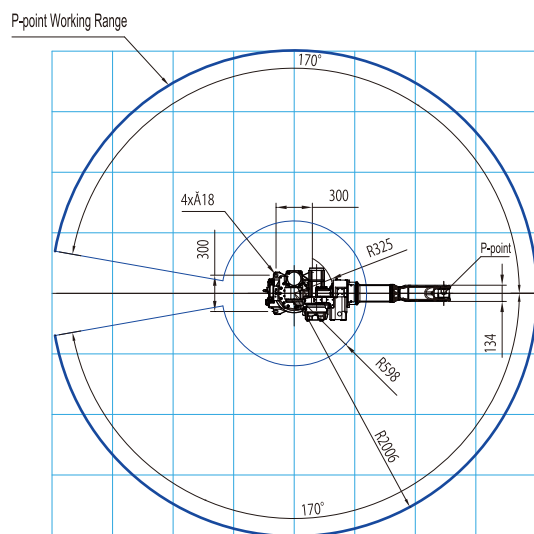
### Slim

30% reduce in foot print  
High-density layout

### User friendly

Built-in application cable for  
various hand tools.

#### [ Manipulator Working Range ]



#### [ Manipulator Specifications ]

		Specification
Name		FD-V8LH
Structure		Vertically articulated type
Number of Axes		6
Wrist Capacity		8 kg
Positional Repeatability (Note 1)		±0.05mm (Note 1)
Driving Method		AC servo motor
Driving Capacity		4800W
Positional Feedback		Absolute encoder
Working Range	Arm	J1 (Rotation) ±170°(±50°) (Note 2) J2 (Front/back) -155°~+100°(Note 3) J3 (Up/down) -170°~+260°
	Wrist	J4 (Swing) ±180° J5 (Bending) -50°~+230° J6 (Twist) ±360°
	Maximum Speed	J1 (Rotation) 3.93 rad/s{225°/s} (3.05rad/s {175°/s})(Note 2) J2 (Front/back) 3.58 rad/s{205°/s} J3 (Up/down) 4.45 rad/s{255°/s}
Wrist Allowable Load	Allowable Moment	J4 (Swing) 17.6 N·m J5 (Bending) 17.6 N·m J6 (Twist) 7.8 N·m
	Allowable Moment of Inertia	J4 (Swing) 0.43 kg·m <sup>2</sup> J5 (Bending) 0.43 kg·m <sup>2</sup> J6 (Twist) 0.09 kg·m <sup>2</sup>
	Arm Cross-sectional Area	7.48m <sup>2</sup> ×340°
Environmental Conditions		Temp: 0~45°C, Hmd: 20~80%RH (No Condensation)
Mass (weight)		237 kg
Capacity of Upper Arm		20 kg (Note 4)
Installation Method		Floor-/Ceiling-/Wall-mounted
Paint Color		White (Munsell notation 10GY 9/1)

(Note 1) Positional repeatability of the tool center point (TCP) value complies with the JIS -B-8432 Standard.  
(Note 2) Specifications for wall mounting appear in parentheses.  
(Note 3) The working range of the J2 axis may be restricted when wall-mounted.  
(Note 4) The capacity of the upper arm varies with the wrist capacity.



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Note This product and the technologies (including software) used in the product are subject to Catch-All Controls. When exporting any of them, verify the users, applications, etc. according to the applicable laws and regulations and take appropriate procedures such as applications for export permission to the Minister of Economy, Trade and Industry if required.

●The information contained in this catalog is current as of April 2021 and is subject to revision without notice.

Daihen Robot Site  
[www.daihen-robot.com/en/](http://www.daihen-robot.com/en/)